

# COMPUTATIONAL METHODS FOR INVESTIGATION OF STABILITY OF MODELS OF 2D CONTINUOUS-DISCRETE LINEAR SYSTEMS

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## Abstract:

The problem of asymptotic stability of models of 2D continuous-discrete linear systems is considered. Computer methods for investigation of asymptotic stability of the Fornasini-Marchesini type and the Roesser type models, are given. The methods proposed require computation of the eigenvalue-loci of complex matrices. Effectiveness of the stability tests are demonstrated on numerical examples.

**Keywords:** continuous-discrete system, hybrid system, linear system, stability, computational methods.

## 1. Introduction

In continuous-discrete systems both continuous-time and discrete-time components are relevant and interacting and these components can not be separated. Such systems are called the hybrid systems. Examples of hybrid systems can be found in [6], [8], [9], [16]. The problems of dynamics and control of hybrid systems have been studied in [5], [6], [16].

In this paper we consider the continuous-discrete linear systems whose models have structure similar to the models of 2D discrete-time linear systems. Such models, called the 2D continuous-discrete or 2D hybrid models, have been considered in [11] in the case of positive systems.

The new general model of positive 2D hybrid linear systems has been introduced in [12] for standard and in [13] for fractional systems. The realization and solvability problems of positive 2D hybrid linear systems have been considered in [11], [14] and [15], [17], respectively.

The problems of stability and robust stability of 2D continuous-discrete linear systems have been investigated in [1-4], [7], [18-20].

The main purpose of this paper is to present computational methods for investigation of asymptotic stability of the Fornasini-Marchesini and the Roesser type models of continuous-discrete linear systems.

The following notation will be used:  $\mathfrak{R}$  - the set of real numbers,  $\mathfrak{R}_+ = [0, \infty]$ ,  $Z_+$  - the set of non-negative integers,  $\mathfrak{R}^{n \times m}$  - the set of  $n \times m$  real matrices and  $\mathfrak{R}_+^n = \mathfrak{R}_+^{n \times 1}$ ,  $\|x(\cdot)\|$  - the norm of  $x(\cdot)$ ,  $\lambda_i\{X\}$  -  $i$ -th eigenvalue of matrix  $X$ .

## 2. Preliminaries and formulation of the problem

The state equation of the Fornasini-Marchesini type model of a continuous-discrete linear system has the form [11]

$$\begin{aligned} \dot{x}(t, i+1) &= A_0 x(t, i) + A_1 \dot{x}(t, i) + A_2 x(t, i+1) + Bu(t, i), \\ i &\in Z_+, t \in \mathfrak{R}_+, \end{aligned} \quad (1)$$

where  $\dot{x}(t, i) = \partial x(t, i) / \partial t$ ,  $x(t, i) \in \mathfrak{R}^n$ ,  $u(t, i) \in \mathfrak{R}^m$ , and  $A_0, A_1, A_2 \in \mathfrak{R}^{n \times n}$ ,  $B \in \mathfrak{R}^{n \times m}$ .

**Definition 1.** The Fornasini-Marchesini type model (1) is called asymptotically stable (or Hurwitz-Schur stable) if for  $u(t, i) \equiv 0$  and bounded boundary conditions

$$x(0, i), i \in Z_+, x(t, 0), \dot{x}(t, 0), t \in \mathfrak{R}_+, \quad (2)$$

the condition  $\lim_{i, t \rightarrow \infty} \|x(t, i)\| = 0$  holds for  $t, i \rightarrow \infty$ .

The characteristic matrix of the model (1) has the form

$$H(s, z) = szI_n - A_0 - sA_1 - zA_2. \quad (3)$$

The characteristic function

$$w(s, z) = \det H(s, z) = \det[szI_n - A_0 - sA_1 - zA_2] \quad (4)$$

of the model (1) is a polynomial in two independent variables  $s$  and  $z$ , of the general form

$$w(s, z) = \sum_{k=0}^n \sum_{j=0}^n a_{kj} s^k z^j, a_{nn} = 1. \quad (5)$$

The state equation of the Roesser type model of a continuous-discrete linear system has the form [11]

$$\begin{aligned} \begin{bmatrix} \dot{x}^h(t, i) \\ x^v(t, i+1) \end{bmatrix} &= \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} x^h(t, i) \\ x^v(t, i) \end{bmatrix} + \begin{bmatrix} B_1 \\ B_2 \end{bmatrix} u(t, i), \\ t &\in \mathfrak{R}_+, i \in Z_+, \end{aligned} \quad (6)$$

where  $\dot{x}^h(t, i) = \partial x^h(t, i) / \partial t$ ,  $x^h(t, i) \in \mathfrak{R}^{n_1}$ ,  $x^v(t, i) \in \mathfrak{R}^{n_2}$  are the vertical and the horizontal vectors, respectively,  $u(t, i) \in \mathfrak{R}^m$  is the input vector and  $A_{11} \in \mathfrak{R}^{n_1 \times n_1}$ ,  $A_{12} \in \mathfrak{R}^{n_1 \times n_2}$ ,  $A_{21} \in \mathfrak{R}^{n_2 \times n_1}$ ,  $A_{22} \in \mathfrak{R}^{n_2 \times n_2}$ ,  $B_1 \in \mathfrak{R}^{n_1 \times m}$ ,  $B_2 \in \mathfrak{R}^{n_2 \times m}$ .

The boundary conditions for (6) are as follows

$$x^h(t, 0), x^v(t, 0), t \in \mathfrak{R}_+, x^h(0, i), x^v(0, i), i \geq 1, i \in Z_+. \quad (7)$$

**Definition 2.** The Roesser type model (6) is called asymptotically stable (or Hurwitz-Schur stable) if for  $u(t, i) \equiv 0$  and bounded boundary conditions (7) the conditions  $\lim_{i, t \rightarrow \infty} \|x^h(t, i)\| = 0$  and  $\lim_{i, t \rightarrow \infty} \|x^v(t, i)\| = 0$  hold for  $t, i \rightarrow \infty$ .

The characteristic matrix of the model (6) has the form

$$H(s, z) = \begin{bmatrix} sI_{n_1} - A_{11} & -A_{12} \\ -A_{21} & zI_{n_2} - A_{22} \end{bmatrix} \quad (8)$$

Using the rules for computing the determinant of block matrices [10], we obtain that the characteristic function  $w(s, z) = \det H(s, z)$  of the Roesser type model can be computed from one of the following equivalent formulae

$$w(s, z) = \det(zI_{n_2} - A_{22}) \det(sI_{n_1} - A_{11} - A_{12}(zI_{n_2} - A_{22})^{-1}A_{21}), \quad (9a)$$

$$w(s, z) = \det(sI_{n_1} - A_{11}) \det(zI_{n_2} - A_{22} - A_{21}(sI_{n_1} - A_{11})^{-1}A_{12}). \quad (9b)$$

The characteristic function of the Roesser type model can be written in the form

$$w(s, z) = \sum_{k=0}^{n_1} \sum_{j=0}^{n_2} a_{kj} s^k z^j, a_{n_1 n_2} = 1. \quad (10)$$

From [1], [7] we have the following theorem.

**Theorem 1.** The Fornasini-Marchesini type model (1) with characteristic function (4) (or the Roesser type model (6) with characteristic function (9)) is asymptotically stable if and only if

$$w(s, z) \neq 0, \operatorname{Re} s \geq 0, |z| \geq 1. \quad (11)$$

The polynomial  $w(s, z)$  satisfying condition (11) is called continuous-discrete stable (C-D stable) or Hurwitz-Schur stable [1].

The main purpose of this paper is to present computational methods for checking the condition (11) of asymptotic stability of the Fornasini-Marchesini type model (1) and the Roesser type model (6) of continuous-discrete linear systems.

### 3. Solution of the problem

**Theorem 2.** The condition (11) is equivalent to the following two conditions

$$w(s, e^{j\omega}) \neq 0, \operatorname{Re} s \geq 0, \forall \omega \in [0, 2\pi], \quad (12)$$

$$w(jy, z) \neq 0, |z| \geq 1, \forall y \in [0, \infty). \quad (13)$$

**Proof.** From [7] it follows that (11) is equivalent to the conditions

$$w(s, z) \neq 0, \operatorname{Re} s \geq 0, |z| = 1, \quad (14)$$

$$w(s, z) \neq 0, \operatorname{Re} s = 0, |z| \geq 1. \quad (15)$$

It is easy to see that conditions (14) and (15) can be written in the forms (12) and (13), respectively. ■

#### 3.1. Asymptotic stability of the Fornasini-Marchesini type model

From (4) for  $z = e^{j\omega}$  we have

$$w(s, e^{j\omega}) = \det[s(I_n e^{j\omega} - A_1) - A_2 e^{j\omega} - A_0]. \quad (16)$$

**Lemma 1.** The condition (12) for the Fornasini-Marchesini type model (1) with  $A_1 \neq \pm I_n$  holds if and only if all eigenvalues of the complex matrix  $S_1^{FM}(e^{j\omega})$  have negative real parts for all  $\omega \in [0, 2\pi]$ , where

$$S_1^{FM}(e^{j\omega}) = (I_n e^{j\omega} - A_1)^{-1} (A_2 e^{j\omega} + A_0). \quad (17)$$

**Proof.** If  $A_1 \neq \pm I_n$  then the matrix  $I_n e^{j\omega} - A_1$  is non-singular for all  $\omega \in [0, 2\pi]$  and

$$[s(I_n e^{j\omega} - A_1) - A_0 - A_2 e^{j\omega}] = [I_n e^{j\omega} - A_1][s - S_1^{FM}(e^{j\omega})], \quad (18)$$

where  $S_1^{FM}(e^{j\omega})$  has the form (17).

From (16) and (18) it follows that

$$w(s, e^{j\omega}) = \det(I_n e^{j\omega} - A_1) \det(sI_n - S_1^{FM}(e^{j\omega})). \quad (19)$$

This means that for  $A_1 \neq \pm I_n$  the eigenvalues of the matrix  $S_1^{FM}(e^{j\omega})$  are the roots of the polynomial  $w(s, e^{j\omega})$ . ■

**Lemma 2.** The condition (13) for the Fornasini-Marchesini type model (1) with  $A_2 \neq I_n$  holds if and only if all eigenvalues of the complex matrix  $S_2^{FM}(jy)$  have absolute values less than one for all  $y \geq 0$ , where

$$S_2^{FM}(jy) = (jyI_n - A_2)^{-1} (A_0 + jyA_1). \quad (20)$$

**Proof.** Substituting  $s = jy$  in (4) one obtains

$$w(jy, z) = \det[z(jyI_n - A_2) - A_0 - jyA_1]. \quad (21)$$

If  $A_2 \neq I_n$  then the matrix  $jyI_n - A_2$  is non-singular for all  $y \geq 0$  and

$$[z(jyI_n - A_2) - A_0 - jyA_1] = [jyI_n - A_2][z - S_2^{FM}(jy)], \quad (22)$$

where  $S_2^{FM}(jy)$  is defined by (20).

From (21) and (22) it follows that

$$w(jy, z) = \det(jyI_n - A_2) \det(zI_n - S_2^{FM}(jy)). \quad (23)$$

Hence, if  $A_2 \neq I_n$  then the eigenvalues of the matrix  $S_2^{FM}(jy)$  are the roots of the polynomial  $w(jy, z)$ . ■

**Theorem 3.** The Fornasini-Marchesini type model (1) with  $A_1 \neq \pm I_n$  and  $A_2 \neq I_n$  is asymptotically stable if and only if the conditions of Lemmas 1 and 2 hold, i.e.

$$\operatorname{Re} \lambda_i \{S_1^{FM}(e^{j\omega})\} < 0, \forall \omega \in [0, 2\pi], i = 1, 2, \dots, n, \quad (24)$$

and

$$|\lambda_i \{S_2^{FM}(jy)\}| < 1, \forall y \geq 0, i = 1, 2, \dots, n, \quad (25)$$

where the matrices  $S_1^{FM}(e^{j\omega})$  and  $S_2^{FM}(jy)$  have the forms (17) and (20), respectively.

**Proof.** It follows from Theorem 2 and Lemmas 1 and 2. ■

From (17) for  $\omega = 0$  and  $\omega = \pi$  we have

$$S_1^{FM}(1) = (I_n - A_1)^{-1} (A_2 + A_0), \quad (26a)$$

$$S_1^{FM}(-1) = (-I_n - A_1)^{-1} (-A_2 + A_0). \quad (26b)$$

From the theory of matrices it follows that if  $(-1)^n \det S_1^{FM}(1) \leq 0$  then not all eigenvalues of the matrix (26a) have negative real parts. Similar condition holds for the

matrix (26b). Hence, we have the following remark.

**Remark 1.** Simple necessary condition for asymptotic stability of the Fornasini-Marchesini type model (1) with  $A_1 \neq \pm I_n$  has the form

$$(-1)^n \det(I_n - A_1) \det(A_2 + A_0) > 0 \tag{27a}$$

$$(-1)^n \det(-I_n - A_1) \det(-A_2 + A_0) > 0. \tag{27b}$$

**Example 1.** Consider the Fornasini-Marchesini type model (1) with the matrices

$$A_0 = \begin{bmatrix} -0.4 & 1 & 0 \\ 0 & 0.2 & 0.5 \\ 0 & -0.1 & -0.1 \end{bmatrix}, A_1 = \begin{bmatrix} -0.5 & 0.1 & 0 \\ 0 & 0.1 & -0.4 \\ 0 & 0.2 & -0.2 \end{bmatrix},$$

$$A_2 = \begin{bmatrix} -0.4 & -1.8 & 0 \\ 0.1 & -0.4 & 0 \\ 0 & 0 & -0.7 \end{bmatrix}, \tag{28}$$

It is easy to check that the necessary conditions (27) hold. Computing eigenvalues of the matrices  $S_1^{FM}(e^{j\omega})$ ,  $\omega \in [0, 2\pi]$ , and  $S_2^{FM}(jy)$ ,  $y \in [0, 100]$ , one obtains the plots shown in Figures 1 and 2. It is easy to check that eigenvalues of  $S_2^{FM}(jy)$  remain in the unit circle for all  $y > 100$ .

From Figures 1 and 2 it follows that the conditions (24) and (25) of Theorem 3 are satisfied and the system is asymptotically stable.

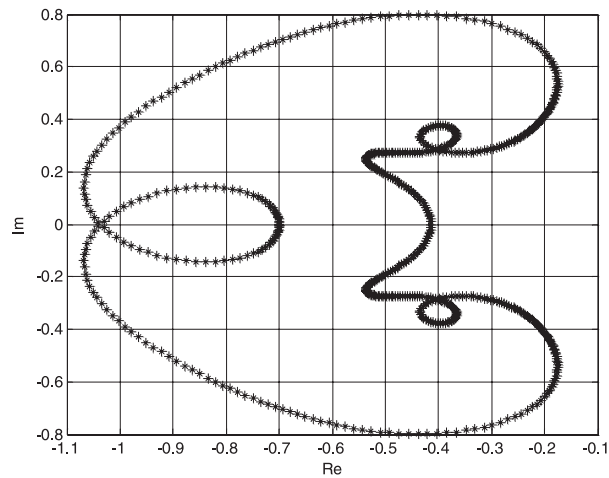


Fig. 1. Eigenvalues of the matrix  $S_1^{FM}(e^{j\omega})$ ,  $\omega \in [0, 2\pi]$ .

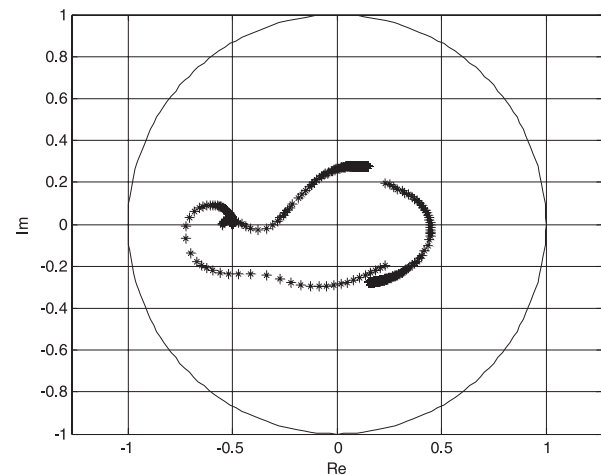


Fig. 2. Eigenvalues of the matrix  $S_2^{FM}(jy)$ ,  $y \in [0, 100]$ .

### 3.2. Asymptotic stability of the Roesser type model

From (8) for  $z = e^{j\omega}$  we have

$$w(s, e^{j\omega}) = \det \begin{bmatrix} sI_{n_1} - A_{11} & -A_{12} \\ -A_{21} & I_{n_2} e^{j\omega} - A_{22} \end{bmatrix} \tag{29}$$

**Lemma 3.** The condition (12) for the Roesser type model (6) with  $A_{22} \neq \pm I_{n_2}$  holds if and only if all eigenvalues of the complex matrix  $S_1^R(e^{j\omega})$  have negative real parts for all  $\omega \in [0, 2\pi]$ , where

$$S_1^R(e^{j\omega}) = A_{11} + A_{12} (I_{n_2} e^{j\omega} - A_{22})^{-1} A_{21}. \tag{30}$$

**Proof.** If  $A_{22} \neq \pm I_{n_2}$  then the matrix  $I_{n_2} e^{j\omega} - A_{22}$  is non-singular for all  $\omega \in [0, 2\pi]$  and from (9a) it follows that

$$w(s, e^{j\omega}) = \det(I_{n_2} e^{j\omega} - A_{22}) \det(sI_{n_1} - S_1^R(e^{j\omega})), \tag{31}$$

where  $S_1^R(e^{j\omega})$  has the form (30). This means that for  $A_{22} \neq \pm I_{n_2}$  the eigenvalues of the matrix  $S_1^R(e^{j\omega})$  are the roots of the polynomial  $w(s, e^{j\omega})$ . ■

**Lemma 4.** The condition (13) for the Roesser type model (6) with  $A_{11} \neq I_{n_1}$  holds if and only if all eigenvalues of the complex matrix  $S_2^R(jy)$  have absolute values less than one for all  $y \geq 0$ , where

$$S_2^R(jy) = A_{22} + A_{21} (jyI_{n_1} - A_{11})^{-1} A_{12}. \tag{32}$$

**Proof.** If  $A_{11} \neq I_{n_1}$  then the matrix  $jyI_{n_1} - A_{11}$  is non-singular for all  $y \geq 0$ . From (9b) for  $s = jy$  we have

$$w(jy, z) = \det(jyI_{n_1} - A_{11}) \det(zI_{n_2} - A_{22} - A_{21}(jyI_{n_1} - A_{11})^{-1} A_{12}). \tag{33}$$

From (32) and (33) it follows that

$$w(jy, z) = \det(jyI_{n_1} - A_{11}) \det(zI_{n_2} - S_2^R(jy)), \tag{34}$$

where  $S_2^R(jy)$  is defined by (32).

If  $A_{11} \neq I_{n_1}$  then the eigenvalues of the matrix  $S_2^R(jy)$  are the roots of the polynomial  $w(jy, z)$ . ■

**Theorem 4.** The Roesser type model (6) with  $A_{22} \neq \pm I_{n_2}$  and  $A_{11} \neq I_{n_1}$  is asymptotically stable if and only if the conditions of Lemmas 3 and 4 hold, i.e.

$$\operatorname{Re} \lambda_i \{S_1^R(e^{j\omega})\} < 0, \forall \omega \in [0, 2\pi], i = 1, 2, \dots, n_1, \tag{35}$$

and

$$|\lambda_i \{S_2^R(jy)\}| < 1, \forall y \geq 0, i = 1, 2, \dots, n_2, \tag{36}$$

where matrices  $S_1^R(e^{j\omega})$  and  $S_2^R(jy)$  have the forms (30) and (32), respectively.

**Proof.** The proof follows from Theorem 2 and Lemmas 3 and 4. ■

From (30) for  $\omega = 0$  and  $\omega = \pi$  it follows that

$$S_1^R(1) = A_{11} + A_{12} (I_{n_2} - A_{22})^{-1} A_{21}, \tag{37a}$$

$$S_1^R(-1) = A_{11} + A_{12} (-I_{n_2} - A_{22})^{-1} A_{21}. \tag{37b}$$

From the above and theory of matrices we have the following remark.

**Remark 2.** Simple necessary condition for asymptotic stability of the Roesser type model (6) with  $A_{22} \neq \pm I_{n_2}$  are as follows:  $(-1)^n \det S_1^R(1) > 0$  and  $(-1)^n \det S_1^R(-1) > 0$ .

**Example 2.** Consider the Roesser type model (6) with the matrices

$$A_{11} = \begin{bmatrix} -1 & 0 \\ 0.1 & -5 \end{bmatrix}, A_{12} = \begin{bmatrix} -0.5 & 0 \\ -1 & 0 \end{bmatrix},$$

$$A_{21} = \begin{bmatrix} -0.5 & -1 \\ 0 & -1 \end{bmatrix}, A_{22} = \begin{bmatrix} -0.5 & 0.8 \\ 0.2 & 0.4 \end{bmatrix}. \quad (38)$$

Eigenvalues of the matrices  $S_1^R(e^{j\omega})$ ,  $\omega \in [0, 2\pi]$  and  $S_2^R(jy)$ ,  $y \in [0, 100]$ , are shown in Figures 3 and 4. It is easy to check that eigenvalues of  $S_2^R(jy)$  remain in the unit circle for all  $y > 100$ .

From Figures 3 and 4 it follows that the conditions (35) and (36) of Theorem 4 are satisfied and the system is asymptotically stable.

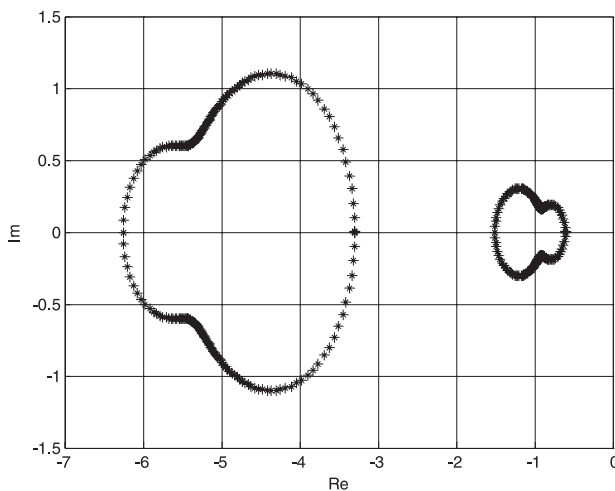


Fig. 3. Eigenvalues of the matrix  $S_1^R(e^{j\omega})$ ,  $\omega \in [0, 2\pi]$ .

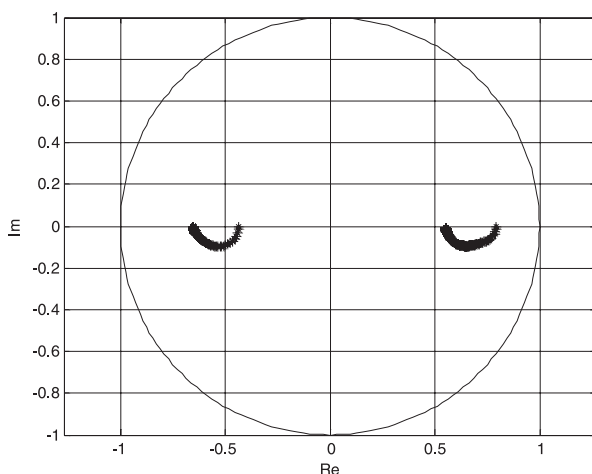


Fig. 4. Eigenvalues of the matrix  $S_2^R(jy)$ ,  $y \in [0, 100]$ .

#### 4. Concluding remarks

Computational methods for investigation of asymptotic stability of the Fornasini-Marchesini type model (1) (Theorem 3) and the Roesser type model (6) (Theorem 4) of continuous-discrete linear systems have been given. These methods require computation of eigenvalue-loci of

complex matrices (17) and (20) for the Fornasini-Marchesini type model and complex matrices (30) and (32) for the Roesser type model.

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