

Aurelian Cernea

**ON AN EVOLUTION INCLUSION  
IN NON-SEPARABLE BANACH SPACES**

**Abstract.** We consider a Cauchy problem for a class of nonconvex evolution inclusions in non-separable Banach spaces under Filippov-type assumptions. We prove the existence of solutions.

**Keywords:** Lusin measurable multifunctions, selection, mild solution.

**Mathematics Subject Classification:** 34A60.

1. INTRODUCTION

In this paper we study differential inclusions of the form

$$x'(t) \in A(t)x(t) + \int_0^t K(t,s)F(s,x(s))ds, \quad x(0) = x_0, \quad (1.1)$$

where  $F : [0, T] \times X \rightarrow \mathcal{P}(X)$  is a set-valued map, Lipschitzean with respect to the second variable,  $X$  is a Banach space,  $A(t)$  is the infinitesimal generator of a strongly continuous evolution system of a two parameter family  $\{G(t, \tau), t \geq 0, \tau \geq 0\}$  of bounded linear operators of  $X$  into  $X$ ,  $D = \{(t, s) \in [0, T] \times [0, T]; t \geq s\}$ ,  $K(., .) : D \rightarrow \mathbf{R}$  is continuous and  $x_0 \in X$ .

The existence and qualitative properties of mild solutions of problem (1.1) have been obtained in [1,2-7,13] etc.. Most of the existence results mentioned above are obtained using fixed point techniques. In [9] it is shown that Filippov's ideas ([11]) can suitably be adapted in order to prove the existence of solutions to problem (1.1). All these approaches are have proved successful the Banach space  $X$  separable.

De Blasi and Pianigiani ([10]) established the existence of mild solutions for semi-linear differential inclusions on an arbitrary, not necessarily separable, Banach space  $X$ . Even if Filippov's ideas are still present, the approach in [10] is fundamental different: it consists in the construction of the measurable selections of the multifunction.

This construction does not use classical selection theorems such as Kuratowski and Ryll-Nardzewski's ([12]) or Bressan and Colombo's ([8]).

The aim of this paper is to obtain an existence result for problem (1.1) similar to the one in [10]. We will prove the existence of solutions for problem (1.1) in an arbitrary space  $X$  under Filippov-type assumptions on  $F$ .

The paper is organized as follows: in Section 2 we present the notations, definitions and preliminary results to be used in the sequel, and in Section 3 we prove the main result.

## 2. PRELIMINARIES

Consider  $X$ , an arbitrary real Banach space with norm  $|\cdot|$  and with the corresponding metric  $d(\cdot, \cdot)$ . Let  $\mathcal{P}(X)$  be the space of all bounded nonempty subsets of  $X$  endowed with the Hausdorff pseudometric

$$d_H(A, B) = \max\{d^*(A, B), d^*(B, A)\}, \quad d^*(A, B) = \sup_{a \in A} d(a, B),$$

where  $d(x, A) = \inf_{a \in A} |x - a|$ ,  $A \subset X$ ,  $x \in X$ .

Let  $\mathcal{L}$  be the  $\sigma$ -algebra of the (Lebesgue) measurable subsets of  $R$  and, for  $A \in \mathcal{L}$ , let  $\mu(A)$  be the Lebesgue measure of  $A$ .

Let  $X$  be a Banach space and  $Y$  be a metric space. An open (resp., closed) ball in  $Y$  with center  $y$  and radius  $r$  is denoted by  $B_Y(y, r)$  (resp.,  $\bar{B}_Y(y, r)$ ). In what follows,  $B = B_X(0, 1)$ .

A multifunction  $F : Y \rightarrow \mathcal{P}(X)$  with closed bounded nonempty values is said to be  $d_H$ -continuous at  $y_0 \in Y$  if for every  $\varepsilon > 0$  there exists  $\delta > 0$  such that for any  $y \in B_Y(y_0, \delta)$  there is  $d_H(F(y), F(y_0)) \leq \varepsilon$ .  $F$  is called  $d_H$ -continuous if it is so at each point  $y_0 \in Y$ .

Let  $A \in \mathcal{L}$ , with  $\mu(A) < \infty$ . A multifunction  $F : Y \rightarrow \mathcal{P}(X)$  with closed bounded nonempty values is said to be *Lusin measurable* if for every  $\varepsilon > 0$  there exists a compact set  $K_\varepsilon \subset A$ , with  $\mu(A \setminus K_\varepsilon) < \varepsilon$  such that  $F$  restricted to  $K_\varepsilon$  is  $d_H$ -continuous.

It is clear that if  $F, G : A \rightarrow \mathcal{P}(X)$  and  $f : A \rightarrow X$  are Lusin measurable, then so are  $F$  restricted to  $B$  ( $B \subset A$  measurable),  $F + G$  and  $t \rightarrow d(f(t), F(t))$ . Moreover, the uniform limit of a sequence of Lusin measurable multifunctions is Lusin measurable, too.

Let  $I$  stand for the interval  $[0, T]$ ,  $T > 0$ .

In what follows,  $\{A(t); t \in I\}$  is the infinitesimal generator of a strongly continuous evolution system  $G(t, s)$ ,  $0 \leq s \leq t \leq T$ .

Recall that a family of bounded linear operators  $G(t, s)$  on  $X$ ,  $0 \leq s \leq t \leq T$  depending on two parameters is said to be a strongly continuous evolution system if the following conditions hold:  $G(s, s) = I$ ,  $G(t, r)G(r, s) = G(t, s)$  for  $0 \leq s \leq r \leq t \leq T$  and  $(t, s) \rightarrow G(t, s)$  is strongly continuous for  $0 \leq s \leq t \leq T$ , i.e.  $\lim_{t \rightarrow s, t > s} G(t, s)x = x$  for all  $x \in X$ .

In what follows, we are concerned with the evolution inclusion

$$x'(t) \in A(t)x(t) + \int_0^t K(t, s)F(s, x(s))ds, \quad x(0) = x_0, \quad (2.1)$$

where  $F : I \times X \rightarrow \mathcal{P}(X)$  is a set-valued map,  $X$  is a Banach space,  $A(t)$  is the infinitesimal generator of a strongly continuous evolution system of a two parameter family  $\{G(t, \tau), t \geq 0, \tau \geq 0\}$  of bounded linear operators of  $X$  into  $X$ ,  $D = \{(t, s) \in I \times I; t \geq s\}$ ,  $K(., .) : D \rightarrow \mathbf{R}$  is continuous and  $x_0 \in X$ .

A continuous mapping  $x(.) \in C(I, X)$  is called a *mild solution* of problem (2.1) if there exists a (Bochner) integrable function  $f(.) \in L^1(I, X)$  such that

$$f(t) \in F(t, x(t)) \quad a.e. (I), \quad (2.2)$$

$$x(t) = G(t, 0)x_0 + \int_0^t G(t, \tau) \int_0^\tau K(\tau, s)f(s)dsd\tau, \quad t \in I. \quad (2.3)$$

In this case, we shall call  $(x(.), f(.))$  a *trajectory-selection pair* of (2.1).

We note that condition (2.3) can be rewritten as

$$x(t) = G(t, 0)x_0 + \int_0^t U(t, s)f(s)ds, \quad t \in I, \quad (2.4)$$

where  $U(t, s) = \int_s^t G(t, \tau)K(\tau, s)d\tau$ .

In what follows, we assume the following hypotheses.

- Hypothesis 2.1.** (i)  $\{A(t); t \in I\}$  is the infinitesimal generator of the strongly continuous evolution system  $G(t, s)$ ,  $0 \leq s \leq t \leq T$ .  
 (ii)  $F(., .) : I \times X \rightarrow \mathcal{P}(X)$  has nonempty closed bounded values and, for any  $x \in X$ ,  $F(., x)$  is Lusin measurable on  $I$ .  
 (iii) There exists  $l(.) \in L^1(I, (0, \infty))$  such that for each  $t \in I$ :

$$d_H(F(t, x_1), F(t, x_2)) \leq l(t)|x_1 - x_2|, \quad \forall x_1, x_2 \in X.$$

- (iv) There exists  $q(.) \in L^1(I, (0, \infty))$  such that for each  $t \in I$ :

$$F(t, 0) \subset q(t)B.$$

- (v)  $D = \{(t, s) \in I \times I; t \geq s\}$ ,  $K(., .) : D \rightarrow \mathbf{R}$  is continuous.

Set  $n(t) = \int_0^t l(u)du$ ,  $t \in I$ ,  $M := \sup_{t,s \in I} |G(t, s)|$  and  $M_0 := \sup_{(t,s) \in D} |K(t, s)|$  and note that  $|U(t, s)| \leq MM_0(t - s) \leq MM_0T$ .

The technical results summarized in the following lemma are essential in the proof of our result. For the proof, we refer the reader to [10].

**Lemma 2.2** ([10] i)). Let  $F_i : I \rightarrow \mathcal{P}(X)$ ,  $i=1,2$ , be two Lusin measurable multifunctions and let  $\varepsilon_i > 0$ ,  $i=1,2$  be such that

$$H(t) := (F_1(t) + \varepsilon_1 B) \cap (F_2(t) + \varepsilon_2 B) \neq \emptyset, \quad \forall t \in I.$$

Then the multifunction  $H : I \rightarrow \mathcal{P}(X)$  has a Lusin measurable selection  $h : I \rightarrow X$ .

ii) Assume that Hypothesis 2.1 is satisfied. Then for any continuous  $x(\cdot) : I \rightarrow X$ ,  $u(\cdot) : I \rightarrow X$  measurable and any  $\varepsilon > 0$  there is:

- a) the multifunction  $t \rightarrow F(t, x(t))$  is Lusin measurable on  $I$ ,
- b) the multifunction  $G : I \rightarrow \mathcal{P}(X)$  defined by

$$G(t) := (F(t, x(t)) + \varepsilon B) \cap B_X(u(t), d(u(t), F(t, x(t))) + \varepsilon)$$

has a Lusin measurable selection  $g : I \rightarrow X$ .

### 3. THE MAIN RESULT

We are now ready to prove our main result.

**Theorem 3.1.** We assume that Hypothesis 2.1 is satisfied. Then, for every  $x_0 \in X$ , Cauchy problem (1.1) has a mild solution  $x(\cdot) \in C(I, X)$ .

*Proof.* Let us first note that if  $z(\cdot) : I \rightarrow X$  is continuous, then every Lusin measurable selection  $u : I \rightarrow X$  of the multifunction  $t \rightarrow F(t, z(t)) + B$  is Bochner integrable on  $I$ . More precisely, for any  $t \in I$ , there holds

$$\begin{aligned} |u(t)| &\leq d_H(F(t, z(t)) + B, 0) \leq d_H(F(t, z(t)), F(t, 0)) + \\ &\quad + d_H(F(t, 0), 0) + 1 \leq l(t)|z(t)| + q(t) + 1. \end{aligned}$$

Let  $0 < \varepsilon < 1$ ,  $\varepsilon_n = \frac{\varepsilon}{2^{n+2}}$ .

Consider  $f_0(\cdot) : I \rightarrow X$ , an arbitrary Lusin measurable, Bochner integrable function, and define

$$x_0(t) = G(t, 0)x_0 + \int_0^t U(t, s)f_0(s)ds, \quad t \in I.$$

Since  $x_0(\cdot)$  is continuous, by Lemma 2.2 ii) there exists a Lusin measurable function  $f_1(\cdot) : I \rightarrow X$  which, for  $t \in I$ , satisfies

$$f_1(t) \in (F(t, x_0(t)) + \varepsilon_1 B) \cap B(f_0(t), d(f_0(t), F(t, x_0(t))) + \varepsilon_1).$$

Obviously,  $f_1(\cdot)$  is Bochner integrable on  $I$ . Define  $x_1(\cdot) : I \rightarrow X$  by

$$x_1(t) = G(t, 0)x_0 + \int_0^t U(t, s)f_1(s)ds, \quad t \in I.$$

By induction, we construct a sequence  $x_n : I \rightarrow X$ ,  $n \geq 2$  given by

$$x_n(t) = G(t, 0)x_0 + \int_0^t U(t, s)f_n(s)ds, \quad t \in I, \tag{3.1}$$

where  $f_n(\cdot) : I \rightarrow X$  is a Lusin measurable function which, for  $t \in I$ , satisfies:

$$f_n(t) \in (F(t, x_{n-1}(t)) + \varepsilon_n B) \cap B(f_{n-1}(t), d(f_{n-1}(t), F(t, x_{n-1}(t))) + \varepsilon_n). \tag{3.2}$$

At the same time, as we saw at the beginning of the proof,  $f_n(\cdot)$  is also Bochner integrable.

From (3.2), for  $n \geq 2$  and  $t \in I$ , we obtain

$$|f_n(t) - f_{n-1}(t)| \leq d(f_{n-1}(t), F(t, x_{n-1}(t))) + \varepsilon_n \leq d(f_{n-1}(t), F(t, x_{n-2}(t))) + d_H(F(t, x_{n-2}(t)), F(t, x_{n-1}(t))) + \varepsilon_n \leq \varepsilon_{n-1} + l(t)|x_{n-1}(t) - x_{n-2}(t)| + \varepsilon_n.$$

Since  $\varepsilon_{n-1} + \varepsilon_n < \varepsilon_{n-2}$ , for  $n \geq 2$ , we deduce that

$$|f_n(t) - f_{n-1}(t)| \leq \varepsilon_{n-2} + l(t)|x_{n-1}(t) - x_{n-2}(t)|. \tag{3.3}$$

Denote  $p_0(t) := d(f_0(t), F(t, x_0(t))), t \in I$ . We next prove by recurrence, that for  $n \geq 2$  and  $t \in I$ :

$$|x_n(t) - x_{n-1}(t)| \leq \sum_{k=0}^{n-2} \int_0^t \varepsilon_{n-2-k} \frac{(MM_0T)^{k+1}(n(t) - n(u))^k}{k!} du + \varepsilon_0 \int_0^t \frac{(MM_0T)^n(n(t) - n(u))^{n-1}}{(n-1)!} du + \int_0^t \frac{(MM_0T)^n(n(t) - n(u))^{n-1}}{(n-1)!} p_0(u) du. \tag{3.4}$$

We start with  $n = 2$ . In view of (3.1), (3.2) and (3.3), for  $t \in I$ , there is

$$\begin{aligned} |x_2(t) - x_1(t)| &\leq \int_0^t |U(t, s)| \cdot |f_2(s) - f_1(s)| ds \leq \int_0^t MM_0T[\varepsilon_0 + l(s)|x_1(s) - x_0(s)|] ds \leq \\ &\leq \varepsilon_0 MM_0Tt + \int_0^t [MM_0Tl(s) \int_0^s |U(s, r)| \cdot |f_1(r) - f_0(r)| dr] ds \leq \\ &\leq \varepsilon_0 MM_0Tt + \int_0^t [(MM_0T)^2 l(s) \int_0^s (p_0(u) + \varepsilon_1) du] ds \leq \\ &\leq \varepsilon_0 MM_0Tt + \int_0^t [(MM_0T)^2 (p_0(u) + \varepsilon_1) \int_u^t l(s) ds] du = \\ &= \varepsilon_0 MM_0Tt + \int_0^t (MM_0T)^2 (n(t) - n(s)) [p_0(s) + \varepsilon_0] ds, \end{aligned}$$

i.e., (3.4) is verified for  $n = 2$ .

Using again (3.3) and (3.4), we conclude:

$$\begin{aligned}
|x_{n+1}(t) - x_n(t)| &\leq \int_0^t |U(t, s)| \cdot |f_{n+1}(s) - f_n(s)| ds \leq \\
&\leq \int_0^t MM_0T[\varepsilon_{n-1} + l(s)|x_n(s) - x_{n-1}(s)|] ds \leq \varepsilon_{n-1}MM_0Tt + \\
&+ \int_0^t l(s) \left[ \sum_{k=0}^{n-2} \int_0^s \varepsilon_{n-2-k} \frac{(MM_0T)^{k+2}(n(s) - n(u))^k}{k!} du + \right. \\
&+ \left. \int_0^s \frac{(MM_0T)^{n+1}(n(s) - n(u))^{n-1}}{(n-1)!} (p_0(u) + \varepsilon_0) du \right] ds = \\
&= \varepsilon_{n-1}MM_0Tt + \sum_{k=0}^{n-2} \varepsilon_{n-2-k} \int_0^t \left[ \int_0^s \frac{(MM_0T)^{k+2}(n(s) - n(u))^k}{k!} l(s) du \right] ds + \\
&+ \int_0^t l(s) \left( \int_0^s \frac{(MM_0T)^{n+1}(n(s) - n(u))^{n-1}}{(n-1)!} l(s) [p_0(u) + \varepsilon_0] du \right) ds = \\
&= \varepsilon_{n-1}MM_0Tt + \sum_{k=0}^{n-2} \varepsilon_{n-2-k} \int_0^t \left( \int_u^t \frac{(MM_0T)^{k+2}(n(s) - n(u))^k}{k!} l(s) ds \right) du + \\
&+ \int_0^t \left( \int_u^t \frac{(MM_0T)^{n+1}(n(s) - n(u))^{n-1}}{(n-1)!} l(s) ds \right) [p_0(u) + \varepsilon_0] du = \\
&= \varepsilon_{n-1}MM_0Tt + \sum_{k=0}^{n-2} \varepsilon_{n-2-k} \int_0^t \frac{(MM_0T)^{k+2}(n(s) - n(u))^{k+1}}{(k+1)!} du + \\
&+ \int_0^t \frac{(MM_0T)^{n+1}(n(s) - n(u))^n}{n!} [p_0(u) + \varepsilon_0] du = \\
&= \sum_{k=0}^{n-1} \varepsilon_{n-1-k} \int_0^t \frac{(MM_0T)^{k+1}(n(s) - n(u))^k}{k!} du + \\
&+ \int_0^t \frac{(MM_0T)^{n+1}(n(s) - n(u))^n}{n!} [p_0(u) + \varepsilon_0] du,
\end{aligned}$$

and statement (3.4) it is true for  $n + 1$ .

From (3.4) it follows that for  $n \geq 2$  and  $t \in I$ :

$$|x_n(t) - x_{n-1}(t)| \leq a_n, \tag{3.5}$$

where

$$a_n = \sum_{k=0}^{n-2} \varepsilon_{n-2-k} \frac{(MM_0T)^{k+1}n(T)^k}{k!} + \frac{(MM_0T)^n n(T)^{n-1}}{(n-1)!} \left[ \int_0^1 p_0(u)du + \varepsilon_0 \right],$$

Obviously, the series whose  $n$ -th term is  $a_n$  converges. So, from (3.5) we infer that  $x_n(\cdot)$  converges to a continuous function,  $x(\cdot) : I \rightarrow X$ , uniformly on  $I$ .

On the other hand, in view of (3.3) there is

$$|f_n(t) - f_{n-1}(t)| \leq \varepsilon_{n-2} + l(t)a_{n-1}, \quad t \in I, n \geq 3$$

which implies that the sequence  $f_n(\cdot)$  converges to a Lusin measurable function  $f(\cdot) : I \rightarrow X$ .

Since  $x_n(\cdot)$  is bounded and

$$|f_n(t)| \leq l(t)|x_{n-1}(t)| + q(t) + 1,$$

we infer that  $f(\cdot)$  is also Bochner integrable.

Passing with  $n \rightarrow \infty$  in (3.1) and using the Lebesgue dominated convergence theorem, we obtain

$$x(t) = G(t,0)x_0 + \int_0^t U(t,s)f(s)ds, \quad t \in I.$$

On the other hand, from (3.2) we get

$$f_n(t) \in F(t, x_n(t)) + \varepsilon_n B, \quad t \in I, n \geq 1$$

and letting  $n \rightarrow \infty$  we obtain

$$f(t) \in F(t, x(t)), \quad t \in I,$$

which completes the proof.

**Remark 3.2.** If  $A(t) \equiv A$  and  $A$  is the infinitesimal generator of a strongly continuous semigroup of bounded linear operators  $\{G(t); t \geq 0\}$  from  $X$  to  $X$ , then problem (1.1) reduces to the problem

$$x'(t) \in Ax(t) + \int_0^t K(t,s)F(s, x(s))ds, \quad x(0) = x_0, \tag{3.6}$$

well known ([1,2-7,13] etc.) as an integrodifferential inclusion.

Obviously, a result similar to that of Theorem 3.1 may be obtained for problem (3.6).

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Aurelian Cernea  
acernea@fmi.unibuc.ro

University of Bucharest  
Faculty of Mathematics and Computer Science  
Academiei 14, 010014 Buharest, Romania

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