

# Small-Signal Parameters of the VeSFET and Its Application in Analog Circuits

Dominik Kasproicz, and Bartosz Swacha

**Abstract**—The Vertical Slit-based Field-Effect Transistor (VeSFET) is a novel junctionless device with two identical, independently controlled gates. The VeSFET, so far prototyped only as single-device test structures, has been considered in the literature exclusively as a component of digital systems. This article shows that the device's properties make it attractive also for the analog designer. Some of the VeSFET's analog-design related parameters are compared with those of the MOSFET of the corresponding technology node. Subsequently, a two-stage Miller operational transconductance amplifier (OTA) is proposed that makes use of the VeSFET's two independently-controlled gates to drastically reduce the common-mode gain. An example application of the OTA in a current mirror is also presented.

**Index Terms**—VeSFET, VeSTIC, OTA, analog circuit, dual-gate device, independent gates.

## I. INTRODUCTION

VeSTIC (Vertical-Slit Transistor-Based Integrated Circuit) is a recently demonstrated technology for low-power VLSI circuits [1]–[3]. The circuits are fabricated with a slightly modified SOI CMOS process sequence. Lithography requirements are greatly relaxed by the total departure from the usual rectangular features in favor of circular ones and by extreme regularity of the layout: all the devices, having the same geometry, are spaced on a square grid (see Fig. 1, left) [2]. Intended as an alternative to CMOS, the technology permits easy integration of various types of device (dual-gate MOSFETs, JFETs, and bipolar transistors) on the same SOI wafer. The staple component of VeSTICs, however, is the novel junctionless Vertical Slit-based Field-Effect Transistor (VeSFET), whose top view is presented in Fig. 1 (right). The key properties of this device include:

- 1) Operation based on the flow of majority carriers. Thus, the dominant regime is partial depletion of the active region rather than inversion.
- 2) Two identical, *independently controlled* gates on either side of the active region connecting the source and drain. The central, narrowest part of the active region is referred to as the *slit*.
- 3) Volume flow of carriers along the slit rather than surface-channel conduction like in the conventional MOSFET or FinFET. The effective cross-section of the slit (and, as a consequence, its conductance) is controlled by the

D. Kasproicz and B. Swacha are with the Institute of Microelectronics and Optoelectronics, Warsaw University of Technology, Warsaw, Poland, email: D.Kasproicz@imio.pw.edu.pl

This project was supported in part by the Polish Ministry of Science and Higher Education, grant N N515 524538, and in part by the National Centre for Research and Development in the frame of Project PBS under Research Project 177244.

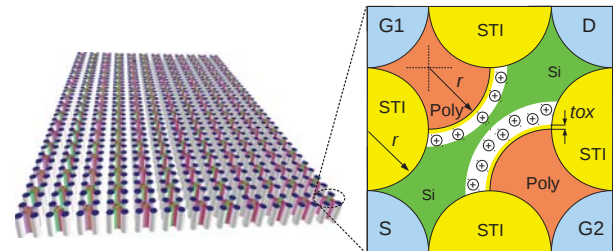


Fig. 1. Left: portion of a VeSTIC layout [2]. White cylinders, passing all through the SOI body layer, are contacts to vertical-channel devices spanned between them. Wiring and isolation between devices (STI) are left out for clarity. Right: top view of a single VeSFET device. The effective geometry of the n-type channel is defined by the depleted regions (white) controlled by two *independent* gates. Parts of the metallic contacts are seen in the corners.

buildup of depleted regions controlled by the voltages of the gates. If the gate voltages are low enough to deplete the *whole* slit to some extent, the device enters the subthreshold region where the drain current is dominated by carrier diffusion.

Those properties have important implications. The use of two separate gates controlling a *common* volume channel is in contrast with other dual-gate transistors having two, only weakly coupled, surface channels like those described in [4]. This makes the VeSFET something more than just two single-gate transistors connected in parallel. Possible advantages include easy implementation of techniques like dynamic control of the threshold voltage or construction of two-input NAND/NOR gates with two, rather than the usual four, transistors (the latter idea, proposed in [5], was verified experimentally in [6]). Furthermore, volume carrier flow mitigates to some extent effects related to silicon-dielectric interface scattering of carriers as well as flicker noise and gate dielectric degradation due to hot-electron injection. Majority-carrier based operation means that the slit is of the same doping type as the source and drain regions. Lack of source- and drain junctions eliminates channel-length variability due to random dopant fluctuation. More about the VeSTIC technology can be found in [2], while an exhaustive description of VeSFET operation, including a compact model, is presented in [5].

The original motivation underlying the VeSTIC technology was to provide an alternative to classic CMOS for low-power VLSI digital applications. Indeed, careful device optimization based on finite-box simulation enabled a nearly ideal subthreshold slope of 65 mV/dec and  $I_{on}/I_{off} > 10^8$  [5]. Those parameters, attractive from the digital-circuit standpoint, have been confirmed by prototype measurements [2], [6].

Nevertheless, any technology aspiring to be a viable alternative for CMOS must also perform well in analog applications. Even predominantly digital systems incorporate analog parts like digital-to-analog or analog-to-digital converters, phase-locked loops for clock recovery, input and output buffers etc. As the cost of through-silicon vias is still high, it is preferable to integrate both analog and digital components of the system on the same die. So far, the VeSFET has been optimized and extensively analyzed numerically only as a component of low-power digital circuits [5], [7]–[9]. It is only recently that small-signal parameters of the VeSFET have been studied and first VeSFET-based analog circuits have been simulated [10].

This article, being an extended version of [10], is organized as follows. Section II reviews the principles of VeSFET operation and compares some of the VeSFET’s analog-design related parameters with those of the corresponding MOSFET. Those parameters are presented as a function of the voltages on the two independent gates, which provides suggestions for optimal device biasing in analog circuits. Section III presents an example of a circuit whose operation is enabled by the existence of a device having two independent gates controlling a common channel. The circuit is a variant of two-stage operational transconductance amplifier (OTA) with two common-mode compensation mechanisms working efficiently across nearly the entire input voltage range. This circuit is subsequently compared with a VeSFET-based ‘textbook’ OTA where the devices’ gates are shorted together. Section IV presents the performance of the former OTA (i.e. the one that makes use of independent gates) as a component of a current mirror. Section V summarizes the work.

## II. VESFET’S SMALL-SIGNAL PARAMETERS

The VeSFET transistor is characterized by the following design parameters (see Fig. 1):

- characteristic radius  $r$ , shared by all the rounded parts like gates, contacts, and isolation (STI),
- thickness  $h$  of the active layer (i.e. silicon layer on top of an SOI wafer where transistors are located),
- thickness  $t_{ox}$  of the gate oxide (or another dielectric),
- active-layer doping level  $N_s$ ,
- gate doping level  $N_g$ .

All those parameters, except radius  $r$ , are process dependent and, as such, cannot be used as design variables. The value of  $r$  must also be kept fixed throughout the wafer to ensure regularity of the VeSFET array, which greatly simplifies the optimization of lithography and etch processes [2]. As a consequence, transistor sizing in the VeSTIC technology can be achieved only by choosing the number of devices connected in parallel. This is in contrast with CMOS, where both the channel length and width can be treated as almost continuous design variables. However, transistor channels used in CMOS analog design are usually tens of times wider than the minimum feature size. This corresponds to a parallel connection of tens of VeSFETs, which seems to provide granularity fine enough for most purposes. If finer tuning is necessary (e.g. for cancellation of systematic offset in an operational amplifier), it can be done by appropriately biasing one of the VeSFET gates, while using the other as a signal input like in a MOSFET.

The VeSFETs considered in this work have a characteristic radius  $r$  of 50 nm, gate-oxide thickness  $t_{ox}$  of 4 nm, active-region thickness  $h$  of 200 nm, and gate doping level  $N_g$  of  $5 \times 10^{18} \text{cm}^{-3}$  (opposite type than the active region). Substrate doping depends on the device function, which will be reviewed in the next paragraph. Such geometries and doping levels have been optimized for digital applications [5]. The use of the same device parameters for analog design is supposed to greatly simplify the manufacturing process of mixed-signal circuits.

Two device flavors emerged from studies on the optimization of VeSFET for digital applications. The goal was to create dual-gate devices that mimic the behavior of two single-gate transistors connected in parallel or in series. Those devices are referred to as OR- and AND-VeSFET, respectively. They enabled building dual-input NAND- and NOR gates with two transistors rather than the usual four. The desired type is obtained by differentiating the active-region doping level  $N_s$ , while leaving all the other physical parameters identical. The active-region doping level is  $4 \times 10^{17} \text{cm}^{-3}$  (n-channel) or  $5 \times 10^{17} \text{cm}^{-3}$  (p-channel) in OR devices and  $1 \times 10^{17} \text{cm}^{-3}$  (n-channel) or  $1.5 \times 10^{17} \text{cm}^{-3}$  (p-channel) in AND devices [5]. This difference has profound impact on the device’s response to gate voltages  $V_{G1}$  and  $V_{G2}$ , especially if the two differ substantially. This effect is demonstrated in Fig. 2. Due to lower doping level in the active region, AND devices exhibit greater sensitivity of the depletion depth to gate voltage. Thus, it is sufficient to ground a single gate to deeply deplete the slit, which leads to a cutoff of the drain current. The active region of the OR-type device, on the other hand, is doped so heavily that grounding a single gate depletes only a part of the slit. The drain current, although reduced to some extent, remains substantial. This also explains why AND devices have a greater threshold voltage of around 0.75 V, as opposed to 0.55 V for the more heavily doped OR devices. The transfer characteristics of both devices, their application in two-transistor logic gates, as well as more in-depth explanation of the underlying physics, can be found in [5]. In loose terms,

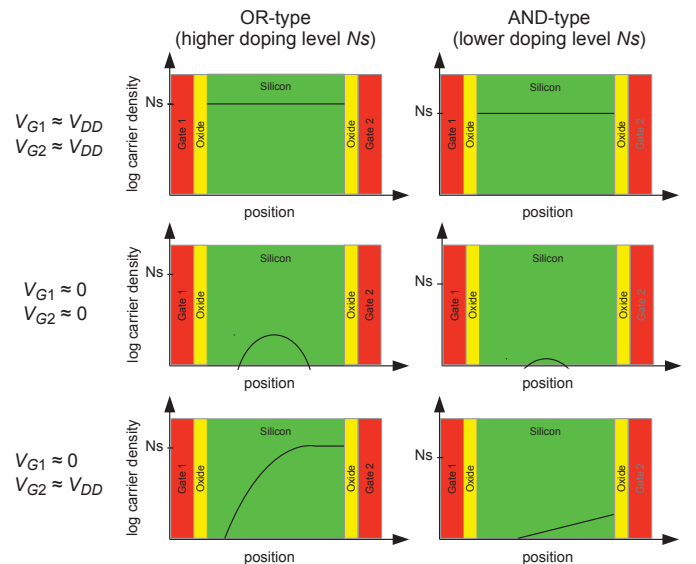


Fig. 2. Carrier distribution across the channel of an OR- and AND-type VeSFET for various biases of Gate1 and Gate2

the behavior of an AND device mimics a series connection of two single-gate devices, while an OR device behaves more like two single-gate transistors connected in parallel.

In the rest of this Section, the AND and OR VeSFETs are compared with an example 90-nm MOSFET. To provide fair comparison, the VeSFET's gates have been shorted together throughout the experiments. The VeSFET data has been obtained by simulation with Synopsys' Sentaurus Device – a tool using the finite-boxes method for electrical simulation of arbitrary 2D or 3D structures composed of semiconductors, conductors and dielectrics [11]. The MOSFET was simulated with Hspice [12] using the PTM model [13]. The 90-nm process node has been chosen as a CMOS equivalent of the 50-nm-radius VeSFET, because both can be manufactured with litho-etch equipment capable of printing 90-nm-wide lines. The MOSFET width used in the simulation was 200 nm, which corresponds to the thickness  $h$  of the active areas of the VeSFETs.

The first parameter of interest is transconductance  $g_m$ . The  $g_m$ - $V_{GS}$  curves for both kinds of n-type VeSFET are presented in Fig. 3. The peak  $g_m$  values of the AND VeSFET are on par with the 90-nm MOSFET. The maximum  $g_m$  of the OR VeSFET is twice as great, which results from the higher active-area conductivity due to higher  $N_s$ . The main difference between the three devices is the threshold voltage, being the highest for the AND VeSFET and the lowest for the MOSFET.

The differences between the three kinds of transistor are more evident in terms of intrinsic voltage gain defined as the ratio of the device's transconductance to its output conductance:  $A_{vi} = g_m/g_{ds}$ . This figure is independent of the device width. The plots of  $A_{vi}$  versus  $V_{GS}$  are presented in Fig. 4. They reach maximum values for high drain voltages for gate voltages around threshold. Of course,  $A_{vi}$  grows with increasing  $V_{DS}$ , i.e. in deep saturation. As can be seen, the intrinsic gain of the AND device is up to three times as large as that of the equivalent MOS transistor.

Another crucial parameter of a transistor is its transconductance efficiency, defined as the ratio of the transconductance to the drain current [14]. Fig. 5 presents the comparison of  $g_m/I_D$  of the two VeSFET types and the same 90-nm MOSFET as before. This metric reflects a device's performance as a

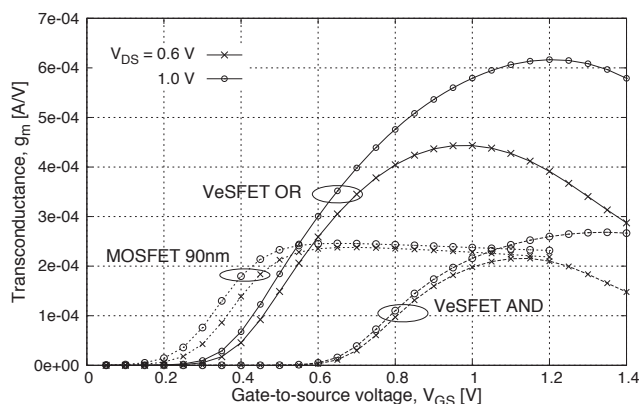


Fig. 3. Transconductance of the 90nm MOSFET (PTM model) and two types of VeSFET. The VeSFET gates are shorted. The MOSFET channel width  $W = 200$  nm, which equals the active-area thickness of the VeSFETs

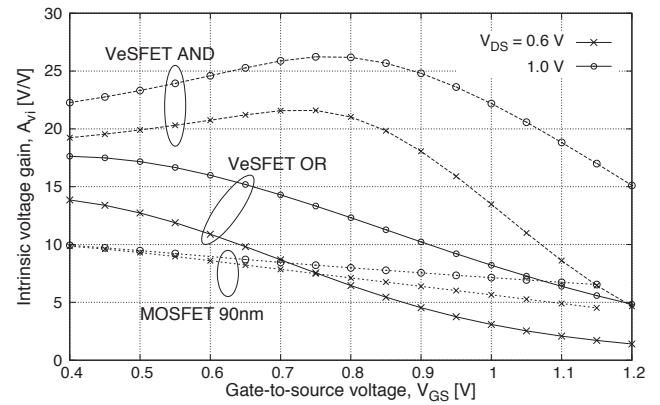


Fig. 4. Intrinsic voltage gain of the VeSFET (dashed – AND-type, solid – OR-type) and 90-nm PTM MOSFET (dotted) as a function of terminal voltages. The VeSFET gates are shorted

low-power amplifying component. The theoretical maximum for the planar MOSFET is  $g_m/I_D = q/(kT)$  (where  $k$  is the Boltzmann constant and  $T$  is the absolute temperature), which is around  $38.5 \text{ V}^{-1}$  at room temperature, but in practice only values of  $25 - 30 \text{ V}^{-1}$  are obtained. In the VeSFET, the maximum value of transconductance efficiency is  $31 \text{ V}^{-1}$  for the OR type and as much as  $51 \text{ V}^{-1}$  for the AND type. As in the case of MOSFETs, the maximum values of  $g_m/I_D$  are attained in the subthreshold regime. The advantage of the AND type is due to its aforementioned greater sensitivity of the depletion depth (and, as a consequence, drain current) to gate voltage. The lower active-region doping level in AND devices means also greater slit resistance, which translates into lower  $I_D$  levels and further boosts the  $g_m/I_D$  ratio. Please note that in the case of MOSFETs  $g_m/I_D$  curves are usually plotted against the inversion coefficient, which is the drain current normalized w.r.t. some process-dependent constant multiplied by the  $W/L$  ratio. This is why such plots are independent of the transistor width. The operation of the VeSFET, on the contrary, is unrelated to inversion, which makes such normalization impossible. Thus, the  $g_m/I_D$  curves have been plotted as a function of the drain current of a “unit-size” transistor, which means a single VeSFET and a MOSFET of  $W = 200$  nm. This is why the *horizontal* position of

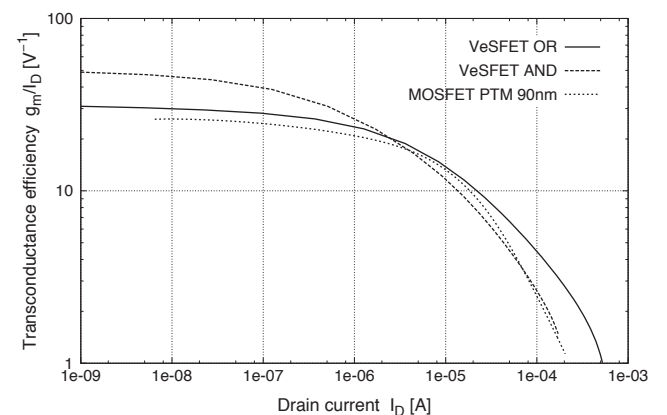


Fig. 5. Transconductance efficiency as a function of the drain current for the 90nm MOSFET (PTM model) and two types of VeSFET (gates shorted). The MOSFET channel width  $W = 200$  nm,  $V_{DS} = 1$  V in all the cases

the MOSFET curve w.r.t. its VeSFET-related counterparts in Fig. 5 is somewhat arbitrary. Nevertheless, it is clear that the maximum  $g_m/I_D$  value for the MOSFET is only 26, i.e. half the value for the AND VeSFET. Interestingly, the curve for the OR VeSFET rolls off for larger currents than in the case of the AND device, which makes the two curves cross at approximately  $I_D = 2 \mu\text{A}$ . This provides the designer with a suggestion to use AND devices if the current per transistor does not exceed single microamps and OR devices otherwise.

The last criterion of comparison between the devices is the intrinsic cut-off frequency  $f_T$  as a function of the drain current. The results are shown in Fig. 6. Once again, the superiority of the AND VeSFET manifests itself mostly in the subthreshold region, where its  $f_T$  exceeds that of the MOSFET by a decade. For drain currents greater than around  $10 \mu\text{A}$ , the OR VeSFET is a better choice. Such good results are mostly due to the large thickness of VeSFET gate oxide. At 4 nm it is much greater than in the corresponding MOSFET, leading to a smaller gate capacitance. The roll-off of the  $f_T$  curves observed for high values  $I_D$  results from a  $g_m$  drop for strong  $V_{GS}$  and  $V_{DS}$ , caused mostly by carrier velocity saturation.

The values of the aforementioned parameters suggest that the VeSFET is superior to the MOSFET of the corresponding process node. The greatest advantage of the VeSFET, however, is the presence of two independent gates controlling a common channel. Fig. 7a presents lines corresponding to constant values of drain current in the space spanned by the voltages of the two gates.

If the threshold voltage is defined as the gate voltage corresponding to some predefined value of drain current, this plot can be interpreted as representing the threshold voltage of one gate as a function of the potential of the other gate. As can be seen, this dependence is very strong, especially for high gate voltages. Indeed, it is much stronger than that for dual-gate planar SOI devices presented in [4] (see Fig.7b). Additionally, the relationship is symmetrical. This creates interesting possibilities for design of analog circuits like the one presented in the following Section.

Small-signal parameters are of course also functions of the voltages on both gates. Transconductance and intrinsic voltage

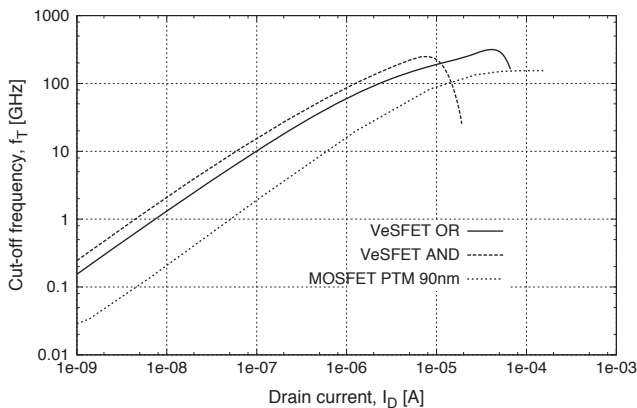


Fig. 6. Intrinsic cut-off frequency as a function of the drain current for the 90nm MOSFET (PTM model) and two types of VeSFET.  $W = 200 \text{ nm}$  in all the devices.

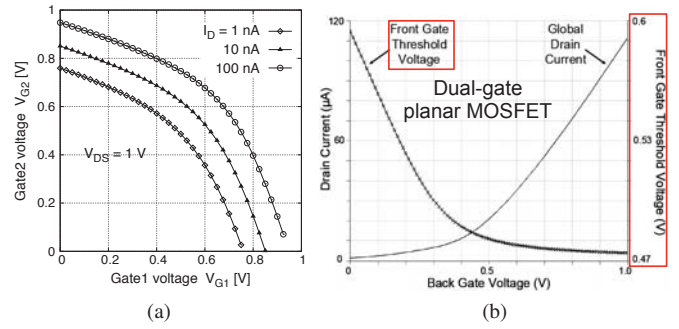


Fig. 7. Lines corresponding to constant values of the AND-VeSFET drain current as a function of gate voltages  $V_{G1}$  and  $V_{G2}$  (a). This plot can also be interpreted as the threshold voltage of  $G_2$  as a function of  $V_{G1}$ . A similar plot for a dual-gate planar MOSFET (source: [4]) shows much weaker threshold-voltage control (b)

gain for a single gate (Gate1 in this case) can be defined as

$$g_{m1} = \partial I_D / \partial V_{G1} \quad (1)$$

and

$$A_{vi1} = g_{m1} / g_{ds}, \quad (2)$$

respectively. The values of  $g_{m1}$  and  $A_{vi1}$  are plotted in Fig. 8 and Fig. 9, respectively, in the space spanned by the voltages on the two gates. Fig. 9 clearly suggests that the maximum intrinsic gain is achieved by applying relatively high voltages (around 1 V) on the driven gate, while keeping the other one grounded or even biasing it with a negative voltage. This effect is easy to explain based on the carrier distribution across the slit. The key to achieving high values of  $g_{m1}$  and  $A_{vi1}$  is to maximize the influence of Gate1 on the overall number of carriers in the slit. This is why it is desirable to bias

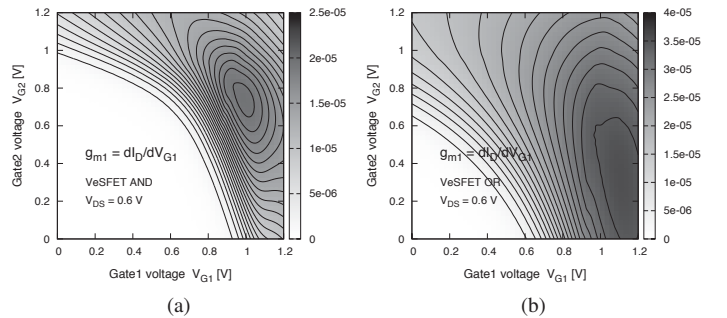


Fig. 8. Transconductance of Gate1 as a function of voltages on both gates for the AND VeSFET (a) and OR VeSFET (b)

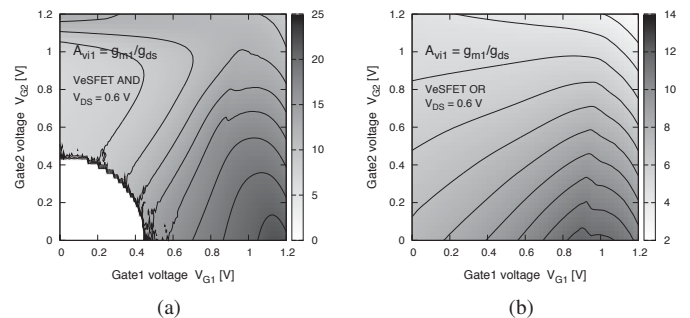


Fig. 9. Intrinsic voltage gain  $A_{vi}$  of signal applied to Gate1 as a function of voltages on both gates for the AND VeSFET (a) and OR VeSFET (b). The extremely noisy data corresponding to the lowest gate voltages for the AND VeSFET have been left out for clarity

Gate1 near the flatband voltage (which is about 0.9 V for the AND-VeSFET and 0.95 V for the OR-VeSFET) or even in weak accumulation. The control of Gate1 over carrier density may extend relatively deep into the slit, but only if Gate2 is biased in depletion. Otherwise the slit becomes “flooded” with carriers controlled by Gate2, leaving little control to Gate1. In the case of AND-VeSFET, however, the influence of either gate on the entire slit is so strong that biasing Gate2 too low may cause its respective depletion region to penetrate as far as under Gate1. This explains why  $g_{m1}$  assumes the maximum at  $V_{G2} \approx 0.75$  V, which is a relatively high value.

### III. VESFET-BASED OTA

Unless otherwise noted, the following assumptions apply throughout the rest of this work. The circuits are built exclusively from AND VeSFETs, as they provide the highest intrinsic voltage gain. If parallel connection of several VeSFETs is required in some portions of the circuit, this fact is denoted in diagrams by an appropriate multiplier, e.g. “x10”. All the circuits are powered with asymmetric supply voltage  $V_{dd} = 1.2$  V. All the voltages are defined w.r.t. the ground. Small-signal parameters like differential gain  $A_d$ , common-mode gain  $A_c$ , and common-mode rejection ratio CMRR are all determined for the “neutral” common-mode input voltage  $V_c = V_{dd}/2$ .

Even though compact models exist for VeSFET drain current [5] and capacitances [15], their accuracy is the highest either for gate voltages above the threshold voltage or in deep subthreshold operation. The transition between those regions is modelled using smoothing functions, which adversely affects the accuracy. As the devices used in the circuits described below are usually biased near the threshold, the accuracy of the models was found inadequate. Therefore, all the circuit simulations in this work have been performed with Synopsys’ Sentaurus Device, which guarantees high accuracy. The price to pay, however, is the inability of obtaining the frequency response of the simulated circuits. Therefore, this work is limited to DC characterization.

The circuit diagram of the OTA investigated in this work is presented in Fig. 10 (a). The diagram of the block denoted there as CMCB (common-mode compensation block) can be found in Fig. 10 (b). The differential pair  $M_1 - M_2$  of the input stage of the OTA is a *differential current mirror* proposed

in [4]. (The latter circuit has been originally presented for planar double gate MOSFETs with independently driven gates. The function of the differential current mirror within the amplifier proposed in the cited work, however, was different than presented here.) The most striking difference between the resulting two-tier architecture and a “conventional”, three-tier differential amplifier is the lack of the “tail” current source. That current source, being in the simplest case a single transistor  $M_{CS}$ , provides the necessary common-mode attenuation in the conventional architecture. However, it limits the input voltage range. Indeed, the minimum acceptable voltage on either input is

$$V_{in\ min} = V_{TH\ M1} + V_{sat\ M1} + V_{sat\ M_{CS}}, \quad (3)$$

where  $V_{sat}$  denotes the saturation voltage of a device while  $V_{TH}$  – its threshold voltage.  $V_{in\ min}$  can be minimized by reducing either  $V_{sat\ M1}$  or  $V_{sat\ M_{CS}}$ . This, however, can only be done by increasing the width of either of these transistors (or, in the case of VeSFETs, connecting several devices in parallel). As  $V_{sat}$  is inversely proportional to the square root of the transistor width, this dramatically increases the silicon area occupied by the circuit. Of course,  $M_5$  cannot be simply removed from the conventional differential amplifier because this would lead to a dramatic increase in the unwanted common-mode gain  $A_c$ . The use of dual-gate transistors, however, provides additional feedback paths that can be used to largely reduce  $A_c$ . One such feedback is introduced by the short between the drain of  $M_1$  and one of its gates. Any change in the drain potential is fed back to the gates of  $M_1$  and  $M_2$ , thus counteracting the original shift in the drain potential and limiting the common-mode gain. Unfortunately, this mechanism also reduces the differential gain. However, this feedback loop is necessary to reduce the output swing due to common-mode input signal, which enables efficient operation of the common-mode compensation block CMCB (described below) across the entire range of input voltages.

The transfer characteristics of the input stage are shown in Fig. 11. The values of small-signal differential gain  $A_d$  and common-mode gain  $A_c$  in this structure are 5.1 V/V and  $-0.32$  V/V, respectively, which translates into a CMRR of 24 dB. This figure is subsequently improved by the CMCB, which is another example of circuit made possible by independent-gate transistors. It is a simple dual-input circuit with a negligible gain for the differential signal and a common-

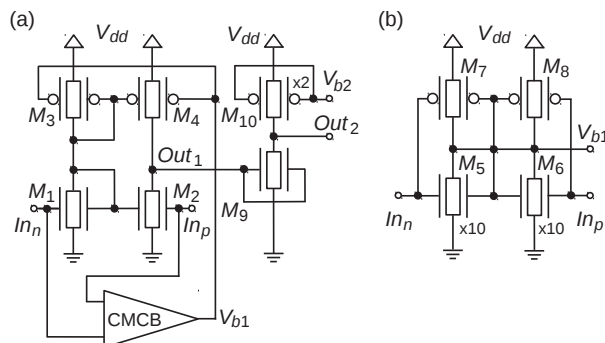


Fig. 10. Two-stage VeSFET-based OTA (a) and the circuit diagram of the common-mode compensation block CMCB (b)

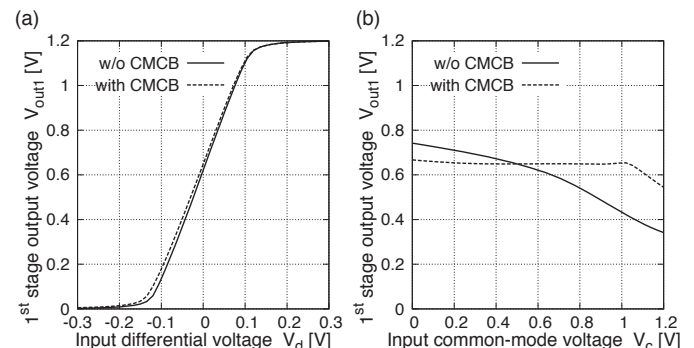


Fig. 11. Transfer curves of the input stage with and without the CMCB

mode gain of about  $-1$  V/V across almost the entire range of input voltages (Fig. 12). The inputs of the CMCB are connected in parallel with those of the OTA's input stage, while the output signal  $V_{b1}$  is fed back to the gates of  $M_3$  and  $M_4$ . The ratio between the n- and p-channel VeSFETs in the CMCB has been chosen so as to minimize the overall common-mode gain of the entire OTA. As shown in Fig. 11 (a), the impact of the CMCB on the OTA's differential gain is negligible. The transfer curves of the complete two-stage OTA with CMCB are presented in Fig. 13. The values of differential- and common-mode gain of this two-stage amplifier are  $-54$  V/V and  $-29.6$  mV/V, respectively, resulting in a CMRR of 65.2 dB. Thus, the CMCB boosted the CMRR by as much as 41 dB. As can be seen in Fig. 13 (b), this compensation is efficient for common input voltages ranging from around 0.35 V to 0.9 V. The systematic input offset of the entire two-stage OTA is  $V_{offset} = 1.28$  mV. The value of  $V_{b2} = 0.616$  V reduces the systematic input offset to single microvolts. However, the choice of  $V_{b2} = V_{dd}/2$  is more convenient because this value can be obtained with a simple voltage divider. Please note that a voltage divider build with diode-connected VeSFET transistors delivers a more accurate voltage ratio than its bulk-MOSFET counterpart because of lack of body effect.

Even though the amplifier (including the CMCB) has been optimized for  $V_{dd} = 1.2$  V, it performs well for supply voltages down to 0.6 V, as summarized in Table I. The acceptable range of common-mode input voltage actually expands as the supply voltage decreases. As indicated in Fig. 14, for  $V_{dd} = 0.6$  V the amplifier remains nearly insensitive to common-mode input voltage ranging from zero to 90% of  $V_{dd}$ . Unfortunately,

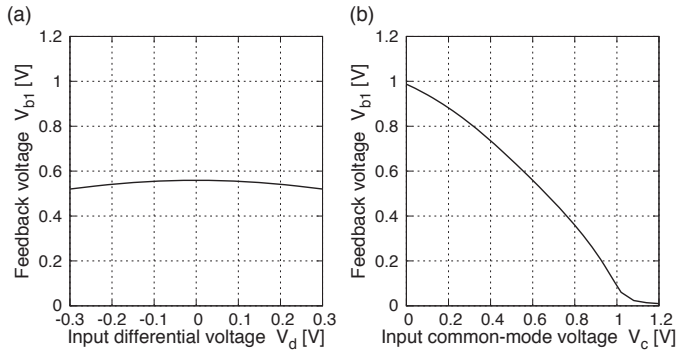


Fig. 12. Transfer curves of the CMCB

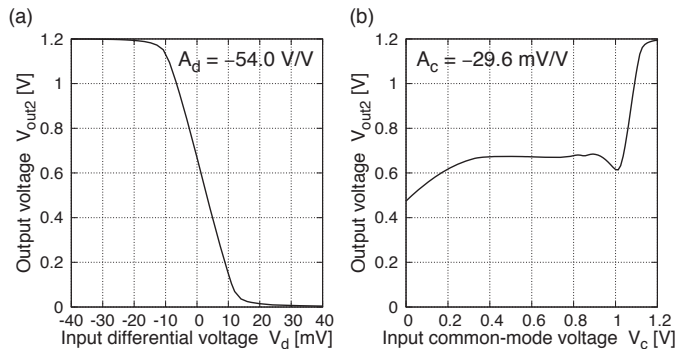


Fig. 13. Transfer curves of the complete OTA with the CMCB.  $A_d$  and  $A_c$  denote differential and common-mode gain, respectively

TABLE I  
SUPPLY-VOLTAGE DEPENDENCE OF SELECTED PARAMETERS OF THE OTA

$V_{dd}$ [V]	$A_d$ [V/V]	$A_c$ [mV/V]	CMRR [dB]	$V_{offset}$ [mV]
0.6	32.8	20.8	64.0	3.10
0.8	37.5	10.3	71.2	2.70
1.0	44.0	38.6	61.1	2.17
1.2	54.0	29.6	65.2	1.28
1.4	69.2	46.0	63.5	-0.33

as in any other OTA, the offset voltage is optimized for one particular value of  $V_{dd}$  and cannot remain unaffected by its change. The fact that  $M_{10}$  in the output stage has two gates may provide an additional feedback input for offset cancellation.

To further confirm the benefits coming from independent-gate operation, the OTA examined above has been compared with a “traditional” OTA architecture presented in Fig. 15. To ensure an appropriate level of common-mode attenuation, as many as 30 VeSFETs had to be used to form the common current source  $M_{CS}$  for the differential pair. This drives the total number of transistors to 47, which is much larger than the 29 devices used in the previous design. What is more, the presence of  $M_{CS}$ , combined with the relatively high threshold voltage of AND VeSFET, drives the minimum acceptable input voltage to levels above  $V_{dd}/2 = 0.6$  V. This effect had to be offset with input-voltage level shifters  $M_5$ – $M_8$ . The transfer curves of the resulting circuit are presented in Fig. 16.

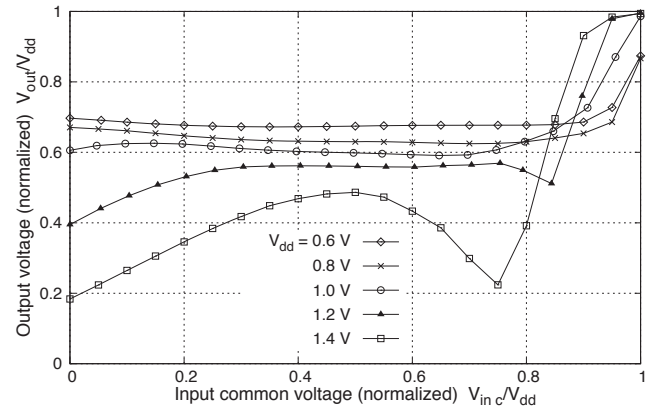


Fig. 14. Common-mode transfer curves of the OTA for various values of supply voltage  $V_{dd}$

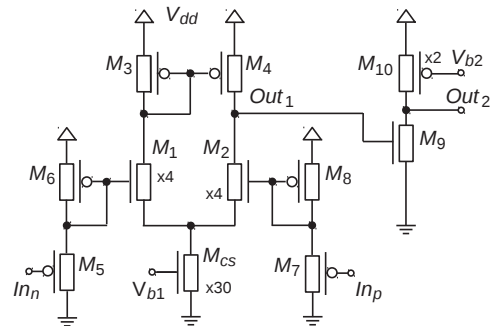


Fig. 15. “Conventional” OTA built with VeSFETs. As each device has its gates shorted, only a single gate per transistor is drawn for clarity.  $V_{b1} = 0.6$  V,  $V_{b2} = 0.7$  V

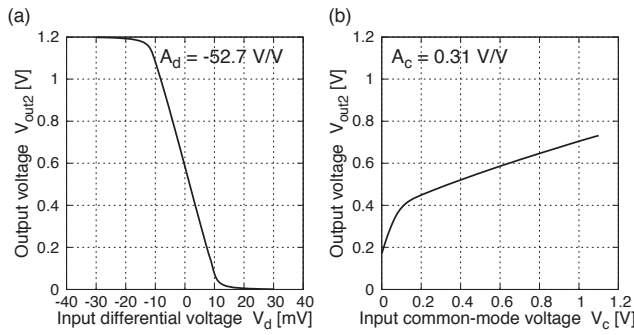


Fig. 16. Transfer curves of the “conventional” OTA shown in Fig. 15.  $A_d$  and  $A_c$  denote differential and common-mode gain, respectively

Table II summarizes crucial parameters of this design compared with those for the independent-gate architecture. The differential voltage gain is  $-52.7$  V/V, i.e. around the same as previously obtained. However, even with a very large  $M_{CS}$  in place, the common-mode input signal is not sufficiently attenuated. This leads to a CMRR of only 44.6 dB, i.e. over 20 dB worse than in the independent-gate architecture. The only way to improve CMRR in this architecture is to make  $M_{CS}$  even wider and bias it with a lower gate voltage  $V_{b1}$  to drive it deeper into saturation. This, however, would lead to further expansion of the circuit size. Additionally, the independent-gate architecture is less sensitive to supply-voltage changes, achieving a PSRR that is 9 dB greater than that of the conventional OTA.

Finally, the two architectures have been compared with respect to speed. As mentioned before, the frequency-domain analysis in Sentaurus Device cannot determine the transmittance of circuits composed of several devices. Thus, time-domain simulations have been performed. Each OTA has been configured as a voltage follower by shorting its inverting input with the output. The non-inverting input was stimulated with a voltage step from 0.6 V to 0.61 V. The OTA using independent gates needed a compensation capacitor between  $Out_1$  and  $Out_2$  to dampen oscillations – see Fig. 17 (a). However, the required capacitance  $C_c$  turned out to be less than 1 fF. This is only several times the average gate capacitance of a single VeSFET (see [15] for exact values), which means  $C_c$  can be realized with only a modest increase in the circuit size. With proper compensation, the output voltage settles within 5 ns. By way of comparison, the “conventional” OTA did not require any compensation, as evidenced in Fig. 17 (b). The output voltage, however, after taking about 10 ns to reach 70% of the step height, started creeping towards its final value at about 1% of its initial speed. This behavior is observed for both

TABLE II  
COMPARISON OF THE TWO OTA ARCHITECTURES: “CONVENTIONAL” (FIG. 15) AND USING INDEPENDENT GATES (FIG. 10)

Parameter	Conventional	Indep. gates
$A_d$ [V/V]	52.7	54.0
$A_c$ [mV/V]	310	29.6
CMRR [dB]	44.6	65.2
PSRR (DC) [dB]	37	46
Voffset [mV]	-0.26	1.28
Num. devices	47	29

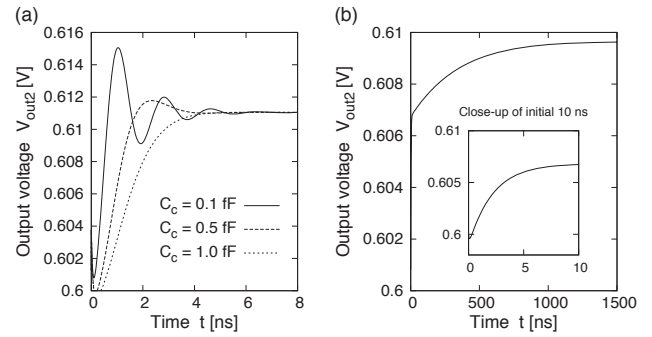


Fig. 17. Step responses of the proposed OTAs: using independent gates (a) and “conventional” (b), both in the voltage follower configuration i.e. with the inverting input connected to  $Out_2$ . The input stimulus is a 2-ps step from 0.6 V to 0.61 V.  $C_c$  is the value of compensation capacitor (found unnecessary in the “conventional” OTA). Note the time-scale difference between the plots

positive and negative input steps of various magnitudes. This is another argument in favor of the independent-gate architecture.

#### IV. EXAMPLE APPLICATION OF THE OTA

An example application of the independent-gate VeSFET OTA is a high-precision current mirror presented in Fig. 18. The OTA forces the drain voltage of  $M_{m1}$  to a value very close to that of  $M_{m2}$ . Unlike in a simple two-transistor current mirror, the drain voltages of  $M_{m1}$  and  $M_{m2}$  are kept equal by inserting the mirror in the feedback loop of the OTA. With identical gate-source and drain-source voltages, the drain currents of those two transistors are the same, even for output voltages well below the saturation voltage of  $M_{m2}$ . Assuming perfect matching of  $M_{m1}$  and  $M_{m2}$ , the only source of copying error is the amplifier offset. This is why the offset should be minimized for an arbitrary value of common-mode voltage. Fig. 19 (a) shows current-copying error as a function of the output voltage for various values of the reference current, while Fig. 19 (b) presents the corresponding output resistance.

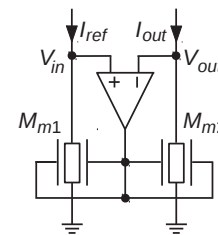


Fig. 18. Current mirror with an OTA in the feedback loop

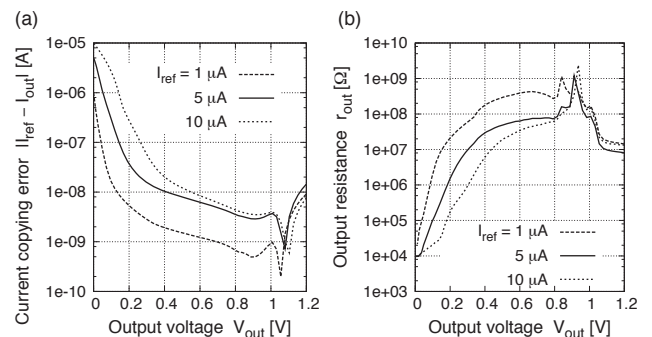


Fig. 19. Current mirror with the VeSFET-based OTA in the feedback loop: current copying error (a) and output resistance (b) for various values of the reference current

The copying error increases substantially only in situations where high output current is expected in spite of a low output voltage. This requires driving the transistors' gates to increasingly high voltages, which is limited by the saturation of the OTA's output at the  $V_{dd}$  level. For a typical situation of  $V_{out} = 0.6\text{ V}$  such saturation takes place if the reference current exceeds about  $13\ \mu\text{A}$ . For lower current levels (or larger output voltages) the source preserves good linearity, with relative errors of current copying less than 0.2%, as shown in Fig. 20. If higher currents or better parameters are expected, several parallel-connected VeSFETs must be used in place of  $M_{m1}$  and  $M_{m2}$ .

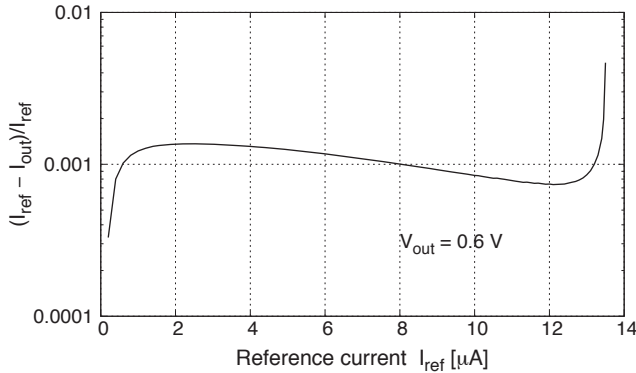


Fig. 20. Relative current-copying error of the OTA-based current mirror for a range of reference currents

## V. CONCLUSIONS AND FUTURE WORK

As shown in the previous sections, the VeSFET has promising properties as a component of analog circuits. The biasing conditions maximizing the transconductance and intrinsic voltage gain have been identified and explained based on the device's physics. The VeSFET has been shown to be superior to the equivalent-generation MOSFET in terms of transconductance, transconductance efficiency, intrinsic voltage gain, and cut-off frequency. The VeSFET's most important property, two independent gates controlling a common channel, enables introduction of strong feedback even in very simple circuits. As an example, two VeSFET-based OTA architectures have been compared. While their differential gain was identical, the one taking advantage of the VeSFET's two independent gates has been demonstrated to outperform the "conventional" Miller architecture in terms of CMRR and speed. Studies of the stability of VeSFET-based OTAs are under way.

## REFERENCES

- [1] W. Maly, "Integrated Circuit, Device, System, and Method of Fabrication", Patent Application WO 2007/133775 A2, 2007
- [2] W. Maly et al., "Twin Gate, Vertical Slit FET (VeSFET) for Highly Periodic Layout and 3D Integration," *Proc. 18th Intl. Conf. Mixed Design of Integrated Circuits and Systems MIXDES 2011*, Gliwice, Poland, 16–18 June 2011, pp. 145–150.
- [3] <http://vestics.org>
- [4] P. Freitas, G. Billiot, H. Lapuyade, J.B. Begueret, "Analog Design Considerations For Independently Driven Double Gate MOSFETs and Their Application in a Low-Voltage OTA," *Proc. 14th IEEE Intl. Conf. on Electronics, Circuits and Systems ICECS 2007*, 11–14 Dec. 2007, pp. 198–201.
- [5] A. Pfitzner, "Vertical-Slit Field-Effect Transistor (VeSFET) – Design Space Exploration and DC Model," *Proc. 18th Intl. Conf. Mixed Design of Integrated Circuits and Systems MIXDES 2011*, Gliwice, Poland, 16–18 June 2011, pp. 151–156.
- [6] A. Kamath et al., "Realizing AND and OR Functions With Single Vertical-Slit Field-Effect Transistor," *IEEE Electron Device Letters*, Vol. 33, No. 2, pp. 152–154, Feb. 2012
- [7] M. Weis et al., "Adder Circuits with Transistors Using Independently Controlled Gates," *Proc. IEEE Intl. Symposium on Circuits and Systems ISCAS 2009*, pp. 449–452.
- [8] Y.-W. Lin, M. Marek-Sadowska, W. P. Maly, "On Cell Layout-Performance Relationships in VeSFET-Based, High-Density Regular Circuits," *IEEE Trans. on Computer-Aided Design of Integrated Circuits and Systems*, Vol. 30, No. 2, Feb. 2011, pp. 229–241.
- [9] X. Qiu; M. Marek-Sadowska, W. Maly, "Vertical Slit Field Effect Transistor in Ultra-Low Power Applications," *Proc. 13th Intl. Symposium on Quality Electronic Design (ISQED)*, 19–21 March 2012, pp. 384–390.
- [10] D. Kasprowicz, B. Swacha, "VeSFET as an Analog-Circuit Component," *Proc. IEEE 16th International Symposium on Design and Diagnostics of Electronic Circuits and Systems DDECS 2013*, Karlovy Vary, Czech Republic, 8–10 April 2013, pp. 199–204.
- [11] Sentaurus Device, Synopsys, Inc., Dec. 2010, Version E-2010.12.
- [12] HSPICE, Synopsys, Inc., Dec. 2010, Version E-2010.12.
- [13] [http://ptm.asu.edu/modelcard/2006/90nm\\_bulk.pm](http://ptm.asu.edu/modelcard/2006/90nm_bulk.pm)
- [14] D. Foty, D. Binkley, M. Bucher, "Starting Over: gm/Id-Based MOSFET Modeling as a Basis for Modernized Analog Design Methodologies", *Technical Proc. 2002 Intl. Conf. on Modeling and Simulation of Microsystems*, Vol. 1, pp. 682–685.
- [15] D. Kasprowicz, "A compact model of VeSFET capacitances," *Proc. 18th Intl. Conf. Mixed Design of Integrated Circuits and Systems MIXDES 2011*, Gliwice, Poland, 16–18 June 2011, pp. 121–126.



**Dominik Kasprowicz** received his M.Sc. and Ph.D. degrees in Electrical Engineering (both with honors) from the Warsaw University of Technology (WUT) in 2001 and 2006, respectively. He has been an Assistant Professor in the Institute of Microelectronics and Optoelectronics of WUT since 2007. His fields of scientific interest include automated optimization of analog circuits and dual-gate transistor modeling. He has published about 20 scientific papers.



**Bartosz Swacha** received his B.Sc. degree in Electrical Engineering from the Warsaw University of Technology (WUT) in 2012. He is pursuing his M.Sc. degree at WUT. He is currently working on sensors for medical applications.