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MULTILINE QUEUEING SYSTEM WITH RANDOM TIME LIMITATIONS AND LIMITED BUFFER SPACE

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Abstract. In the paper, we investigate multi-server queueing systems with demands of random space requirements (volumes), in which buffer space is limited by constant value and queueing ore (and) service time are limited by exponentially distributed random variables. For such systems, stationary demands number distribution and loss probability are determined. Some numerical results are attached as well.

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convolution

1. Introduction

Queueing systems with demands of a random space requirement (or random volume) [1, 2] are the generalization of the classical queueing models [3, 4]. They can be used to model and solve various practical problems in the design of computer and communication systems (see e.g. [1, 2, 5]). In particular, such models can be applied to buffer space volume determination in the nodes of computer and communication networks. The main proposition of the theory of such systems [1] is the heterogeneity of demands served by the system with respect to their random volumes, in other words, we propose that different demands need different memory size (volume) during their presence in the system.

In the paper, we investigate queueing systems in which demands are also "impatient", i.e. they can leave the system during their waiting in the queue or (and) during their servicing. In the classical queueing theory (for demands without random volume), systems with times limitations were investigated e.g. in [4, 6]. In particular, in [6] queueing systems with random limitations of queueing and (or)

service time were investigated. In the paper [7], the system with random volume demands, deterministically limited total demands volume and deterministically limited queueing or sojourn time were analyzed.

In this paper, we investigate a similar system, but the difference is that, in the system under consideration, queueing and (or) service time are limited by exponentially distributed random variables. For example, we have a situation when a demand contains some information that can be grown old fore random reasons, and therefore it must be eliminated from the system.

The paper is organized as follows: In the Section 2, we give the mathematical description of the model and introduce some necessary notations. In Section 3, we introduce the functions describing the system behavior and define an appropriate Markov process. In Section 4, we build a system of differential equations for the function introduced in Section 3 and give its steady-state solution, from which the steady-state demands number distribution is determined. In Section 5, we determine the loss probability for the system under consideration. Section 6 contains examples of numerical results illustrating theoretical formulas, and the last Section 7 presents conclusions and final remarks.

2. Model description

We consider a queueing system of $M/M/n/m \le \infty$ -type, in which all demands are characterized by some random volume (or space requirement) ζ , where ζ is a non-negative random variable that doesn't depend on the volumes of other demands and the epoch of the demand's entering to the system. Denote by $L(x) = \mathbf{P}\{\zeta < x\}$ the distribution function of the random variable ζ . Let $\sigma(t)$ be the total demands volume or the sum of all volumes of demands present in the system at time instant t. The values of the random process $\sigma(t)$ are bounded by the constant value V(V > 0) named the system buffer capacity. Let $\eta(t)$ be the number of demands present in the system at time instant t.

If a demand of volume x arrives to the system at epoch t when there are $\eta(t^-) < n+m$ other demands in it and $\sigma(t^-) + x \le V$, we have $\sigma(t) = \sigma(t^-) + x$, $\eta(t) = \eta(t^-) + 1$ and the demand is accepted to the system. In opposite case $(\sigma(t^-) + x > V)$, the demand will be lost without influence to future system behavior. In this case, we have $\sigma(t) = \sigma(t^-)$, $\eta(t) = \eta(t^-)$. The arriving demand will be lost also if there are m+n other demands at the epoch t.

Demands accepting to the system are served in accordance to FIFO discipline. But their queueing time and (or) sojourn time are limited by some random variables having an exponential distributions with parameters ν and α , respectively, i.e. demands can leave the system (be lost) during waiting in the queue or servicing. In particular, if only queueing time is limited in the system, we have $\alpha = 0$; if only service time is limited, we have $\mu = 0$; and if sojourn time is limited in the system, we obtain $\nu = \alpha$. Let a be the parameter of demands enter flow, μ be

the parameter of service time (we assume that service time doesn't depend on the demand volume). We also assume that the traffic load of the system $\rho = a/[n(\mu + \alpha)]$ is finite ($\rho < \infty$).

Our aim is the determination of the steady-state distribution of number of demands present in the system and the demand loss probability.

3. Process and characteristics

The behavior of the system under consideration can be described by the following Markov random process

$$(\eta(t), \sigma_1(t), ..., \sigma_{\eta(t)}(t)), \tag{1}$$

where $\sigma_j(t)$ is the volume of the *j*-th demand presenting in the system at time instant *t*. It is clear that $\sigma(t) = \sum_{k=1}^{\eta(t)} \sigma_j(t)$.

The process (1) we shall characterize by the functions having the following probability sense:

$$P_0(t) = \mathbf{P}{\eta(t) = 0};$$
 (2)

$$P_k(t) = \mathbf{P}\{\eta(t) = k\}, \ k = \overline{0, n+m}; \tag{3}$$

$$G_k(y,t) = \mathbf{P}\{\eta(t) = k, \sigma(t) < y\}, \ k = \overline{1, n+m}. \tag{4}$$

It is clear that, for $k = \overline{1, n+m}$, we have $P_k(t) = G_k(V, t)$.

4. Steady-state distribution of demands present in the system

It can be easily shown that the functions (2)-(4) satisfy the following Kolmogorov-type equations (see also [8] for comparison):

$$\frac{dP_0(t)}{dt} = -aL(V)P_0(t) + (\mu + \alpha)P_1(t);$$
 (5)

$$\frac{dP_1(t)}{dt} = aL(V)P_0(t) - a\int_0^V G_1(V - y, t) dL(y) - (\mu + \alpha)P_1(t) + 2(\mu + \alpha)P_2(t); \quad (6)$$

$$\frac{dP_k(t)}{dt} = a \int_0^V G_{k-1}(V - y, t) dL(y) - a \int_0^V G_k(V - y, t) dL(y) - (-k(\mu + \alpha)P_k(t) + (k+1)(\mu + \alpha)P_{k+1}(t), k = \overline{2, n-1};$$
(7)

$$\frac{dP_k(t)}{dt} = a \int_0^V G_{k-1}(V - y, t) dL(y) - a \int_0^V G_k(V - y, t) dL(y) - (8)$$

$$- [n(\mu + \alpha) + (k - n)v]P_k(t) + [n(\mu + \alpha) + (k - n + 1)v]P_{k+1}(t), k = \overline{n, n + m - 1};$$

$$\frac{dP_{n+m}(t)}{dt} = a \int_{0}^{V} G_{n+m-1}(V - y, t) dL(y) - [n(\mu + \alpha) + m\nu] P_{n+m}(t). \tag{9}$$

Assume that at least one of the values m and V is finite. Then, we have obviously that $\eta(t) \Rightarrow \eta$, $\sigma(t) \Rightarrow \sigma$ when $t \to \infty$ in the sense of a weak convergence, where the random variables η and σ are the steady-state number of demands present in the system and their total volume, consequently. So, the following finite limits exist:

$$p_k = \mathbf{P}\{\eta = k\} = \lim_{t \to \infty} P_k(t), k = \overline{0, n + m}; \tag{10}$$

$$g_k(y) = \mathbf{P}\{\eta = k, \, \sigma < y\} = \lim_{t \to \infty} G_k(y, t), \, k = \overline{1, n + m}. \tag{11}$$

We have evidently $p_k = g_k(V)$ for k = 1, n + m.

It follows from the equations (5)-(9) that the steady-state characteristics (10) and (11) satisfy the following equations:

$$0 = -aL(V)p_0 + (\mu + \alpha)p_1; (12)$$

$$0 = aL(V)p_0 - a\int_0^V g_1(V - y)dL(y) - (\mu + \alpha)p_1 + 2(\mu + \alpha)p_2;$$
 (13)

$$0 = a \int_{0}^{V} g_{k-1}(V - y) dL(y) - a \int_{0}^{V} g_{k}(V - y) dL(y) - (14)$$
$$-k(\mu + \alpha) p_{k} + (k+1)(\mu + \alpha) p_{k+1}, k = \overline{2, n-1};$$

$$0 = a \int_{0}^{V} g_{k-1}(V - y) dL(y) - a \int_{0}^{V} g_{k}(V - y) dL(y) - \frac{1}{2} \int_{0}^{V} g_{k}(V - y) dL(y) - \frac{1}{2} \int_{0}^{V} g_{k-1}(V - y) dL(y) dL(y) - \frac{1}{2} \int_{0}^{V} g_{k-1}(V - y) dL(y) dL(y) - \frac{1}{2} \int_{0}^{V} g_{k-1}(V - y) dL(y) dL(y)$$

$$0 = a \int_{0}^{V} g_{n+m-1}(V - y) dL(y) - [n(\mu + \alpha) + mV] p_{n+m}.$$
 (16)

Introduce the following notation for the Stieltjes convolution of the distribution function L(x): $L_*^{(0)}(y) \equiv 1$, $L_*^{(k)}(y) = \int_0^y L_*^{(k-1)}(y-x) dL(x)$, k = 1, 2, ...

Then, by direct substitution, we can easily show that the solution of the Eqs. (12)-(16) has the form:

$$g_{k}(y) = \begin{cases} p_{0} \frac{(n\rho)^{k}}{k!} L_{*}^{(k)}(y), & 1 \leq k \leq n; \\ p_{0} \frac{n^{n} \rho^{k}}{n!} \left[\prod_{j=0}^{k-n} (1+j\beta) \right]^{-1} L_{*}^{(k)}(y), & n+1 \leq k \leq n+m, \end{cases}$$

$$(17)$$

where $\beta = v/[n(\mu + \alpha)]$.

We have from the relations (17) that

$$p_{k} = g_{k}(V) = \begin{cases} p_{0} \frac{(n\rho)^{k}}{k!} L_{*}^{(k)}(V), & 1 \leq k \leq n; \\ p_{0} \frac{n^{n} \rho^{k}}{n!} \left[\prod_{j=0}^{k-n} (1+j\beta) \right]^{-1} L_{*}^{(k)}(V), & n+1 \leq k \leq n+m. \end{cases}$$
(18)

The probability p_0 can be determined from the normalization condition $\sum_{k=0}^{n+m} p_k = 1$, whereas we obtain:

$$p_0 = \left\{ \sum_{k=0}^n \frac{(n\rho)^k}{k!} L_*^{(k)}(V) + \frac{n^n}{n!} \sum_{k=n+1}^{n+m} \rho^k \left[\prod_{j=0}^{k-n} (1+j\beta) \right]^{-1} L_*^{(k)}(V) \right\}^{-1}.$$

5. Loss probability

Let A be the event that an arbitrary arriving demand is accepted to the system and served completely and K be the mean number of busy servers in steady state. We have evidently that $K = \sum_{k=1}^{n} kp_k + n \sum_{k=n+1}^{n+m} p_k$, and we obtain for probability of the event A: $\mathbf{P}\{A\} = \mu K/a$. Then, the probability that an arbitrary demand is lost at its arriving epoch or is not served completely can be determined as $P_{loss} = 1 - \mathbf{P}\{A\} = 1 - \frac{\mu K}{a}$.

6. Numerical examples

In this section, we present numerical examples illustrating theoretical results. More precisely, we present how the loss probability P_{loss} depends on the buffer capacity V and the parameters μ , α , β . Assume that the volumes of entering demands are exponentially distributed with parameter f = 1 and service time has an exponential distribution with parameter μ . Consider three cases of the considered system when n = 1 (a single-server system).

In the first case (Figs. 1 and 2), only the queueing time is limited, i.e. we have $\alpha = 0$. Assume that the system buffer capacity V takes the values from 0 to 10, and the parameter ν takes the values from 0 to 2. Furthermore, when a = 1 and $\mu = 0.5$, then $\beta = 2\nu$ and $\rho = 2$. For example, if there is one waiting place in the queue (m = 1), then, for $\nu = 1$ and V = 2, the loss probability P_{loss} is equal to 0.68765 (Fig. 1). If m = 3, then $P_{loss} = 0.701542$ (Fig. 2).

In the second case, only service time is limited (Figs. 3 and 4), then we have $\nu=0$. Assume that the system buffer capacity V takes the values from 0 to 5, and the parameter α takes the values from 0 to 2. Furthermore, when $\alpha=1$ and $\mu=0.5$, then $\beta=0$ and $\rho=1/(0.5+\alpha)$. For example, if the queue size is 1 (m=1), for $\alpha=2$ and V=1, the loss probability $P_{loss}=0.898072$ (Fig. 3). If m=3, then we have $P_{loss}=0.8985$ (see Fig. 4).

In the third case, the sojourn time of demand in the system is limited, then we assume $v = \alpha$ (Figs. 5 and 6). Assume that V takes the values from 0 to 5 and α takes values from 0 to 2. In addition, when a = 1 and $\mu = 0.5$, we have $\beta = \alpha/(0.5 + \alpha)$ and $\rho = 1/(0.5 + \alpha)$. For example, if there is one waiting place in the queue (m = 1), for $\alpha = 2$ and V = 1, we have $P_{loss} = 0.898516$ (Fig. 5). If m = 3, then $P_{loss} = 0.898603$ (Fig. 6).

7. Conclusions

In the paper, we consider a multiline queueing system with random time limitations and limited buffer space. The determination of the steady-state distribution of number of demands present in the system and the demand loss probability are presented. Some special cases of the system under consideration are provided with numerical calculations in Maple. In any case, when the number of waiting places increases, of course the loss probability of demand also increases. This model shows the loss probability of demand (see Figs. 1-6). The results obtained in the paper can be used for estimating of total demands volume characteristics in the nodes of computer and telecommunication networks.

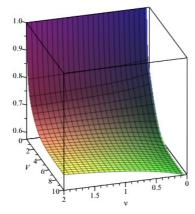


Fig. 1. Loss probability, m = n = 1, $\alpha = 0$

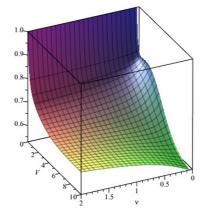


Fig. 2. Loss probability, n = 1, m = 3, $\alpha = 0$

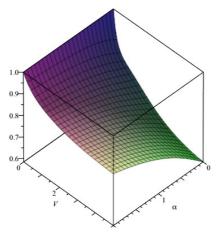


Fig. 3. Loss probability, m = n = 1, v = 0

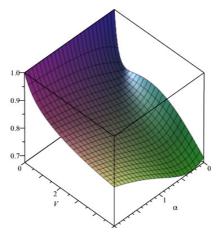


Fig. 4. Loss probability, n = 1, m = 3, $\nu = 0$

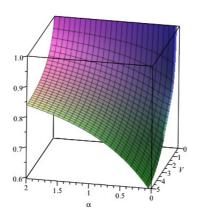


Fig. 5. Loss probability, m = n = 1, $v = \alpha$

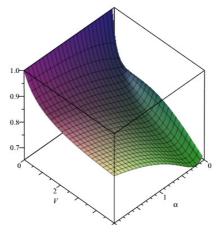


Fig. 6. Loss probability, n = 1, m = 3, $v = \alpha$

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