Rafał Kapica, Janusz Morawiec

# CONTINUOUS SOLUTIONS OF ITERATIVE EQUATIONS OF INFINITE ORDER

**Abstract.** Given a probability space  $(\Omega, \mathcal{A}, P)$  and a complete separable metric space X, we consider continuous and bounded solutions  $\varphi \colon X \to \mathbb{R}$  of the equations  $\varphi(x) = \int_{\Omega} \varphi(f(x,\omega))P(d\omega)$  and  $\varphi(x) = 1 - \int_{\Omega} \varphi(f(x,\omega))P(d\omega)$ , assuming that the given function  $f \colon X \times \Omega \to X$  is controlled by a random variable  $L \colon \Omega \to (0,\infty)$  with  $-\infty < \int_{\Omega} \log L(\omega)P(d\omega) < 0$ . An application to a refinement type equation is also presented.

**Keywords:** random-valued vector functions, sequences of iterates, iterative equations, continuous solutions.

Mathematics Subject Classification: Primary 45A05, 39B12; Secondary 39B52, 60B12.

## 1. INTRODUCTION

Throughout this paper we assume that  $(\Omega, \mathcal{A}, P)$  is a probability space, (X, d) is a complete separable metric space and  $f: X \times \Omega \to X$  is a random-valued function, i.e., it is measurable with respect to the product  $\sigma$ -algebra  $\mathcal{B}(X) \otimes \mathcal{A}$ , where  $\mathcal{B}(X)$  denotes the  $\sigma$ -algebra of all Borel subsets of X. We consider the equation

$$\varphi(x) = \int_{\Omega} \varphi(f(x,\omega)) P(d\omega), \qquad (1.1)$$

which has extensively been studied in various classes of functions (see, e.g., [3,7,13]). For more details concerning equation (1.1) and its particular cases, we refer the reader to survey papers [2, part 4] and [1]. Following [11], we also examine the equation of the form

$$\varphi(x) = 1 - \int_{\Omega} \varphi(f(x,\omega)) P(d\omega).$$
(1.2)

147

Numerous papers concern equation (1.1) with  $f(x,\omega) = L(\omega)x - M(\omega)$ , assuming that  $0 < \int_{\Omega} \log L(\omega)P(d\omega) < \infty$ . In the present paper we are interested in the opposite case

$$-\infty < \int_{\Omega} \log L(\omega) P(d\omega) < 0.$$
(1.3)

More precisely, we adopt the following hypothesis.

(H) There is a measurable function  $L: \Omega \to (0, \infty)$  such that

$$d(f(x,\omega), f(y,\omega)) \le L(\omega)d(x,y) \quad \text{for } x, y \in X, \omega \in \Omega$$
(1.4)

and (1.3) holds.

As an application of the results obtained, we get a corollary on  $L^1$ -solutions of the equation

$$\Phi(x) = \int_{\Omega} |\det A(\omega)F'(x)|\Phi(A(\omega)F(x) - C(\omega))P(d\omega).$$
(1.5)

Equation (1.5) extends both the discrete and the continuous refinement equations which have extensively been studied in connection with their applications (see, e.g., [5, 6, 8, 16]).

The presented results are related to invariance properties of the transfer operator for Markov chains associated with iterated random functions (see, e.g., [9]). In fact, the probability distribution of the limit of the sequences of iterates of a random function satisfies (1.1). Our purpose is to investigate solutions of (1.1), as well as (1.2), in wider classes of functions; e.g., in the class of bounded and continuous functions.

#### 2. MAIN RESULTS

We begin with the following simple lemma.

**Lemma 2.1.** If (1.3) holds, then the sequence  $\left(\prod_{n=1}^{N} L(\omega_n)\right)$  converges a.s. to zero. *Proof.* By the Kolmogorov strong law of large numbers,

$$\lim_{N \to \infty} \left(\prod_{n=1}^{N} L(\omega_n)\right)^{\frac{1}{N}} = \exp\left\{\int_{\Omega} \log L(\omega) P(d\omega)\right\} < 1 \quad \text{a.s.}$$

Consequently,

$$\lim_{N \to \infty} \prod_{n=1}^{N} L(\omega_n) = 0 \quad \text{a.s.}$$

In the proofs of our results, we will iterate the random-valued function f. The iterates of such a function are defined by (see [4,10])

$$f^{1}(x,\omega_{1},\omega_{2},\dots) = f(x,\omega_{1}), \quad f^{n+1}(x,\omega_{1},\omega_{2},\dots) = f(f^{n}(x,\omega_{1},\omega_{2},\dots),\omega_{n+1}).$$

Note that  $f^n$  is a random-valued function on the product probability space  $(\Omega^{\infty}, \mathcal{A}^{\infty}, P^{\infty})$ .

We are now in a position to formulate our results. First note that the unique constant solution of (1.2) equals 1/2 and we will omit this simple fact in all results of this section.

**Proposition 2.2.** Assume (H) and let  $(\sigma_n)$  be a sequence of measure preserving transformations of  $(\Omega^{\infty}, \mathcal{A}^{\infty}, P^{\infty})$  such that

$$\bigwedge_{\omega \in \Omega^{\infty}} \left[ \left( \bigwedge_{m \in \mathbb{N}} \lim_{N \to \infty} \prod_{n=1}^{N} L((\sigma_m(\omega))_n) = 0 \right) \Rightarrow \lim_{N \to \infty} \prod_{n=1}^{N} L((\sigma_N(\omega))_n) = 0 \right].$$
(2.1)

If  $x_0 \in X$  and if  $(f^n(x_0, \cdot) \circ \sigma_n)$  has a subsequence which converges in measure, then every continuous and bounded solution  $\varphi \colon X \to \mathbb{R}$  of (1.1) or (1.2) is constant.

Proof. Put

$$A = \bigcap_{m=1}^{\infty} \sigma_m^{-1} \left( \left\{ \omega \in \Omega^{\infty} \colon \lim_{N \to \infty} \prod_{n=1}^N L(\omega_n) = 0 \right\} \right).$$

From Lemma 2.1 it follows that  $P^{\infty}(A) = 1$ . By (2.1),

$$\lim_{N \to \infty} \prod_{n=1}^{N} L((\sigma_N(\omega))_n) = 0 \quad \text{for } \omega \in A.$$

Using (1.4) and a simple induction, we obtain

$$d(f^N(x,\sigma_N(\omega)), f^N(y,\sigma_N(\omega))) \le d(x,y) \prod_{n=1}^N L((\sigma_N(\omega))_n)$$
(2.2)

for  $x, y \in X, \omega \in \Omega^{\infty}, N \in \mathbb{N}$ .

Assume now that  $(f^{n_k}(x_0, \cdot) \circ \sigma_{n_k})$  converges in measure. Without loss of generality, we can assume that  $(n_k)$  contains even (or odd) numbers only. From (2.2) it follows that for every  $x \in X$  the sequence  $(f^{n_k}(x, \cdot) \circ \sigma_{n_k})$  converges in measure and the limit  $\xi$  is independent of x.

Let  $\varphi \colon X \to \mathbb{R}$  be a continuous and bounded solution of (1.1) or (1.2). In both cases

$$\varphi(x) = \int\limits_{\Omega^\infty} \varphi(f^{2n}(x,\omega)) P^\infty(d\omega),$$

whence

$$\varphi(x) = \int_{\Omega^{\infty}} \varphi(f^{2n}(x, \sigma_{2n}(\omega))) P^{\infty}(d\omega)$$

for  $x \in X, n \in \mathbb{N}$ . Passing to the limit, we get

$$\varphi(x) = \int_{\Omega^{\infty}} \varphi(\xi(\omega)) P^{\infty}(d\omega) \quad \text{for } x \in X,$$

which shows that  $\varphi$  is constant.

The following result gives some condition on f under which the sequence  $(f^n(x, \cdot) \circ \sigma_n)$  converges a.s. for a special sequence  $(\sigma_n)$ .

**Theorem 2.3.** Assume (H) and let  $x_0 \in X$ . If

$$\int_{\Omega} \log \max\{d(f(x_0,\omega), x_0), 1\} P(d\omega) < \infty,$$
(2.3)

then every continuous and bounded solution  $\varphi \colon X \to \mathbb{R}$  of (1.1) or (1.2) is constant.

*Proof.* Following [14], define a sequence  $(\sigma_n)$  by

$$\sigma_n(\omega_1,\omega_2,\dots)=(\omega_n,\dots,\omega_1,\omega_{n+1},\dots).$$

Clearly,  $\sigma_n$  preserves the product measure  $P^{\infty}$  and (2.1) holds. According to Proposition 2.2, it is enough to show the convergence of  $(f^n(x_0, \cdot) \circ \sigma_n)$ . Since  $f^n(\cdot, \omega)$  depends exclusively on the first n coordinates of  $\omega \in \Omega^{\infty}$ , we see that (2.2) implies

$$d(f^{N+1}(x_0, \sigma_{N+1}(\omega)), f^N(x_0, \sigma_N(\omega))) \le \prod_{n=1}^N L(\omega_n) d(f(x_0, \omega_{N+1}), x_0),$$

whence

$$d(f^{N+N'}(x_0,\sigma_{N+N'}(\omega)), f^N(x_0,\sigma_N(\omega))) \le \sum_{n=N}^{N+N'-1} \prod_{k=1}^n L(\omega_k) d(f(x_0,\omega_{n+1}),x_0)$$

for  $\omega \in \Omega^{\infty}$ ,  $N, N' \in \mathbb{N}$ . Consequently, in view of [11, Theorem 2] and (2.3), the series

$$\sum_{N=1}^{\infty} \prod_{n=1}^{N} L(\omega_n) d(f(x_0, \omega_{N+1}), x_0)$$

converges almost surely on  $\Omega^\infty$  and the required convergence follows.

**Theorem 2.4.** If (H) holds, then every bounded and uniformly continuous function  $\varphi \colon X \to \mathbb{R}$  satisfying

$$|\varphi(x) - \varphi(y)| \le \int_{\Omega} |\varphi(f(x,\omega)) - \varphi(f(y,\omega))| P(d\omega) \quad \text{for } x, y \in X$$
 (2.4)

is constant.

*Proof.* Let  $\varphi \colon X \to (-M, M)$  be a uniformly continuous function such that (2.4) holds.

Fix  $x, y \in X, \varepsilon > 0$  and let  $\delta$  be a positive real such that  $|\varphi(u) - \varphi(v)| \leq \frac{\varepsilon}{2}$ , provided  $d(u, v) \leq \delta$  for  $u, v \in X$ .

From (1.4) and Lemma 2.1, we infer  $\lim_{N\to\infty} d(f^N(x,\omega), f^N(y,\omega)) = 0$ . Hence, for a sufficiently large  $N \in \mathbb{N}$  and for suitably chosen set  $A \in \mathcal{A}^{\infty}$ , there holds

$$P^{\infty}(\Omega^{\infty} \setminus A) \leq \frac{\varepsilon}{4M}$$
 and  $d(f^{N}(x,\omega), f^{N}(y,\omega)) \leq \delta$  for  $\omega \in A$ .

Finally, by iterating (2.4), we obtain

$$|\varphi(x) - \varphi(y)| \le \int_{A} |\varphi(f^{N}(x,\omega)) - \varphi(f^{N}(y,\omega))| P^{\infty}(d\omega) + 2MP^{\infty}(\Omega^{\infty} \setminus A) \le \varepsilon,$$

which completes the proof.

As a consequence of Theorem 2.4, we obtain a result concerning the uniqueness in the class of uniformly continuous and bounded functions.

**Corollary 2.5.** If **(H)** holds, then every bounded and uniformly continuous solution  $\varphi: X \to \mathbb{R}$  of (1.1) or (1.2) is constant.

The next two examples show that neither boundedness nor continuity may be omitted in Theorems 2.3, 2.4 and in Corollary 2.5.

Example 2.6. If

$$f(0,\omega) = 0$$
 and  $f(x,\omega) \neq 0$  for  $x \neq 0, \omega \in \Omega$ ,

then (2.3) holds with  $x_0 = 0$  and for every  $\alpha, \beta \in \mathbb{R}$  with  $\alpha \neq \beta$ , the function

$$\varphi = \alpha \chi_{\{0\}} + \beta \chi_{\mathbb{R} \setminus \{0\}} \tag{2.5}$$

is a bounded and discontinuous solution of (1.1). If  $\alpha + \beta = 1$ , then (2.5) is a solution of (1.2), provided

$$f(0,\omega) \neq 0$$
 and  $f(x,\omega) = 0$  for  $x \neq 0, \omega \in \Omega$ .

**Example 2.7.** Let  $\Omega = \{\omega_1, \omega_2\}$ , let  $p_1, p_2$  be positive reals with  $p_1 + p_2 = 1$  and let  $L_1 > 0$  satisfy

$$L_1^{p_1} (1 - p_1 L_1)^{p_2} < p_2^{p_2}$$
 and  $p_1 L_1 < 1$ .

Put

$$L_2 = \frac{1 - p_1 L_1}{p_2}, \quad L(\omega_i) = L_i \quad \text{and} \quad f(x, \omega_i) = L(\omega_i)x$$

for  $x \in \mathbb{R}, i = 1, 2$ . Clearly, conditions (1.4) and (1.3) are fulfilled. Equation (1.1) now takes the form

$$\varphi(x) = p_1 \varphi(L_1 x) + p_2 \varphi(L_2 x).$$

Since  $p_1L_1 + p_2L_2 = 1$ , the identity function is a solution of the equation above. It is easy to verify that the function " $x \mapsto x + 1/2$ " satisfies

$$\varphi(x) = 1 - p_1 \varphi(-L_1 x) - p_2 \varphi(-L_2 x).$$

Denote by  $\mathbb{R}^{n \times m}$  the set of all matrices with *n* rows and *m* columns, and by  $\|\cdot\|$  the maximum norm in  $\mathbb{R}^n$ .

From now on we assume that

$$f(x,\omega) = A(\omega)F(x) - C(\omega), \qquad (2.6)$$

where  $A = [A_{ij}]: \Omega \to \mathbb{R}^{n \times m}, C: \Omega \to \mathbb{R}^n$  are measurable and  $F = [F_i]: \mathbb{R}^n \to \mathbb{R}^m$  is continuous. It is clear that the function given by (2.6) is random-valued (see [12]). Equations (1.1) and (1.2) now take the forms

$$\varphi(x) = \int_{\Omega} \varphi(A(\omega)F(x) - C(\omega))P(d\omega)$$
(2.7)

and

$$\varphi(x) = 1 - \int_{\Omega} \varphi(A(\omega)F(x) - C(\omega))P(d\omega), \qquad (2.8)$$

respectively.

The following corollary will be useful in the next section.

**Corollary 2.8.** Let F(0) = 0,

$$|F_i(x) - F_i(y)| \le ||x - y||$$
 for  $x, y \in X, i = 1, ..., m$ 

and

$$-\infty < \int_{\Omega} \log \max_{k=1,\dots,n} \{ |A_{k1}(\omega)| + \dots + |A_{km}(\omega)| \} P(d\omega) < 0.$$

Then:

(i) Every bounded and uniformly continuous solution  $\varphi \colon \mathbb{R}^n \to \mathbb{R}$  of (2.7) or (2.8) is constant.

(ii) If

$$\int_{\Omega} \log \max\{\|C(\omega)\|, 1\} P(d\omega) < \infty,$$
(2.9)

then every continuous and bounded solution  $\varphi \colon \mathbb{R}^n \to \mathbb{R}$  of (2.7) or (2.8) is constant.

*Proof.* Clearly,  $(\mathbf{H})$  holds with

$$L(\omega) = \max_{k=1,\dots,n} \{ |A_{k1}(\omega)| + \dots + |A_{km}(\omega)| \}$$

and by (2.9) we obtain (2.3) with  $x_0 = 0$ . Hence the assertions follow from Corollary 2.5 and Theorem 2.3, respectively.

## 3. AN APPLICATION TO A REFINEMENT TYPE EQUATION

Let  $A: \Omega \to \mathbb{R}^{n \times n}$  and  $C: \Omega \to \mathbb{R}^n$  be measurable, det  $A(\omega) \neq 0$  for  $\omega \in \Omega$  and let  $F: \mathbb{R}^n \to \mathbb{R}^n$  be a diffeomorphism. Then for an f of form (2.6), there holds

$$l_n \otimes P(f^{-1}(B)) = \int_{\Omega} l_n \Big( F^{-1} \big( A(\omega)^{-1} (B + C(\omega)) \big) \Big) P(d\omega) = 0$$

for  $B \in \mathcal{B}(\mathbb{R}^n)$  of zero Lebesgue measure  $l_n$ . Consequently, if  $\Phi \colon \mathbb{R}^n \to \mathbb{R}$  is Lebesgue measurable, then  $\Phi \circ f$  is measurable with respect to the completion of the product  $\sigma$ -algebra  $\mathcal{L}_n \otimes \mathcal{A}$ . Moreover, if the measure P is complete, then equation (1.5) with unknown  $L^1$ -function  $\Phi \colon \mathbb{R}^n \to \mathbb{R}$  makes sense. (We omit details, which may be found in [15] for n = 1).

Fix measurable functions  $a_1, \ldots, a_n, c_1, \ldots, c_n \colon \Omega \to \mathbb{R}$  and diffeomorphisms  $F_1, \ldots, F_n$  from  $\mathbb{R}$  onto itself such that

$$F_i(0) = 0$$
 and  $|F_i(x) - F_i(y)| \le |x - y|$  for  $x, y \in \mathbb{R}, i = 1, ..., n$ ,

and define functions  $A = [A_{ij}]: \Omega \to \mathbb{R}^{n \times n}, F: \mathbb{R}^n \to \mathbb{R}^n$  and  $C: \Omega \to \mathbb{R}^n$  putting

$$F(x) = (F_1(x_1), \dots, F_n(x_n)), \quad C = (c_1, \dots, c_n)$$

and

$$A_{ij} = 0$$
 if  $i \neq j$  and  $A_{ii} = a_i$  for  $i, j = 1, \dots, n_i$ 

The following corollary concerns a refinement type equation of form (1.5) with a complete measure P and the functions A, F, C defined above.

**Corollary 3.1.** Assume that  $a_1, \ldots, a_n$  are positive (resp. negative),  $F_1, \ldots, F_n$  are increasing (resp. decreasing) and

$$-\infty < \int_{\Omega} \log \max_{k=1,\dots,n} |a_k(\omega)| P(d\omega) < 0.$$

Then the trivial function is the only  $L^1$ -solution  $\Phi \colon \mathbb{R}^n \to \mathbb{R}$  of (1.5). Proof. Suppose that  $\Phi \colon \mathbb{R}^n \to \mathbb{R}$  is an  $L^1$ -solution of (1.5). Define  $\varphi \colon \mathbb{R}^n \to \mathbb{R}$  by

$$\varphi(x) = \int\limits_{U_x} \Phi(t) dt$$

where  $U_x = (-\infty, x_1) \times \cdots \times (-\infty, x_n)$  for  $x \in \mathbb{R}^n$ . Since

 $U_x = f^{-1}(\cdot, \omega)(U_{f(x,\omega)})$ 

and the function " $\mathbb{R}^n \times \Omega \ni (x, \omega) \mapsto |\det A(\omega)F'(x)|\Phi(A(\omega)F(x) - C(\omega))$ " is product measurable, it follows that

$$\begin{split} \varphi(x) &= \int_{\Omega} \left( \int_{U_x} |\det A(\omega)F'(t)| \Phi(A(\omega)F(t) - C(\omega))dt \right) P(d\omega) = \\ &= \int_{\Omega} \left( \int_{U_{f(x,\omega)}} \Phi(t)dt \right) P(d\omega) = \int_{\Omega} \varphi(A(\omega)F(x) - C(\omega))P(d\omega). \end{split}$$

This means that  $\varphi$  is a bounded and uniformly continuous solution of (2.7). Moreover, all the assumptions of Corollary 2.8(i) are satisfied. Consequently,  $\varphi$  is constant and so  $\Phi$  equals zero.

#### Acknowledgments

This research was supported by Silesian University Mathematics Department (Discrete Dynamical Systems and Iteration Theory program – the first author, and Functional Equations program – the second author).

## REFERENCES

- K. Baron, Recent results in the theory of functional equations in a single variable, Sem. LV, http://www.mathematik.uni-karlsruhe.de/~semlv, No. 15 (2003), 16 pp.
- [2] K. Baron, W. Jarczyk, Recent results on functional equations in a single variable, perspectives and open problems, Aequationes Math. 61 (2001), 1–48.
- [3] K. Baron, W. Jarczyk, Random-valued functions and iterative functional equations, Aequationes Math. 67 (2004), 140–153.
- [4] K. Baron, M. Kuczma, Iteration of random-valued functions on the unit interval, Colloq. Math. 37 (1977), 263–269.
- [5] D. Dahmen, C.A. Micchelli, Continuous refinement equations and subdivision, Adv. Comput. Math. 1 (1993), 1–37.
- [6] I. Daubechies, Orthonormal bases of wavelets with compact support, Comm. Pure Appl. Math. 41 (1988), 909–996.
- [7] G. Derfel, A probabilistic method for studying a class of functional-differential equations [in Russian], Ukrain. Mat. Zh. 41 (1989), 1322–1327; English transl.: Ukrainian Math. J. 41 (1989), 1137–1141.
- [8] G. Derfel, N. Dyn, D. Levin, Generalized refinement equations and subdivision processes, J. Aprox. Theory 80 (1995), 272–297.

- [9] P. Diaconis, D. Freedman, Iterated random functions, SIAM Rev. 41 (1999), 45-76.
- [10] Ph. Diamond, A stochastic functional equation, Aequationes Math. 15 (1977), 225–23.
- [11] A.K. Grincevičjus, On the continuity of the distribution of a sum of dependent variables connected with independent walks on lines [in Russian], Teor. Verojatnost. i Primenen 19 (1974), 163–168; English translation: Teor. Probability Appl. 19 (1974), 163–168.
- [12] C.J. Himmelberg, Measurable relations, Fund. Math. 87 (1975), 53-72.
- [13] W. Jarczyk, Convexity properties of nonnegative solutions of a convolution equation, Selected topics in functional equations and iteration theory, Grazer Math. Ber. 316 (1992), 71–92.
- [14] R. Kapica, Sequences of iterates of random-valued vector functions and continuous solutions of a linear functional equation of infinite order, Bull. Polish Acad. Sci. Math. 50 (2002), 447–455.
- [15] R. Kapica, J. Morawiec, On a refinement type equation, J. Appl. Anal. 14 (2008), 251–257.
- [16] L.L. Schumaker, Spline functions: Basic theory, John Wiley, New York, 1981.

Janusz Morawiec morawiec@math.us.edu.pl

Silesian University Institute of Mathematics Bankowa 14, 40-007 Katowice, Poland

Rafał Kapica rkapica@math.us.edu.pl

Silesian University Institute of Mathematics Bankowa 14, 40-007 Katowice, Poland

Received: April 22, 2008. Revised: November 3, 2008. Accepted: March 9, 2009.