MAKING IT HAPPEN BUILDING AND DEVELOPING TRACK QUALITY MEASUREMENT (TQM) TROLLEY

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INTRODUCTION

Network Rail standard of measuring Track Quality was set by the HSTRC (High Speed Track Recording Car). In the last couple of years Network Rail introduced HSTRC successor, packed with modern technology highly sophisticated NMT (New Measurement Train). Both trains deliver excellent results on high speed measurement and less accurate on slow speed recording.

The purpose of building the TQM was prompted by an idea of extending existing standard onto the areas where high speed measurement are less reliable. In technical terms it meant building a system capable to emulate the HSTRC standard (Fig. 11) from the data recorded at walking speed.

1. WHAT IT IS AND WHAT IT DOES ?

TQM stands for Track Quality Measurement recorder. TQM measures the following track geometry parameters (Fig. 3):

- Horizontal Versine (on various chord length)
- Vertical Versine (on various chord length)
- Longitudinal Level (on various chord length)
- Cross Level
- Gauge
- Distance along the track



Fig.1. TQM (Track Quality Measurement) trolley.

By using those parameters TQM software is able to emulate the Network Rail track quality standard (Fig.11) set by HSTRC or NMT.

In order to bring closer to the reader all perplexities encountered in designing and manufacturing of a TQM, the Short Base Measurement (SBM) terminology needs to be adopted to describe a problem (Fig. 2) which finally had a biggest impact on TQM concept design solution. SBM measuring references are physically constructed rigid bases of user definable length in a range from 1 to 4 metres. Various track measurements are taken against those bases which are simply pulled or carried out onboard of a transporting trolley frame (Fig.3)

SBM disadvantages are well known to the Engineering Surveying profession. All surveyors are trying to avoid short referring bases (RO) in their surveying practises in order to secure accuracy of the detail surveyed. TQM intension, however, was directed in the hart of this problem by trying to succeed in carrying the survey in a "wrong" way (short RO reference) and hoping to deliver the picture of a long shaped track alignment. Those are the stages of a struggle and thinking encountered in order to make this project successful.

+/-		2mm	+/-	2mm	+/- 2mm		+/- 2mm		Accuracy goal for LB (Long Base) generated						
	10m	20m	10m	20m	10m	20m	10m	20m	Horizontal Versine (on 10 or 20m chord)						
	1m		2m		3m		4m		Short Base length (SB) used						
	100	400	25	100	11	44	6	25	Projection Scale $(LB)^2/(SB)^2$						
	+/- 0.02	+/- 0.005	+/- 0.08	0.02	+/- 0.18	+/- 0.05	+/- 0.32	+/- 0.08	Expected Short Base (SB) measurement accuracy						
Γ	Compiled results on 1000m radius curve					n radiu	is curv	To read the figures follow the example: In order to achieve +/-2mm accuracy in software							
	SB	B HV magnit. SB HV Accur.20m HV Accuracy			HV Ac	curacy	generated HV on 20m chord length a singular HV								
	1m	0.12	2mm	+/-0.005mm		c			reading on 2m long SB chord has to be measured						
	2m	0.50	Omm	+/-0	.02mm		50mm		with accuracy of ± -0.02 mm. This translated on						
	3m 4m	1.12	2mm 0mm	+/-0 +/-0	.05mm .08mm	-	+/-2mn	n	+/-0.02mm gives 50mm+/-2mm gen. 20m LB HV						

2. THE IMPACT OF ACCURACY ANALYSIS ON CONCEPT DESIGN

Fig. 2. Expected Short Base measurement accuracy.



Fig. 3. TQM concept design.

3. ADDRESSING SB CONCEPT SOLUTION

Advantages:

- Stable reference base (no loss of accuracy on pivoting)
- Ability to introduce reciprocal reading corrections
- Ability to use suitable base lengths for various application
- Calibration parameters stay with the SB (not with the trolley)
- Flexibility in choosing calibration place office or track
- Lightweight TQM modules can be easily carried onto the track or the metro station

Disadvantages:

• Measurements are not always going to be taken in the right place (Fig.5)





Fig. 4. Variable gauge Cant errors.

Fig. 5. Vertical and Horizontal unevenness against TQM SB's.

<u>Note:</u> When the out of square railhead section is measured using rigid SB's the following errors are introduced to the recorded data: Vertical Unevenness creates non existing Horizontal Unevenness and accordingly Horizontal Unevenness creates non existing Vertical Unevenness (Fig.5).

To eliminate this inconvenience the following software corrections were introduced:

- Hor. Versine readings are correcting Vert. Versine readings
- Vert. Versine readings are correcting Hor. Versine readings

Additionally high cant, gage variation and trolley acceleration negative influence on reading quality was removed as follows:

- Cross Level readings are correcting Longitudinal Level readings
- Time stamp readings (interval reading acceleration) are correcting Longitudinal Level readings
- Gauge readings are correcting Cross Level readings (Fig.4)

All other type of errors (trolley frame free movement errors) were removed mechanically

4. ENSURING ACCURACY

By performing calibration operator gets confidence to the system ability and to the quality of the data recorded.

The following aspects of TQM calibration was taken care of:

- Software controlled calibration procedure (Fig.7)
- Calibration tools development
- Assessment and elimination of ambient temperature negative effect on reading quality



Fig. 6. Conversion factor and Zero calibration procedure.

Download Date m (HV) m (LL) m (CL) m (VV) m(Gauge) TOM_FACT.CAL 28/06/2006 -4 9409 -55.5554 -42.7982 -2.4759 -7.3332	Cert Block 1 Cert Block 2 Cert Block 3 Factor Calibration
Position 1 Position 2 Position 3 Zero Calibration	HV 00 CAL 20 CAL 40 CAL CAL Accept m = 0.0127 4.5409
	9.8510 5.7628 5.7628 Prev m= 4.8221
234786 UNL 4.5956 UNL 4.5956 UNL 4.5956 UNL ACCEPT COLUMN C= 234786	-55.6584 0.2530 -0.8453 -3.3404 CAL CAL Prev m: -55.6384 Prev m: -55.6384
4.4819 CAL -0.0773 CAL 0.2378 CAL -0.0762 CAL Accept CAL C = 0.0306 C = 4.4819	CL 00 CAL 50 CAL 2200 CAL 42.7962 0.1162 1.2845 5.9576 CAL CAL CAL CAL 0.300 Provide 42.6823
CL Prev C= Ock Ock Prev C= Ock	VV 00 CAL 05 CAL 10 CAL CAL Accept im = 0.0141 m = -2.4759
VV Prov C= 12.7712 12.5484 CAL 5.0123 CAL 5.1219 CAL Accept Image: Colored	-2.2/59 9.6350 7.6155 5.5960 Prov.m2.4643
Gauge Prev C= 35.5166 35.5376 CAL 4.5524 CAL 5.1242 CAL 4.5837 CAL Accept EEE 3.5.5376	CAL Mail Cal <t< td=""></t<>
SAVE & EXIT	SAVE & EXIT

Fig. 7. Software controlled calibration procedure.

5. DATA SAMPLING AND DATA PROCESSING

Data sampling was set @ 0.1m interval with sampling rate of 14 Hz (walking speed recording). All eight TQM channels are recorded at this speed. With respect to the lengths of SB used this solution has produced SB[m]/(2*0.1)[m] numbers of independent sets of overlapping versine data (eg. 3m SB delivers 15 sets of data). Translating this into the memory consumption it takes approx. 1mb of memory per 1km of survey data recorded.

Calculation stages:

- Applying calibration parameters to the raw observation
- Applying all data corrections
- Calculating most probable readings @ 0.5m interval from readings recorded @ 0.1m
- Compiling Alignment and Top rail profiles (Left and Right rail)
- Applying 35m and 70m wavelength Butterworth filter
- Calculating SD
- Validating SD against the Network Rail SD Track Quality criteria
- Generating all obligatory Track Quality reports

5.1 Hardware platform

A desire to record, process and transmit the data directly from the field to the office (or tamper) concerned pointed out to use a Windows based, standard PC equipped with suitable DAQ card.

After long struggle in finding a reliable solution, Itronix tablet PC housing National Instruments DAQ card, was chosen.

This set of hardware copes favourably with all type of vibrations, weather conditions and magnetic fields encountered during track survey.

5.2 Software Solution

The following package of TQM software was developed for TQM system: TQM Calibrator, TQM Recorder, TQM Editor and TQM Viewer

	TABLE			MeaHV	eaVV M		eaCL		MeaLL	
RECORDING	ALL C	S	MeaGau	ge	GenGauge		GenTwist		enTwist	
	Distance	MeaHV	MeaVV	GenGauge	MeaGg	Twist	MeaCL	MealL	Eve	ent Time
Sensors	0.1803	-0.70	0.27	1434.61	0.31	1.80	36.72	-11.99	1	1228.949
File Name	0.1805	-0.70	0.25	1434.65	0.35	2.39	36.92	-13.09	1	1229.177
BernoUPF.tqm	0.1807	-0.85	0.33	1434.58	0.42	-0.00	37.12	-13.65	1	1229.409
CONFIGURE	0.1809	-0.94	0.31	1434.62	0.60	1.00	36.72	-11.99	1	1229.638
Distance [km]	0.1812	-1.09	0.54	1434.58	0.67	0.60	36.32	-10.33	1	1229.981
0.181734	0.1813	-0.97	0.40	1434.67	0.64	0.20	36.52	-7.01	1	1230.213
RESET	0.1816 0.1817	-0.77	0.51	1434.50 1434.66	0.28	1.60	37.32 35.93	-10.33	1	1230.441 1230.557
Speed [m/sec]										
0.962										
EVIT	TAN		C	CC		SAME			BRIDGE	
EXII	STR		SV	VN	SW	r	FP			MP

Fig. 8. All channels table form recording.



TQM Editor v1.7.0.72 User:MJL Computer:TQM Date:Sat 23 Sep 2006

- 4 09:21:47 Original TQM file: RL11.TQM
- 4 09:21:47 Copying TQM file to: Current
- 4 09:21:47 TQM file RL11.TQM in standard format
 4 09:21:47 Existing backup file not overwritten: \BKP\RL11.TQM
 4 09:23:45 Reversing locations
 4 09:24:19 Updating all recordings of channel MeaVV by 0.25
 4 09:26:55 Interpolating channel MeaCL between (-14.6880, -1.23)
- 4 09:27:40 Setting nominal gauge to 1435
- 4 09:27:40 Recalc
- 4 09:29:07 Applying post-meas. Correct.

Fig. 10. Fully controlled data editing.



Fig. 9. Selected channel graph recording.

TQM Track Quality - Exceedence Report
DATE : 06/09/2006 @ 13:00:51 FILE : C:\TQM data\sun3.tgm ELR : Track : Down Line
MIs-Yard (Chn)LspdTW3M L_TOP R_TOP LCYC RCYC AI35 Mph +ve -ve +ve -ve Mm 0m 134y (6c) 30 8 8 8 0m 136y (6c) 30 20 8 8
TQM Track Quality - Action Report
Mis-Yard (Chn):L/Spd: Fault Value : CORRECTED BY : DATE : Remarks
0m 134y (6c): 30 : G VAR 9mm : : : ASSESS/10day
0m 154y (7c): 30 : G VAR 9mm : : : : ASSESS/10day
TQM Track Quality - Graph Report
TOM Track Quality SD Bagart
Individuality - SD Report
TRACK QUALITY REPORT Good/Issu/Poor/Vmasfe LATE: 0(4)2006 # 31300511 FILE: 0:1V2M DataJaun3.tgm ER:R : Teach: 100M LINE
MILe / Eighth 17M3M Ex (LTOP E+ E- 1RTOP E+ E- 1RT35 E+ E- 1AL35 Ex 1GAUG E+ E- 1MT701AL701 MPH
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
$\begin{array}{cccccccccccccccccccccccccccccccccccc$
1/5 - 1/6 : 13 0 : 13 0 0 : 15 1 0 : 16 1 0 : 8 0 : 1433 0 15 : 25 : 15 : 100

Fig. 11. TQM Track Quality reports.

6. ERRORS, TESTS AND COMPARISONS



Fig. 12. Certified blocks measurement.



Fig. 13. Survey differences: HSTRC, Manual Survey, TQM.

Twenty Certified Blocks (CB) were measured in 20 series using calibrated TQM modules for HV and Gauge. Graph shows maximum discrepancies of all measurement. Lines represent series of observation. For clarity not all of the series were plotted on the drawing

Survey differences: High Speed Track Recording Car (HSTRC), Manual Survey, TQM data comparison (Fig.14) Dash blue line represents mean value of differences of +/-2mm between relevant data recording of Manual Survey and HSTRC survey. Test was carried out on 100m/hr track including reverse curves of 2000-3000m radius

7. RECENT CASE STUDY

Most recently TQM played a major role in the Network Rail PALAS project by validating the position of a Fixed Points coordinates and measuring track quality to assess the effectiveness of a Palas system. For this purpose a Total Track Survey (TTS) technique was developed using onboard mounted Leica 1201 Total Station.

TTS is a surveying technique which delivers track spatial data from the survey observations, recorded from arbitrary points rather than from a previously coordinated stations (Fig.14).



Fig. 14. Overlapping Versine (Leica 1201).



Fig. 15. Studs coordinates validation.



For this purpose a TPG (Fig.15) was developed and the n4CE codes (Application in Cadd software package) were written to automate coordinate generation for both rails.

Fig. 16. TPG (Track Prism Gauge).

Illustrated in Fig.18 surveying procedure shows TQM stopping position where all overlapping resections to the stud prisms and relevant TPG observations were recorded. n4CE derived SD resection validation (Fig.15 – white box numbers) permits prompt identification of an erroneous coordinates (red numbers).

Such overlapped resection observation can be further "least square" adjusted using network adjustment software packages (STARNET).

The main advantages for using this surveying technique over the traditional ones are:

increased accuracy of derived coordinates (no instrument centring errors involved)
 shortening survey time

In one survey run TQM TTS technique delivers: Full Track Quality data, validates integrity (or derives new) Track Control coordinates, validates or derives all Fixed Points data.

More detailed information about TQM system can be found in: www.rail-tqm.co.uk

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