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A NECESSARY AND SUFFICIENT CONDITION FOR σ -HURWITZ STABILITY OF THE CONVEX COMBINATION OF THE POLYNOMIALS

Abstract. In the paper are given a necessary and sufficient condition for σ -Hurwitz stability of the convex combination of the polynomials.

Keywords: Convex sets of polynomials, stability of polynomial, Hurwitz stability, σ -stability.

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1. INTRODUCTION

We will consider the set of real polynomials

$$F(x,Q) = \left\{ a_n(q)x^n + a_{n-1}(q)x^{n-1} + \dots + a_1(q)x + a_0(q) \right\},\,$$

where $q = (q_1, q_2, \dots, q_k) \in Q \subset R^k$, Q is a compact set, $a_i(q) \colon Q \to R$ $(i = 0, 1, \dots, n), a_n(q) \neq 0$ for each $q \in Q$.

Let $\sigma \in R$ and $\sigma > 0$.

Definition 1. We shall say that the real polynomial

$$f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0 = a_n (x - x_1)(x - x_2) \dots (x - x_n)$$
 (1)

where $a_n \neq 0$, is Hurwitz stable if $Re(x_i) < 0$ (i = 1, 2, ..., n). The polynomial (1) is called σ -Hurwitz stable if $Re(x_i) < -\sigma$ (i = 1, 2, ..., n).

Definition 2. The set of the polynomials F(x,Q) is called σ -Hurwitz stable if each polynomial $g(x) \in F(x,Q)$ is σ -Hurwitz stable.

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Consider the interval polynomial

$$G(x) = [\underline{a}_n, \overline{a}_n]x^n + [\underline{a}_{n-1}, \overline{a}_{n-1}]x^{n-1} + \dots + [\underline{a}_1, \overline{a}_1]x + [\underline{a}_0, \overline{a}_0],$$

and the set of the polynomials

$$W(x) = \{ f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0 \colon a_i \in \{ \underline{a}_i, \overline{a}_i \} \ (i = 0, 1, \dots, n) \}.$$

The following theorem is true

Theorem 1 (Bhattacharyya, Chapellat, Keel [2]). The interval real polynomial

$$G(x) = [\underline{a}_n, \overline{a}_n]x^n + [\underline{a}_{n-1}, \overline{a}_{n-1}]x^{n-1} + \ldots + [\underline{a}_1, \overline{a}_1]x + [\underline{a}_0, \overline{a}_0],$$

where $0 \notin [\underline{a}_n, \overline{a}_n]$, is σ -Hurwitz stable if and only if the set of the polynomials W(x) is σ -Hurwitz stable.

Let

$$f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0 = a_n (x - x_1)(x - x_2) \cdots (x - x_n),$$

where $a_n \neq 0$.

Denote by H(f) the Hurwitz matrix for the polynomial f(x), i.e.

$$H(f) = \begin{bmatrix} a_{n-1} & a_n & 0 & 0 & 0 & \dots & 0 \\ a_{n-3} & a_{n-2} & a_{n-1} & a_n & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & \dots & 0 & a_0 \end{bmatrix}.$$

It is easy to see that $H(f) \in \mathbb{R}^{n \times n}$.

Consider the real polynomials

$$f_j(x) = a_n^{(j)} x^n + a_{n-1}^{(j)} x^{n-1} + \dots + a_1^{(j)} x + a_0^{(j)}$$
 (2)

for j = 1, 2, ..., m, where $a_n^{(j)} \neq 0$ (j = 1, 2, ..., m), and the convex combinations of these polynomials

$$C(f_1, f_2, \dots, f_m) = \{ \alpha_1 f_1(x) + \alpha_2 f_2(x) + \dots + \alpha_m f_m(x) : \alpha_j \ge 0 \quad (j = 1, 2, \dots, m), \ \alpha_1 + \alpha_2 + \dots + \alpha_m = 1 \}.$$

In this paper we give the necessary and sufficient condition for σ -Hurwitz stability of the convex combination $C(f_1, f_2, \ldots, f_m)$.

We assume that the polynomials (2) are Hurwitz stable. Hence, follows that there exists the inverse matrix $H^{-1}(f_j)$ (j = 1, 2, ..., m).

Let

$$\lambda_k (H^{-1}(f_j)H(f_i)) \quad (k = 1, 2, \dots, n; i, j = 1, 2, \dots, m; j < i)$$

denote the eigenvalues of the matrix $H^{-1}(f_i)H(f_i)$.

The following theorems are true:

Theorem 2 (Białas [3]). If the real polynomials

$$f_1(x) = a_n^{(1)} x^n + a_{n-1}^{(1)} x^{n-1} + \dots + a_1^{(1)} x + a_0^{(1)},$$

$$f_2(x) = a_n^{(2)} x^n + a_{n-1}^{(2)} x^{n-1} + \dots + a_1^{(2)} x + a_0^{(2)},$$

where $a_n^{(1)} \neq 0$, $a_n^{(2)} \neq 0$, are Hurwitz stable, then the convex combination

$$C(f_1, f_2) = \{\alpha_1 f_1(x) + \alpha_2 f_2(x) : \alpha_1 \ge 0, \alpha_2 \ge 0, \alpha_1 + \alpha_2 = 1\}$$

is Hurwitz stable if and only if

$$\lambda_k(H^{-1}(f_1)H(f_2)) \notin (-\infty, 0) \quad (k = 1, 2, \dots, n).$$

Theorem 3 (Bartlett, Hollot, Huang [1]). If the polynomials (2) are Hurwitz stable, then the convex combination

$$C(f_1, f_2, \dots, f_m) = \{\alpha_1 f_1(x) + \alpha_2 f_2(x) + \dots + \alpha_m f_m(x) : \alpha_j \ge 0 \quad (j = 1, 2, \dots, m), \ \alpha_1 + \alpha_2 + \dots + \alpha_m = 1\}$$
(3)

is Hurwitz stable if and only if the convex combinations $C(f_i, f_j)$ are Hurwitz stable for each i, j = 1, 2, ..., m; i < j.

2. MAIN RESULT

Let

$$f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0,$$

where $a_n \neq 0$.

It is easy to note that for $\alpha \in R$ we have

$$q(s) = f(s+\alpha) = b_n s^n + b_{n-1} s^{n-1} + \dots + b_1 s + b_0$$

where

$$b_0 = f(\alpha),$$

 $b_i = \frac{1}{i!} \frac{d^i f(x)}{dx^i} \Big|_{x=\alpha} \quad (i = 1, 2, \dots, n).$

As it is easy to see, we have the following result.

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Lemma 1. The real polynomial

$$f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0,$$

where $a_n \neq 0$, is σ -Hurwitz stable if and only if the polynomial

$$g(s) = f(s - \sigma)$$

is Hurwitz stable.

Now, we will prove

Theorem 4. If the polynomials (2) are σ -Hurwitz stable, then the convex combination

$$C(f_1, f_2, \dots, f_m) = \{\alpha_1 f_1(x) + \alpha_2 f_2(x) + \dots + \alpha_m f_m(x) : \alpha_i \ge 0 \quad (j = 1, 2, \dots, m), \ \alpha_1 + \alpha_2 + \dots + \alpha_m = 1\}$$

is σ -Hurwitz stable if and only if

$$\lambda_k(H^{-1}(g_i)H(g_j)) \notin (-\infty, 0) \quad (k = 1, 2, \dots, n)$$
(4)

for
$$i, j = 1, 2, ..., m$$
; $i < j$, where $g_i(s) = f_i(s - \delta), g_j(s) = f_j(s - \delta)$.

Proof. From Lemma1, it follows that the convex combination $C(f_i, f_j)$ is σ -Hurwitz stable if and only if the convex combination $C(g_i, g_j)$ is Hurwitz stable.

However, from Theorem 2 and 3 follows that the set $C(g_i, g_j)$ is Hurwitz stable if and only if the conditions (4) holds. This completes the proof of Theorem 4.

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