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## Robust stability of a family of matrices

by

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**Abstract:** For a family of matrices with multilinear uncertainty structure, stability of the entire matrix family can be guaranteed by stability of its vertex matrices.

**Keywords:** robust stability, matrix families, multilinear uncertainty structure, algebra theory, vertex results.

Stability of matrix families is an important research subject in robust control, and has received much attention in the past few years, see Horn and Johnson (1985), Bhattacharyya et al. (1995), Barmish (1994), Ackermann (1993), Bartlett et al. (1988), Kaczorek (1993), Ackermann (1991, 1992), Anderson et al. (1995), Polyak and Kogan (1995), Wang (1997, 1998a, 1998b), Wang and Yu (2001a), Duan et al. (2001), Wang and Yu (2001b).

The robust stability problem with linear uncertainty structure has been completely resolved by the celebrated Edge Theorem of Bartlett, Hollot and Huang (1988). Multilinear uncertainty structure is a special class of nonlinear uncertainty structure, see Ackermann (1991, 1992), Anderson et al. (1995), Polyak and Kogan (1995), Wang (1997, 1998a, 1998b), Wang and Yu (2001a), Duan et al. (2001), Wang and Yu (2001b). It is more complicated than the linear uncertainty structure, but has some intrinsic properties in robust stability analysis, see Ackermann (1992), Anderson et al. (1995), Polyak and Kogan (1995), Wang (1998a, 1998b). This is due to the fact that a multilinear function is a linear function of some variable when all other variables are fixed. Ackermann (1992), Anderson et al. (1995), Wang (1998a) have investigated robust stability

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problem with multilinear uncertainty structure, revealed some interesting phenomena, and established some easily testable criteria. In this brief paper, we exploit the multilinear uncertainty structure and by using some matrix properties, we show that, for a family of matrices with multilinear uncertainty structure, D-stability of the entire matrix family can be guaranteed by D-stability of its vertex matrices.

Consider the matrix family

$$\mathcal{F} = \left\{ \sum_{i=1}^{m} f_i(q_1, q_2, \dots, q_l) A_i \mid q_i \in [\underline{q}_i, \overline{q}_i], \ i = 1, 2, \dots, l \right\}$$
 (1)

where  $A_i \in \mathcal{C}^{n \times n}$ , i = 1, 2, ..., m are fixed matrices, and  $f_i(q_1, q_2, ..., q_l)$ , i = 1, 2, ..., m are multiaffine functions of the uncertain parameters  $q_1, q_2, ..., q_l$ .

Denote the vertex set of  $\mathcal{F}$  as

$$\mathcal{F}_V = \left\{ \sum_{i=1}^m f_i(q_1, q_2, \dots, q_l) A_i \mid q_i \in \{\underline{q}_i, \overline{q}_i\}, \ i = 1, 2, \dots, l \right\}$$
 (2)

and suppose that all matrices in  $\mathcal{F}_V$  are normal matrices.

The set of all eigenvalues of a square matrix A is denoted as eigen[A]. For a family A of square matrices, define

$$eigen[A] = \{eigen[A] \mid A \in A\}. \tag{3}$$

The convex hull of a set  $\Lambda$  is denoted as  $conv[\Lambda]$ .

THEOREM 1

$$eigen[\mathcal{F}] \subset conv[eigen[\mathcal{F}_V]].$$
 (4)

Proof. For any  $\lambda \in eigen[\mathcal{F}]$ , we must show that  $\lambda \in conv[eigen[\mathcal{F}_V]]$ . Since  $\lambda \in eigen[\mathcal{F}]$ , there exist  $q_i^0 \in [\underline{q}_i, \overline{q}_i]$ , i = 1, 2, ..., l such that  $\lambda$  is an eigenvalue of  $\sum_{i=1}^m f_i(q_1^0, q_2^0, ..., q_l^0) A_i \doteq A_0$ . Namely, there exists  $x \in \mathcal{C}^n$ ,  $x \neq 0$  such that

$$A_0 x = \lambda x. (5)$$

Without loss of generality, suppose the eigenvector x is normalized, i.e.,  $x^H x = 1$  (the superscript H denotes conjugate transpose). Then

$$\lambda = \lambda x^H x = x^H A_0 x = x^H \Big[ \sum_{i=1}^m f_i(q_1^0, q_2^0, \dots, q_l^0) A_i \Big] x.$$
 (6)

We now prove that

$$\sum_{i=0}^{m} f(s^0, s^0) \wedge f(som_i[\mathcal{F}_{s,i}])$$
 (7)

First, note that  $f_i(q_1, q_2^0, \ldots, q_l^0)$ ,  $i = 1, 2, \ldots, m$  are affine functions of  $q_1$ . So,  $\sum_{i=1}^m f_i(q_1, q_2^0, \ldots, q_l^0) A_i$  is also an affine function of  $q_1$ . Thus, there exists  $\eta \in [0, 1]$  such that

$$\sum_{i=1}^{m} f_i(q_1^0, q_2^0, \dots, q_l^0) A_i$$

$$= \eta \left( \sum_{i=1}^{m} f_i(\underline{q}_1, q_2^0, \dots, q_l^0) A_i \right) + (1 - \eta) \left( \sum_{i=1}^{m} f_i(\overline{q}_1, q_2^0, \dots, q_l^0) A_i \right). \tag{8}$$

Second, when  $q_1^* = \underline{q}_1$  or  $\overline{q}_1$ ,  $f_i(q_1^*, q_2, q_3^0, \dots, q_l^0)$ ,  $i = 1, 2, \dots, m$  are affine functions of  $q_2$ . So,  $\sum_{i=1}^m f_i(q_1^*, q_2, q_3^0, \dots, q_l^0) A_i$  is also an affine function of  $q_2$ . Thus, there exists  $\mu_1 \in [0, 1]$  (for  $\underline{q}_1$ ) and  $\mu_2 \in [0, 1]$  (for  $\overline{q}_1$ ) such that

$$\sum_{i=1}^{m} f_{i}(\underline{q}_{1}, q_{2}^{0}, q_{3}^{0}, \dots, q_{l}^{0}) A_{i} = \mu_{1} \left( \sum_{i=1}^{m} f_{i}(\underline{q}_{1}, \underline{q}_{2}, q_{3}^{0}, \dots, q_{l}^{0}) A_{i} \right) 
+ (1 - \mu_{1}) \left( \sum_{i=1}^{m} f_{i}(\underline{q}_{1}, \overline{q}_{2}, q_{3}^{0}, \dots, q_{l}^{0}) A_{i} \right) 
\sum_{i=1}^{m} f_{i}(\overline{q}_{1}, q_{2}^{0}, q_{3}^{0}, \dots, q_{l}^{0}) A_{i} = \mu_{2} \left( \sum_{i=1}^{m} f_{i}(\overline{q}_{1}, \underline{q}_{2}, q_{3}^{0}, \dots, q_{l}^{0}) A_{i} \right) 
+ (1 - \mu_{2}) \left( \sum_{i=1}^{m} f_{i}(\overline{q}_{1}, \overline{q}_{2}, q_{3}^{0}, \dots, q_{l}^{0}) A_{i} \right).$$
(9)

Henceforth, we have

$$\sum_{i=1}^{m} f_{i}(q_{1}^{0}, q_{2}^{0}, \dots, q_{l}^{0}) A_{i} 
= \eta \left( \sum_{i=1}^{m} f_{i}(\underline{q}_{1}, q_{2}^{0}, \dots, q_{l}^{0}) A_{i} \right) + (1 - \eta) \left( \sum_{i=1}^{m} f_{i}(\overline{q}_{1}, q_{2}^{0}, \dots, q_{l}^{0}) A_{i} \right) 
= \eta \left[ \mu_{1} \left( \sum_{i=1}^{m} f_{i}(\underline{q}_{1}, \underline{q}_{2}, q_{3}^{0}, \dots, q_{l}^{0}) A_{i} \right) \right] 
+ (1 - \mu_{1}) \left( \sum_{i=1}^{m} f_{i}(\underline{q}_{1}, \overline{q}_{2}, q_{3}^{0}, \dots, q_{l}^{0}) A_{i} \right) \right] 
+ (1 - \eta) \left[ \mu_{2} \left( \sum_{i=1}^{m} f_{i}(\overline{q}_{1}, \underline{q}_{2}, q_{3}^{0}, \dots, q_{l}^{0}) A_{i} \right) \right] 
+ (1 - \mu_{2}) \left( \sum_{i=1}^{m} f_{i}(\overline{q}_{1}, \underline{q}_{2}, q_{3}^{0}, \dots, q_{l}^{0}) A_{i} \right) \right]$$
(11)

Continuing this process, we can prove that

$$\sum_{i=1}^{m} f_i(q_1^0, q_2^0, \dots, q_l^0) A_i \in conv[\mathcal{F}_V].$$
(12)

For notational simplicity, let

$$\mathcal{F}_V = \{ F_i \mid i = 1, 2, \dots, p \}, \ p = 2^l.$$
(13)

Then, there exist  $\eta_i \geq 0$ , i = 1, 2, ..., p and  $\sum_{i=1}^{p} \eta_i = 1$  such that

$$\sum_{i=1}^{m} f_i(q_1^0, q_2^0, \dots, q_l^0) A_i = \sum_{i=1}^{p} \eta_i F_i.$$
(14)

Therefore

$$\lambda = x^{H} \left[ \sum_{i=1}^{m} f_{i}(q_{1}^{0}, q_{2}^{0}, \cdots, q_{l}^{0}) A_{i} \right] x$$

$$= x^{H} \left[ \sum_{i=1}^{p} \eta_{i} F_{i} \right] x = \sum_{i=1}^{p} \eta_{i} x^{H} F_{i} x.$$
(15)

Since  $F_i$ , i = 1, 2, ..., p are normal matrices, there exist unitary matrices  $U_i$ , i = 1, 2, ..., p such that

$$U_i^H F_i U_i = diag\{\lambda_{i1}, \lambda_{i2}, \dots, \lambda_{in}\}. \tag{16}$$

Hence

$$x^{H} F_{i} x = x^{H} U_{i} diag\{\lambda_{i1}, \lambda_{i2}, \dots, \lambda_{in}\} U_{i}^{H} x.$$

$$(17)$$

Let

$$y_i = U_i^H x = [y_{i1}, y_{i2}, \dots, y_{in}]^T \in C^n.$$
 (18)

Then

$$x^{H}F_{i}x = y_{i}^{H}diag\{\lambda_{i1}, \lambda_{i2}, \dots, \lambda_{in}\}y_{i} = \sum_{i=1}^{n} \overline{y_{ij}}y_{ij}\lambda_{ij}.$$
 (19)

Since  $\overline{y_{ij}}y_{ij} = |y_{ij}|^2 \ge 0$  and

$$\sum_{i=1}^{n} \overline{y_{ij}} y_{ij} = y_i^H y_i = x^H U_i U_i^H x = x^H x = 1$$
(20)

we have

Furthermore, since  $\eta_i \geq 0$ , i = 1, 2, ..., p and  $\sum_{i=1}^p \eta_i = 1$ , we have

$$\lambda = \sum_{i=1}^{p} \eta_i x^H F_i x \in conv[eigen[\mathcal{F}_V]]. \tag{22}$$

This completes the proof.

Given an open convex region  $\mathcal{D}$  in the complex plane, a matrix is termed  $\mathcal{D}$ -stable, if all of its eigenvalues lie in  $\mathcal{D}$ . A matrix family is termed  $\mathcal{D}$ -stable, if all of its members are  $\mathcal{D}$ -stable. Hurwitz stability and Schur stability are two special cases of  $\mathcal{D}$ -stability when the stability regions are the open left half plane and the open unit disk, respectively. By Theorem 1, we have

COROLLARY 1  $\mathcal{F}$  is  $\mathcal{D}$ -stable if and only if  $\mathcal{F}_V$  is  $\mathcal{D}$ -stable.

Example 1 Consider the matrix family

$$\mathcal{F} = \left\{ \sum_{i=1}^{2} f_i(q_1, q_2) A_i \middle| q_1 \in [1, 2], q_2 \in [2, 4] \right\}$$
 (23)

where  $f_1(q_1, q_2) = q_1q_2 - 4$ ,  $f_2(q_1, q_2) = 2q_1 - q_2$ ; and

$$A_1 = \begin{pmatrix} 0.2 & 0 & 0.1 \\ 0 & 0.1 & 0 \\ -0.1 & 0 & 0.2 \end{pmatrix}$$
 (24)

$$A_2 = \begin{pmatrix} 0.179167 & 0.004167 & -0.083333 \\ 0.004167 & -0.029167 & 0.045833 \\ -0.083333 & 0.045833 & 0.029167 \end{pmatrix}.$$
 (25)

It is easy to see that the four vertex (normal) matrices in  $\mathcal{F}_V$  are

$$V_1 = \sum_{i=1}^{2} f_i(q_1, q_2) A_i|_{q_1=1, q_2=2} = \begin{pmatrix} -0.4 & 0 & -0.2 \\ 0 & -0.2 & 0 \\ 0.2 & 0 & -0.4 \end{pmatrix}$$
 (26)

$$V_2 = \sum_{i=1}^{2} f_i(q_1, q_2) A_i|_{q_1=1, q_2=4}$$

$$= \begin{pmatrix} -0.358333 & -0.008333 & 0.166667 \\ -0.008333 & 0.058333 & -0.091667 \\ 0.166667 & -0.091667 & -0.058333 \end{pmatrix}$$
(27)

$$V_3 = \sum_{i=1}^{2} f_i(q_1, q_2) A_i|_{q_1 = 2, q_2 = 2}$$

$$= \begin{pmatrix} 0.358333 & 0.008333 & -0.166667 \\ 0.008333 & -0.058333 & 0.091667 \end{pmatrix}$$
(28)

$$V_4 = \sum_{i=1}^{2} f_i(q_1, q_2) A_i|_{q_1=2, q_2=4} = \begin{pmatrix} 0.8 & 0 & 0.4 \\ 0 & 0.4 & 0 \\ -0.4 & 0 & 0.8 \end{pmatrix}.$$
 (29)

Moreover, it is easy to see that

$$eigen[V_1] = \{-0.4 + 0.2i, -0.4 - 0.2i, -0.2\}$$
 (30)

$$eigen[V_2] = \{-0.434412, 0.127763, -0.051685\}$$
 (31)

$$eigen[V_3] = \{0.434412, -0.127763, 0.051685\}$$
 (32)

$$eigen[V_4] = \{0.8 + 0.4i, 0.8 - 0.4i, 0.4\}$$
 (33)

Hence, we see that the vertex set  $\mathcal{F}_V = \{V_1, V_2, V_3, V_4\}$  is Schur stable. By Corollary 1, we conclude that the entire family  $\mathcal{F}$  is Schur stable.

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