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## STABILITY OF SOLUTIONS OF INFINITE SYSTEMS OF NONLINEAR DIFFERENTIAL-FUNCTIONAL EQUATIONS OF PARABOLIC TYPE

Abstract. A parabolic initial boundary value problem and an associated elliptic Dirichlet problem for an infinite weakly coupled system of semilinear differential-functional equations are considered. It is shown that the solutions of the parabolic problem is asymptotically stable and the limit of the solution of the parabolic problem as  $t \to \infty$  is the solution of the associated elliptic problem. The result is based on the monotone methods.

**Keywords:** stability of solutions, infinite systems, parabolic equations, elliptic equations, semilinear differential-functional equations, monotone iterative method.

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Let S be an infinite set. Let  $G \subset \mathbb{R}^m$  be an open bounded domain with  $C^{2+\alpha}$  boundary  $(\alpha \in (0,1))$  and  $D := (0,T) \times G$ , where  $T \leq \infty$ . Let  $\overline{D} := [0,T) \times \overline{G}$ .

We consider a boundary initial value problem for an infinite weakly coupled system of semilinear autonomous differential-functional parabolic equations of the form:

$$\frac{\partial u^{i}(t,x)}{\partial t} - \mathcal{L}^{i}[u^{i}](t,x) = f^{i}(x,u(t,x),u(t,\cdot)) \quad \text{for } t > 0, \ x \in G, \ i \in S,$$
(1)

$$u^{i}(t,x) = h^{i}(x)$$
 for  $t > 0, x \in \partial G, i \in S$ , (2)

$$u^{i}(0,x) = h^{i}(x) \quad \text{for} \quad x \in \overline{G}, \ i \in S$$
(3)

and the associated Dirichlet problem for an infinite weakly coupled system of semilinear differential-functional elliptic equations of the form:

$$-\mathcal{L}^{i}[u^{i}](x) = f^{i}(x, u(x), u(\cdot)) \quad \text{for } x \in G, \ i \in S,$$

$$\tag{4}$$

$$u^{i}(x) = h^{i}(x) \quad \text{for } x \in \partial G, \ i \in S,$$
(5)

where

$$\mathcal{L}^{i}[u^{i}](t,x) := \sum_{j,k=1}^{m} a^{i}_{jk}(x) u^{i}_{x_{j}x_{k}}(t,x) + \sum_{j=1}^{m} b^{i}_{j}(x) u^{i}_{x_{j}}(t,x)$$

are strongly uniformly elliptic in G,

$$f^i: \ \bar{G} \times \mathcal{B}(S) \times C_S(\bar{G}) \ni (x, y, z) \mapsto f^i(x, y, z) \in \mathbb{R}$$

for every  $i \in S$ . The notation  $f(x, u(x), u(\cdot))$  means that the dependence of f on the second variable is a function-type dependence and on the third variable is a functional-type dependence. In (1),  $f(x, u(t, x), u(t, \cdot))$  means that the dependence on the third variable is a functional-type dependence with respect to x, but a functiontype dependence with respect to t.

The following results extend and generalize the results of D. H. Sattinger [7], H. Amann [3] and S. Brzychczy [4].

We use the following notation. Let  $\mathcal{B}(S)$  be the Banach space of all bounded functions  $w: S \to \mathbb{R}, w(i) = w^i \ (i \in S)$  with the norm  $||w||_{\mathcal{B}(S)} := \sup_{i \in S} |w^i|$ .  $\mathcal{B}(S)$ is endowed with a partial order  $w \leq \tilde{w}$  defined as  $w^i \leq \tilde{w}^i$  for every  $i \in S$ . Elements of  $\mathcal{B}(S)$  will be denoted by  $(w^i)_{i \in S}$ , too. Let C(G) be the space of all continuous functions  $v: \overline{G} \to \mathbb{R}$  with the norm  $\|v\|_{C(\overline{G})} := \max_{x \in \overline{G}} |v(x)|$ . In this space,  $v \leq \tilde{v}$ means that  $v(x) \leq \tilde{v}(x)$  for every  $x \in \overline{G}$ . By  $C^{l+\alpha}(\overline{G})$ , where  $l = 0, 1, 2, \ldots$  and  $\alpha \in$ (0,1), we denote the space of all functions continuous in G with derivatives of order less or equal l being Hölder continuous with exponent  $\alpha$  in G (see [6, pp. 52–53]) and by  $C^{l+\alpha}(D)$ , where  $l = 0, 1, 2, \ldots$  and  $\alpha \in (0, 1)$ , we denote the space of all functions continuous in  $\overline{D}$  with all derivatives  $\frac{\partial^{r+s}}{\partial t^r \partial x^s}$  being Hölder continuous with exponent  $\alpha$  in D if  $0 \leq 2r + s \leq l$  (see [5, pp. 37-38]). By  $H^{l,p}(G)$  we denote the Sobolev space of all functions whose weak derivatives of order l are in  $L^p(G)$  (see [1, pp. 44-46]). A notation  $g \in C^{l+\alpha}(\partial G)$  (resp.  $g \in H^{l,p}(\partial G)$ ) means that there exists a function  $\mathbf{g} \in$  $C^{l+\alpha}(\bar{G})$  (resp.  $\mathbf{g} \in H^{l,p}(G) \cap C(\bar{G})$ ) such that  $\mathbf{g}(x) = g(x)$  for every  $x \in \partial G$ . In these spaces, norms are defined as  $\|g\|_{C^{l+\alpha}(\partial G)} := \inf_{\mathbf{g} \in C^{l+\alpha}(\bar{G}): \forall x \in \partial G: \mathbf{g}(x) = g(x)} \|\mathbf{g}\|_{C^{l+\alpha}(\bar{G})}$ and  $\|g\|_{H^{2,p}(\partial G)} := \inf_{\mathbf{g} \in H^{2,p}(G) \cap C(\overline{G}): \forall x \in \partial G: \mathbf{g}(x) = g(x)} \|\mathbf{g}\|_{H^{2,p}(G)}$ , respectively.

We denote  $z = (z^i)_{i\in S} \in C_S(\bar{G})$  if  $z: \bar{G} \to \mathcal{B}(S)$  and  $z^i: \bar{G} \to \mathbb{R}$  $(i \in S)$  is a continuous function with  $\sup_{i\in S} \|z^i(x)\|_{C(\bar{G})} < \infty$ . The space  $C_S(\bar{G})$  is a Banach space with the norm  $\|z\|_{C_S(\bar{G})} := \sup_{i\in S} \|z^i(x)\|_{C(\bar{G})}$  and the partial order  $z \leq \tilde{z}$  defined as  $z^i(x) \leq \tilde{z}^i(x)$  for every  $x \in \bar{G}$ ,  $i \in S$ . The space  $C_S^{l+\alpha}(\bar{G})$  is the space of all functions  $(z^i)_{i\in S}$  such that  $z^i \in C^{l+\alpha}(\bar{G})$  for every  $i \in S$  and  $\sup_{i\in S} \|z^i(x)\|_{C^{l+\alpha}(\bar{G})} < \infty$ . In this space, the norm is defined as  $\|z(x)\|_{C_S^{l+\alpha}(\bar{G})} = \sup_{i\in S} \|z^i(x)\|_{C^{l+\alpha}(\bar{G})}$ . In similar way,  $C_S^{l+\alpha}(\bar{D})$  is the space of all functions  $(z^i)_{i\in S}$  such that  $z^i \in C^{l+\alpha}(\bar{D})$  for every  $i \in S$  and  $\sup_{i\in S} \|z^i(x)\|_{C^{l+\alpha}(\bar{D})} < \infty$  with the norm  $\|z(x)\|_{C_S^{l+\alpha}(\bar{D})} = \sup_{i\in S} \|z^i(x)\|_{C^{l+\alpha}(\bar{D})}$ . We will write that  $z = (z^i)_{i\in S} \in L_S^p(G)$  if  $z^i \in L^p(G)$  for every  $i \in S$  and 
$$\begin{split} \sup_{i\in S} \|z^i(x)\|_{L^p(G)} &< \infty. \text{ A notation } z = (z^i)_{i\in S} \in H^{l,p}_S(G) \text{ means that } z^i \in H^{l,p}(G) \\ \text{for every } i \in S \text{ and } \sup_{i\in S} \|z^i(x)\|_{H^{l,p}(G)} &< \infty. \text{ In these spaces, norms are defined as } \|z(x)\|_{L^p_S(G)} = \sup_{i\in S} \|z^i(x)\|_{L^p(G)} \text{ and } \|z(x)\|_{H^{l,p}_S(G)} = \sup_{i\in S} \|z^i(x)\|_{H^{l,p}(G)}, \\ \text{respectively.} \end{split}$$

A function  $\tilde{u}$  is said to be *regular in*  $\overline{D}$  if  $\tilde{u} \in C_S(\overline{D})$  and  $\tilde{u}$  has continuous derivatives  $\frac{\partial \tilde{u}}{\partial t}, \frac{\partial \tilde{u}}{\partial x_j}, \frac{\partial^2 \tilde{u}}{\partial x_j \partial x_k}$  in D for j, k = 1..m. A function  $\tilde{u}$  is said to be a *classical* (*regular*) solution of problem (1), (2), (3) in  $\overline{D}$  if  $\tilde{u}$  is regular in  $\overline{D}$  and fulfils the system of equations (1) in D with conditions (2) and (3). A function  $\tilde{u}$  is said to be a *weak solution* of problem (1), (2), (3) in  $\overline{D}$  if  $\tilde{u}(t, \cdot) \in L_S^2(G), \frac{\partial \tilde{u}^i(t, \cdot)}{\partial t} \in L^2(G),$  $\mathcal{L}^i[\tilde{u}^i](t, \cdot) \in L^2(G)$  and

$$\left\langle \frac{\partial \tilde{u}^{i}(t,x)}{\partial t},\xi(x)\right\rangle - \left\langle \mathcal{L}^{i}[\tilde{u}^{i}](t,x),\xi(x)\right\rangle = \left\langle f^{i}(x,\tilde{u}(t,x),\tilde{u}(t,\cdot)),\xi(x)\right\rangle$$

for every t > 0,  $i \in S$  and for any test function  $\xi \in C_0^{\infty}(\overline{G})$ , where  $\langle \cdot, \cdot \rangle$  is the inner product in  $L^2(G)$ , i.e.,  $\langle f, g \rangle = \int_G fg \, dx$  and  $\tilde{u}$  fulfils conditions (2), (3) in trace sense.

A function  $\hat{u}$  is said to be regular in  $\overline{G}$  if  $\hat{u} \in C_S(\overline{G}) \cap C_S^2(G)$ . A function  $\hat{u}$  is said to be a classical (regular) solution of problem (4), (5) in  $\overline{G}$  if  $\hat{u}$  is regular in  $\overline{G}$ and fulfils the system of equations (4) in G with condition (5). A function  $\hat{u}$  is said to be a weak solution of problem (4), (5) in  $\overline{G}$  if  $\hat{u} \in L_S^2(G)$ ,  $\mathcal{L}^i[\hat{u}^i] \in L^2(G)$  and

$$-\left\langle \mathcal{L}^{i}[\hat{u}^{i}](x),\xi(x)\right\rangle = \left\langle f^{i}(x,\hat{u}(x),\hat{u}(\cdot)),\xi(x)\right\rangle$$

for every  $i \in S$  and for any test function  $\xi \in C_0^{\infty}(\overline{G})$  and  $\hat{u}$  fulfils condition (5) in trace sense.

A solution  $\hat{u}(x)$  of elliptic problem (4), (5) is said to be a stable solution of parabolic problem (1), (2), (3) if for any  $\epsilon > 0$  there exists a  $\delta > 0$  such that  $\|\hat{u}(\cdot) - h(\cdot)\|_{C_S(\bar{G})} < \delta$  implies  $\|\hat{u}(\cdot) - \tilde{u}(t, \cdot)\|_{C_S(\bar{G})} < \epsilon$  for each t > 0, where  $\tilde{u}(t, x)$  is a solution of parabolic problem (1), (2), (3). A solution  $\hat{u}(x)$  is called an *asymptotically stable solution of parabolic problem* (1), (2), (3) if it is a stable solution of parabolic problem (1), (2), (3) end  $\lim_{t\to\infty} \|\hat{u}(\cdot) - \tilde{u}(t, \cdot)\|_{C_S(\bar{G})} = 0.$ 

Functions  $\tilde{u}_0 = \tilde{u}_0(t, x)$  and  $\tilde{v}_0 = \tilde{v}_0(t, x)$  regular in  $\bar{D}$ , satisfying the infinite systems of inequalities

ani i.

$$\begin{cases} \frac{\partial u_{0}^{i}(t,x)}{\partial t} - \mathcal{L}^{i}[\tilde{u}_{0}^{i}](t,x) \leq f^{i}(x,\tilde{u}_{0}(t,x),\tilde{u}_{0}(t,\cdot)) & \text{for } t > 0, \ x \in G, \ i \in S, \\ \tilde{u}_{0}^{i}(t,x) \leq h^{i}(x) & \text{for } t > 0, \ x \in \partial G, \ i \in S, \\ \tilde{u}_{0}^{i}(0,x) \leq h^{i}(x) & \text{for } x \in \bar{G}, \ i \in S \end{cases}$$

$$\begin{cases} \frac{\partial \tilde{v}_{0}^{i}(t,x)}{\partial t} - \mathcal{L}^{i}[\tilde{v}_{0}^{i}](t,x) \geq f^{i}(x,\tilde{v}_{0}(t,x),\tilde{v}_{0}(t,\cdot)) & \text{for } t > 0, \ x \in G, \ i \in S, \\ \tilde{v}_{0}^{i}(t,x) \geq h^{i}(x) & \text{for } t > 0, \ x \in \partial G, \ i \in S, \\ \tilde{v}_{0}^{i}(0,x) \geq h^{i}(x) & \text{for } t > 0, \ x \in \partial G, \ i \in S, \\ \tilde{v}_{0}^{i}(0,x) \geq h^{i}(x) & \text{for } x \in \bar{G}, \ i \in S \end{cases}$$

$$(7)$$

are called a *lower* and an *upper function*, respectively, for parabolic problem (1), (2), (3) in  $\overline{D}$ . In a similar way, functions  $\hat{u}_0 = \hat{u}_0(x)$  and  $\hat{v}_0 = \hat{v}_0(x)$  regular in  $\overline{G}$ , satisfying the infinite systems of inequalities

$$\begin{cases} -\mathcal{L}^{i}[\hat{u}_{0}^{i}](x) \leq f^{i}(x,\hat{u}_{0}(x),\hat{u}_{0}(\cdot)) & \text{for } x \in G, \ i \in S, \\ \hat{u}_{0}^{i}(x) \leq h^{i}(x) & \text{for } x \in \partial G, \ i \in S, \end{cases}$$

$$\tag{8}$$

$$\begin{cases} -\mathcal{L}^{i}[\hat{v}_{0}^{i}](x) \geq f^{i}(x, \hat{v}_{0}(x), \hat{v}_{0}(\cdot)) & \text{for } x \in G, \ i \in S, \\ \hat{v}_{0}^{i}(x) \geq h^{i}(x) & \text{for } x \in \partial G, \ i \in S \end{cases}$$
(9)

are called a *lower* and an *upper function*, respectively, for elliptic problem (4), (5) in  $\overline{G}$ .

We define

$$\mathcal{K} := \{ (x, y, z) \colon x \in \overline{G}, y \in [m_0, M_0], z \in \langle u_0, v_0 \rangle \},\$$

where  $m_0 := (m_0^i)_{i \in S}, \ M_0 := (M_0^i)_{i \in S}, \ m_0^i := \min_{x \in \bar{G}} u_0^i(x), \ M_0^i := \max_{x \in \bar{G}} v_0^i(x)$ and  $\langle u_0, v_0 \rangle := \{\zeta \in L_S^p(G) : \ u_0(x) \le \zeta(x) \le v_0(x) \text{ for } x \in G\}, \text{ if } u_0 \le v_0.$ 

Assumptions. We make the following assumptions:

(a)  $\mathcal{L}$  is uniformly elliptic operator in  $\overline{G}$ , i.e., there exists a constant  $\mu > 0$  such that

$$\sum_{j,k=1}^{m} a_{jk}^{i}(x)\xi_{j}\xi_{k} \ge \mu \sum_{j=1}^{m} \xi_{j}^{2}, \quad i \in S,$$

for all  $\xi = (\xi_1, \dots, \xi_m) \in \mathbb{R}^m$ ,  $x \in G$  and the adjoint operator  $\mathcal{L}^*$  to  $\mathcal{L}$  exists.

(b) The functions  $a_{jk} = (a_{jk}^i)_{i \in S}$ ,  $b_j = (b_j^i)_{i \in S}$  for j, k = 1, ..., m are of class  $C_S^{0+\alpha}(\bar{G})$  and fulfil the Lipschitz condition on  $\partial G$ ; also  $a_{jk}^i(x) = a_{kj}^i(x)$  for every  $i \in S, j, k = 1, ..., m$  and  $x \in \bar{G}$ .

(c) 
$$h \in C_S^{2+\alpha}(\bar{G}).$$

(d) There exists at least one ordered pair  $u_0, v_0 \in C_S^{2+\alpha}(\bar{G})$  of a lower and an upper function for problem (4), (5) in  $\bar{G}$ , i.e.,

$$u_0(x) \le v_0(x)$$
 for  $x \in \overline{G}$ .

- (e)  $f(\cdot, y, z) \in C_S^{0+\alpha}(\overline{G})$  for  $y \in [m_0, M_0], z \in \langle u_0, v_0 \rangle$ .
- (f) For every  $i \in S, x \in \overline{G}, y, \tilde{y} \in \mathcal{B}(S)$  and  $z, \tilde{z} \in C_S(\overline{G})$

$$|f^{i}(x, y, z) - f^{i}(x, \tilde{y}, \tilde{z})| \leq L_{f}(||y - \tilde{y}||_{\mathcal{B}(S)} + ||z - \tilde{z}||_{C_{S}(\bar{G})}),$$

where  $L_f > 0$  is a constant independent of  $i \in S$ .

- (g)  $f^i$  is an increasing function with respect to the second and third variables for every  $i \in S$ .
- (h)  $u_0(x) \le h(x) \le v_0(x)$  for every  $x \in \overline{G}$ .

**Remark.** Let us see that if assumptions (d) and (h) are fulfiled, then the functions  $u_0(x)$  and  $v_0(x)$  are a lower and an upper function for parabolic problem (1), (2), (3) in  $\overline{D}$ .

By applying the monotone iterative method, we may proove the following theorem.

**Theorem 1.** If assumption (a)–(h) hold then problem (1), (2), (3) has the unique solution  $\tilde{u} \in C_S^{2+\alpha}(\bar{D})$  (0 <  $\alpha$  < 1) within the sector  $\langle u_0, v_0 \rangle$ .

We will outline a proof of the theorem (cf. [5, pp. 49–56, 61–62]). We start from the lower function  $u_0$  and the upper function  $v_0$  and we define by induction two monotone sequences  $\{u_n\}$  and  $\{v_n\}$  as regular solutions of problem (1), (2), (3) with  $u_{n-1}$  and  $v_{n-1}$  substituted for u in the right-hand sides of the system.

The essential part of the proof is showing that if the functions  $f^i$  fulfil assumptions (e) and (f) and the substituted function  $\beta \in C_S^{0+\alpha}(\bar{D})$  (where  $\beta = u_{n-1}$  and  $\beta = v_{n-1}$ , respectively), then the function  $f^i(x, \beta(t, x), \beta(t, \cdot)) \in C_S^{0+\alpha}(\bar{D})$ .

The function  $\beta \in C_S^{0+\alpha}(\bar{D})$ , so

$$\|\beta(t,x) - \beta(t',x')\|_{\mathcal{B}(S)} \le H_{\beta}(|t-t'|^{\frac{\alpha}{2}} + |x-x'|^{\alpha}),$$

where  $H_{\beta} > 0$  is some constant. Therefore,

$$\begin{aligned} |f^{i}(x,\beta(t,x),\beta(t,\cdot)) - f^{i}(x',\beta(t',x'),\beta(t',\cdot))| &\leq \\ &\leq |f^{i}(x,\beta(t,x),\beta(t,\cdot)) - f^{i}(x',\beta(t,x),\beta(t,\cdot))| + \\ &+ |f^{i}(x',\beta(t,x),\beta(t,\cdot)) - f^{i}(x',\beta(t',x'),\beta(t',\cdot))| \leq \\ &\leq H_{f}|x - x'|^{\alpha} + L_{f}(||\beta(t,x) - \beta|(t',x')||_{\mathcal{B}(S)} + ||\beta(t,\cdot) - \beta(t',\cdot)||_{C_{S}(\bar{G})}) \leq \\ &\leq H_{f}|x - x'|^{\alpha} + L_{f}H_{\beta}(|t - t'|^{\frac{\alpha}{2}} + |x - x'|^{\alpha}) + L_{f}H_{\beta}|t - t'|^{\frac{\alpha}{2}} \leq \\ &\leq H(|t - t'|^{\frac{\alpha}{2}} + |x - x'|^{\alpha}), \end{aligned}$$

where  $H = H_f + 2L_f H_\beta$ .

We obtain a solution of problem (1), (2), (3) as the limit of the sequences  $\{u_n\}$  and  $\{v_n\}$ .

For elliptic problem (4), (5), the following existence theorem is known (cf. [9]):

**Theorem 2.** If assumptions (a)–(g) hold, then problem (4), (5) has a solution  $\hat{u} \in C_S(\bar{G}) \cap C_S^2(G)$ .

Let assumptions (a)–(h) hold. We study the behavior of solutions of the parabolic problem with conditions independent of t.

**Theorem 3.** Let  $v_0(x)$  be an upper function of elliptic problem (4), (5) in  $\overline{G}$  and

$$\begin{cases} \frac{\partial u^{i}(t,x)}{\partial t} - \mathcal{L}^{i}[u^{i}](t,x) = f^{i}(x,u(t,x),u(t,\cdot)) & \text{for } t > 0, x \in G, i \in S, \\ u^{i}(t,x) = v_{0}^{i}(x) & \text{for } t > 0, x \in \partial G, i \in S, \\ u^{i}(0,x) = v_{0}^{i}(x) & \text{for } x \in G, i \in S. \end{cases}$$
(10)

Then problem (10) has a solution  $\tilde{v}(t,x) \in C_S^{2+\alpha}(\bar{D})$ , which is nonincreasing with respect to t and  $\tilde{v}(t,x) \leq v_0(x)$  in  $\bar{D}$ .

*Proof.* By virtue of Theorem 1, parabolic problem (10) has the unique solution  $\tilde{v}(t,x) \in C_S^{2+\alpha}(\bar{D}).$ 

The function  $v_0(x)$  is an upper function for elliptic problem (4), (5) and is independent of t, so  $v_0(x)$  is a solution of the following problem:

$$\begin{cases} \frac{\partial v_0^i(x)}{\partial t} - \mathcal{L}^i[v_0^i](x) \ge f^i(x, v_0(x), v_0(\cdot)) & \text{for } t > 0, \ x \in G, \ i \in S, \\ v_0^i(x) = v_0^i(x) & \text{for } t > 0, \ x \in \partial G, \ i \in S, \\ v_0^i(x) = v_0^i(x) & \text{for } x \in G, \ i \in S. \end{cases}$$
(11)

Applying the Szarski theorem on weak partial differential-functional inequalities [8] to problems (10) and (11) we obtain:

$$\tilde{v}(t,x) \leq v_0(x)$$
 in  $\bar{D}$ .

Now let

$$\tilde{v}_{\tau}(t,x) := \tilde{v}(t+\tau,x) \text{ for } \tau > 0$$

The function  $\tilde{v}_{\tau}(t, x)$  satisfies the following problem:

$$\begin{cases} \frac{\partial \tilde{v}_{\tau}^{i}(t,x)}{\partial t} - \mathcal{L}^{i}[\tilde{v}_{\tau}^{i}](t,x) = f^{i}(x,\tilde{v}_{\tau}(t,x),\tilde{v}_{\tau}(t,\cdot)) & \text{for } t > 0, \ x \in G, \ i \in S, \\ \tilde{v}_{\tau}^{i}(t,x) = v_{0}^{i}(x) & \text{for } t > 0, \ x \in \partial G, \ i \in S, \\ \tilde{v}_{\tau}^{i}(0,x) = \tilde{v}^{i}(\tau,x) \le v_{0}^{i}(x) & \text{for } x \in G, \ i \in S. \end{cases}$$
(12)

Applying again the Szarski theorem on weak partial differential-functional inequalities [8] to problems (10) and (12) we obtain:

$$\tilde{v}_{\tau}(t,x) \leq \tilde{v}(t,x)$$
 in  $\bar{D}$ .

Let  $t_1, t_2 > 0$  and  $t_1 \leq t_2$ ; for  $\tau = t_2 - t_1$  there is

$$\tilde{v}(t_1, x) \ge \tilde{v}_{\tau}(t_1, x) = \tilde{v}(t_1 + \tau, x) = \tilde{v}(t_2, x)$$
 in  $\bar{D}$ ,

so  $\tilde{v}(t, x)$  is nonincreasing with respect to t.

**Theorem 4.** Let  $u_0(x)$  be a lower function for elliptic problem (4), (5) in  $\overline{G}$  and

$$\begin{cases} \frac{\partial u^i(t,x)}{\partial t} - \mathcal{L}^i[u^i](t,x) = f^i(x,u(t,x),u(t,\cdot)) & \text{for } t > 0, \ x \in G, \ i \in S, \\ u^i(t,x) = u^i_0(x) & \text{for } t > 0, \ x \in \partial G, \ i \in S, \\ u^i(0,x) = u^i_0(x) & \text{for } x \in G, \ i \in S. \end{cases}$$
(13)

Then problem (13) has a solution  $\tilde{u}(t,x) \in C_S^{2+\alpha}(\bar{D})$ , which is nondecreasing with respect to t and  $\tilde{u}(t,x) \geq u_0(x)$  in  $\bar{D}$ .

Now we show the main result of this paper. We prove that the uniform limit at  $t \to \infty$  of a solution of the parabolic problem is a solution of the elliptic problem.

**Theorem 5.** If u(t, x) is a regular uniformly bounded solution of the parabolic boundary initial value problem

$$\begin{cases} \frac{\partial u^i(t,x)}{\partial t} - \mathcal{L}^i[u^i](t,x) = f^i(x,u(t,x),u(t,\cdot)) & \text{for } t > 0, \ x \in G, \ i \in S, \\ u^i(t,x) = v_0^i(x) & \text{for } t > 0, \ x \in \partial G, \ i \in S, \\ u^i(0,x) = v_0^i(x) & \text{for } x \in G, \ i \in S, \end{cases}$$
(14)

and there exists a  $\hat{u}$  such that  $\lim_{t\to\infty} \|u(t,\cdot) - \hat{u}(\cdot)\|_{C_S(\bar{G})} = 0$ , then the function  $\hat{u}$  is a regular solution of elliptic boundary value problem (4), (5).

*Proof.* First we will prove that  $\hat{u}$  is a weak solution of elliptic problem (4), (5).

Parabolic problem (14) has the unique regular solution by Theorem 1. Multiplying the equations in (14) by a test function  $\xi \in C_0^{\infty}(G)$  and integrating, we get

$$\left\langle \frac{\partial u^i(t,x)}{\partial t}, \xi(x) \right\rangle - \left\langle \mathcal{L}^i[u^i](t,x), \xi(x) \right\rangle = \left\langle f^i(x,u(t,x),u(t,\cdot)), \xi(x) \right\rangle$$

for every  $\xi \in C_0^{\infty}(G), t > 0, i \in S$ , and using the adjoint operator  $\mathcal{L}^{\star i}$  to  $\mathcal{L}^i$ 

$$\mathcal{L}^{\star i}[g^i](x) := \sum_{j,k=1}^m \frac{\partial^2}{\partial x_j \partial x_k} (a^i_{jk}(x)g^i(x)) - \sum_{j=1}^m \frac{\partial}{\partial x_j} (b^i_j(x)g^i(x))$$

we obtain

$$\left\langle \frac{\partial u^{i}(t,x)}{\partial t},\xi(x)\right\rangle - \left\langle u^{i}(t,x),\mathcal{L}^{\star i}[\xi](x)\right\rangle = \left\langle f^{i}(x,u(t,x),u(t,\cdot)),\xi(x)\right\rangle$$

for every  $\xi \in C_0^{\infty}(G)$ , t > 0,  $i \in S$ . Next, we choose any T > 0, and integrating with respect to t on the interval [0, T] and multiplying by  $\frac{1}{T}$  we get

$$\frac{1}{T} \int_{0}^{T} \left\langle \frac{\partial u^{i}(t,x)}{\partial t}, \xi(x) \right\rangle dt - \frac{1}{T} \int_{0}^{T} \left\langle u^{i}(t,x), \mathcal{L}^{\star i}[\xi](x) \right\rangle dt = \\ = \frac{1}{T} \int_{0}^{T} \left\langle f^{i}(x,u(t,x),u(t,\cdot)), \xi(x) \right\rangle dt \quad (15)$$

for every  $\xi \in C_0^{\infty}(G), i \in S$ . Now, we pass to the limits in (15) as  $T \to \infty$ . For every  $i \in S$ ,

$$\begin{split} \lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} \langle \frac{\partial u^{i}(t,x)}{\partial t}, \xi(x) \rangle dt &= \\ &= \lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} \frac{\partial}{\partial t} \left\langle u^{i}(t,x), \xi(x) \right\rangle dt = \lim_{T \to \infty} \frac{1}{T} \left\langle u^{i}(T,x), \xi(x) \right\rangle - \left\langle u^{i}(0,x), \xi(x) \right\rangle = \\ &= \lim_{T \to \infty} \left\langle \frac{u^{i}(T,x) - u^{i}(0,x)}{T}, \xi(x) \right\rangle = 0, \end{split}$$

because  $\left|\frac{u^i(T,x)-u^i(0,x)}{T}\xi(x)\right| \leq \frac{1}{T}2C\max_{x\in\bar{G}}|\xi| \to 0$  as  $T\to\infty$  and G is a bounded domain.

Next, for every  $i \in S$ 

$$\lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} \left\langle u^{i}(t,x), \mathcal{L}^{\star i}[\xi](x) \right\rangle dt = \lim_{T \to \infty} \left\langle \frac{\int_{0}^{T} u^{i}(t,x)dt}{T}, \mathcal{L}^{\star i}[\xi](x) \right\rangle = \left\langle \lim_{T \to \infty} \frac{\int_{0}^{T} u^{i}(t,x)dt}{T}, \mathcal{L}^{\star i}[\xi](x) \right\rangle = \left\langle \lim_{T \to \infty} \frac{\frac{\partial}{\partial t} \int_{0}^{T} u^{i}(t,x)dt}{1}, \mathcal{L}^{\star i}[\xi](x) \right\rangle = \left\langle \lim_{T \to \infty} u^{i}(T,x), \mathcal{L}^{\star i}[\xi](x) \right\rangle = \left\langle \hat{u}^{i}(x), \mathcal{L}^{\star i}[\xi](x) \right\rangle.$$

And for every  $i \in S$ 

$$\begin{split} \lim_{T \to \infty} \left| \frac{1}{T} \int_{0}^{T} \langle f^{i}(x, u(t, x), u(t, \cdot)), \xi(x) \rangle dt - \langle f^{i}(x, \hat{u}(x), \hat{u}(\cdot)), \xi(x) \rangle \right| = \\ &= \left| \left\langle \lim_{T \to \infty} \frac{\int_{0}^{T} f^{i}(x, u(t, x), u(t, \cdot)) - f^{i}(x, \hat{u}(x), \hat{u}(\cdot)) dt}{T}, \xi(x) \right\rangle \right| = \\ &= \left| \left\langle \lim_{T \to \infty} \frac{\frac{\partial}{\partial t} \int_{0}^{T} f^{i}(x, u(t, x), u(t, \cdot)) - f^{i}(x, \hat{u}(x), \hat{u}(\cdot)) dt}{1}, \xi(x) \right\rangle \right| = \\ &= \left| \left\langle \lim_{T \to \infty} (f^{i}(x, u(T, x), u(T, \cdot)) - f^{i}(x, \hat{u}(x), \hat{u}(\cdot))), \xi(x) \right\rangle \right| \leq \\ &\leq \left\langle \lim_{T \to \infty} |f^{i}(x, u(T, x), u(T, \cdot)) - f^{i}(x, \hat{u}(x), \hat{u}(\cdot))|, |\xi(x)| \right\rangle \leq \\ &\leq \left\langle \lim_{T \to \infty} (L_{1} \| u(T, x) - \hat{u}(x) \|_{\mathcal{B}(S)} + L_{2} \| u(T, \cdot) - \hat{u}(\cdot) \|_{C_{S}(G)}), |\xi(x)| \right\rangle = \\ &= \langle 0, |\xi(x)| \rangle = 0, \end{split}$$

 $\mathbf{SO}$ 

$$\lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} \left\langle f^{i}(x, u(t, x), u(t, \cdot)), \xi(x) \right\rangle dt = \left\langle f^{i}(x, \hat{u}(x), \hat{u}(\cdot)), \xi(x) \right\rangle$$

Therefore,

$$-\left\langle \hat{u}^{i}(x), \mathcal{L}^{\star i}[\xi](x) \right\rangle = \left\langle f^{i}(x, \hat{u}(x), \hat{u}(\cdot)), \xi(x) \right\rangle$$

and

$$-\left\langle \mathcal{L}^{i}[\hat{u}^{i}](x),\xi(x)\right\rangle = \left\langle f^{i}(x,\hat{u}(x),\hat{u}(\cdot)),\xi(x)\right\rangle$$

,

so  $\hat{u}$  is a weak solution of elliptic problem (4), (5).

Since  $\hat{u}$  is bounded in G,  $\hat{u} \in L^p_S(G)$  for any  $p \in [1, \infty]$ . Let p > m. Thus  $f(x, \hat{u}(x), \hat{u}(\cdot)) \in L^p_S(G)$ .

Now we consider problem

$$\begin{cases} -\mathcal{L}^{i}[w^{i}](x) = f^{i}(x, \hat{u}(x), \hat{u}(\cdot)) & \text{for } x \in G, \ i \in S, \\ w^{i}(x) = h^{i}(x) & \text{for } x \in \partial G, \ i \in S, \end{cases}$$
(16)

System (16) is a system of Dirichlet problems with a single equation each. We apply the Agmon–Douglis–Nirenberg theorem to every problem separately and get  $w = (w^i)_{i=1}^{\infty} \in H_S^{2,p}(G)$ . By the Agmon–Douglis–Nirenberg theorem, each of the problems included in (16) has the unique solution, so  $\hat{u} = w \in H_S^{2,p}(G)$ .

Because the Sobolev space  $H^{2,p}(\bar{G})$  is continuously imbeddable in  $C^{0+\alpha}(\bar{G})$  for p > m and then

 $\|u^i\|_{C^{0+\alpha}(\bar{G})} \leq C \|u^i\|_{H^{2,p}(G)}, \quad i \in S,$  where C is independed of i [1, p. 144], we get

$$\hat{u} \in C_S^{0+\alpha}(\bar{G}).$$

Applying the Schauder theorem to (16) for  $\hat{u} \in C_S^{0+\alpha}(\bar{G})$  separately for every  $i \in S$ , we obtain

$$\hat{u} \in C_S^{2+\alpha}(\bar{G}).$$

Now using Theorem 5 we show the stability of solutions of the parabolic problem with the conditions independent of time.

**Theorem 6.** Let assumptions (a)-(h) hold.

- (i) If u
   is a maximal regular solution of problem (4), (5) such that h fulfils u
   (x) ≤ h(x) for x ∈ G
   , then the function u
   is an asymptotically stable solution from above of parabolic problem (1), (2), (3).
- (ii) If <u>u</u> is a minimal regular solution of problem (4), (5) such that h fulfils h(x) ≤ <u>u</u>(x) for x ∈ Ḡ, then the function <u>u</u> is an asymptotically stable solution from below of parabolic problem (1), (2), (3).
- (iii) If u is the unique (i.e., u
   = u = u) regular solution of problem (4), (5), then the function u is an asymptotically stable solution of parabolic problem (1), (2), (3).

*Proof.* (i) From the theorem on weak partial differential-functional inequalities [8], Theorem 3 and Theorem 5, each solution u(t, x) of problem (1), (2), (3) such that

$$u_0(x) \le h(x) \le v_0(x) \text{ in } G$$

satisfies

$$u_0(x) \leq \tilde{u}(t,x) \leq u(t,x) \leq \tilde{v}(t,x) \leq v_0(x)$$
 in  $\bar{D}$ 

where  $\tilde{u}$ ,  $\tilde{v}$  are solutions of problems (13) and (10), respectively.

The function  $\overline{u}$  is a maximal regular solution of problem (4), (5); thus the solution  $\tilde{v}(t, x)$  satisfies

$$\overline{u}(x) \le \tilde{v}(t,x) \le v_0(x).$$

Hence  $\tilde{v}(t, x)$  is bounded from below and, by Theorem 3, is a nondecreasing function with respect to t, so  $\lim_{t\to\infty} \tilde{v}(t, x)$  exists. From Theorem 1 we know that

$$\|\tilde{u}\|_{C^{2+\alpha}_{S}(\bar{D})} \le B$$

for  $0 < \alpha < 1$ , where B > 0 is a constant indepedent of i, t, x, so  $\{\tilde{u}(t, \cdot)\}_{t \in [0,\infty)}$  are equicontinuous functions.  $\bar{G}$  is a compact set. Thus  $\tilde{v}(t, x)$  converges uniformly as  $t \to \infty$ . By Theorem 5, this limit is a solution of problem (4), (5).  $\overline{u}(x) \leq \lim_{t\to\infty} \tilde{v}(t, x)$  and  $\overline{u}(x)$  is a maximal solution of problem (4), (5). Consequently,

$$\lim_{t \to \infty} \tilde{v}(t, x) = \overline{u}(x).$$

Hence u(t, x) such that  $\overline{u}(x) \leq u(t, x) \leq \tilde{v}(t, x)$  converges uniformly to  $\overline{u}(x)$ , so  $\overline{u}(x)$  is asymptotically stable solution from above of problem (1), (2), (3).

The proofs of (ii) and (iii) run similarly.

**Corollary.** If the function h = h(t, x) depends on t, but is bounded by functions  $\check{h}(x), \hat{h}(x) \in C_S^{2+\alpha}(\bar{G})$  independent of t such that  $u_0(x) \leq \check{h}(x) \leq h(t, x) \leq \hat{h}(x) \leq v_0(x)$  for t > 0,  $x \in \bar{G}$  and an asymptotically stable solution u of

$$\begin{cases} \frac{\partial u^{i}(t,x)}{\partial t} - \mathcal{L}^{i}[u^{i}](t,x) = f^{i}(x,u(t,x),u(t,\cdot)) & \text{for } t > 0, \ x \in G, \ i \in S, \\ u^{i}(t,x) = h^{i}(t,x) & \text{for } t > 0, \ x \in \partial G, \ i \in S, \\ u^{i}(0,x) = h^{i}(0,x) & \text{for } x \in G, \ i \in S \end{cases}$$

exists, then

 $\check{u}(x) \le u(x) \le \hat{u}(x) \quad for \ x \in \bar{G},$ 

where  $\check{u}$  is the minimal solution of

$$\begin{cases} -\mathcal{L}^{i}[u^{i}](t,x) = f^{i}(x,u(t,x),u(t,\cdot)) & \text{for } x \in G, \ i \in S, \\ u^{i}(t,x) = \check{h}^{i}(x) & \text{for } x \in \partial G, \ i \in S, \end{cases}$$

and  $\hat{u}$  is the maximal solution of

$$\begin{cases} -\mathcal{L}^{i}[u^{i}](t,x) = f^{i}(x,u(t,x),u(t,\cdot)) & \text{for } x \in G, \ i \in S, \\ u^{i}(t,x) = \hat{h}^{i}(x) & \text{for } x \in \partial G, \ i \in S. \end{cases}$$

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