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THE OPERATIONAL CALCULUS MODEL FOR THE n^{TH} -ORDER BACKWARD DIFFERENCE

ABSTRACT

In this paper, there has been constructed such a model of the non-classical Bittner operational calculus, in which the derivative is understood as the backward difference $\nabla_n\{x(k)\} := \{x(k) - x(k - n)\}$. Next, the presented model has been generalized by considering the operation $\nabla_{n,b}\{x(k)\} := \{x(k) - b x(k - n)\}$, where $b \in \mathbb{C} \setminus \{0\}$.

Key words:

operational calculus, derivative, integrals, limit conditions, backward difference.

THE FOUNDATIONS OF THE NON-CLASSICAL BITTNER OPERATIONAL CALCULUS

The *Bittner operational calculus* [2–5] is a system

$$CO(L^0, L^1, S, T_q, s_q, Q), \quad (1)$$

in which L^0 and L^1 are linear spaces (over the same scalar field Γ) such that $L^1 \subset L^0$. The linear operation $S : L^1 \rightarrow L^0$ (denoted as $S \in \mathcal{L}(L^1, L^0)$), called the (abstract) *derivative*, is a surjection. What is more, Q is a set of indices q for the operations $T_q \in \mathcal{L}(L^0, L^1)$ and $s_q \in \mathcal{L}(L^1, L^1)$ such that $ST_q f = f$, $f \in L^0$ and $s_q x = x - T_q S x$, $x \in L^1$. These operations are called *integrals* and *limit conditions*, respectively. The kernel of S , i.e. $\text{Ker } S$ is a set of elements understood as *constants* for the derivative S . The limit conditions s_q , $q \in Q$ are projections of L^1 on the subspace $\text{Ker } S$.

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If we define the objects (1), then we have in mind the *representation* or the *model* of the operational calculus.

An example of the operational calculus (1) is a *discrete* model, in which the derivative is the *backward difference* $\nabla\{x(k)\} := \{x(k) - x(k - 1)\}$.

THE BACKWARD DIFFERENCE MODEL

Let \mathbb{Z} and \mathbb{C} mean the set of integers and the set of complexes, respectively. Moreover, let $C(\mathbb{Z}, \mathbb{C})$ be a linear space of two-sided complex sequences $x = \{x(k)\}_{k \in \mathbb{Z}}$ with usual sequences addition and sequences multiplication by complexes.

In [7], the author of the present paper has proven that the system (1), in which $L^0 = L^1 := C(\mathbb{Z}, \mathbb{C})$ and

$$Sx \equiv \nabla x := \{x(k) - x(k - 1)\}, \tag{2}$$

$$T_{k_0}x := \begin{cases} -\sum_{i=k+1}^{k_0} x(i) & \text{for } k < k_0 \\ 0 & \text{for } k = k_0 \\ \sum_{i=k_0+1}^k x(i) & \text{for } k > k_0 \end{cases}, \quad k \in \mathbb{Z}, \tag{3}$$

$$s_{k_0}x := \{x(k_0)\}, \tag{4}$$

where $x = \{x(k)\} \in L^0 = L^1$ and $x = \{x(k)\} \in L^0 = L^1$ and $k_0 \equiv q \in Q := \mathbb{Z}^1$, is an operational calculus model. In the same article, it has also been shown that to the so-called *backward difference on the basis* $b = \{b(k)\}$

$$S_b x := \{x(k) - b(k)x(k - 1)\},$$

where $b(k) \neq 0$ for each $k \in \mathbb{Z}$ and $\{b(k)\}\{x(k)\} := \{b(k)x(k)\}$ means a usual multiplication of sequences b, x in the algebra L^0 , there correspond the integrals

$$T_{b,k_0}x = \{e(k)\}T_{k_0}\left\{\frac{x(k)}{e(k)}\right\}$$

¹ Given the definition of integrals T_{k_0} , we assume that $\sum_{i=k_0+1}^{k_0} x(i) := 0$.

as well as limit conditions

$$s_{b,k_0}x = \{e(k)\} s_{k_0} \left\{ \frac{x(k)}{e(k)} \right\},$$

where

$$e(k) = \begin{cases} \frac{1}{\prod_{i=k+1}^0 b(i)} & \text{for } k < 0 \\ 1 & \text{for } k = 0 \\ \prod_{i=1}^k b(i) & \text{for } k > 0 \end{cases}, \quad k \in \mathbb{Z}.$$

THE HIGHER-ORDER BACKWARD DIFFERENCE MODEL

A generalization of the operation $\nabla \equiv \nabla_1$ is the below n^{th} -order backward difference

$$\nabla_n x(k) := x(k) - x(k - n), \tag{5}$$

where n is a given natural number, i.e. $n \in \mathbb{N}$.

Taking (5) as a derivative S , we shall determine the integrals T_{k_0} as well as their corresponding limit conditions s_{k_0} . Firstly, let us notice that any constant c for the derivative (5) is an n -periodic sequence, i.e. $c(k + n) = c(k)$ for each $k \in \mathbb{Z}$ (cf. [1]), because this condition is equivalent to $c(k) - c(k - n) = 0, k \in \mathbb{Z}$. What is more, for any sequence $c \in \text{Ker } \nabla_n$ there exist numbers $a_0, a_1, \dots, a_{n-1} \in \mathbb{C}$ such that

$$c = \{a_0 \varepsilon_0^k + a_1 \varepsilon_1^k + \dots + a_{n-1} \varepsilon_{n-1}^k\}, \tag{6}$$

where

$$\varepsilon_0, \varepsilon_1, \dots, \varepsilon_{n-1} \tag{7}$$

are n^{th} roots of unity, i.e.

$$\varepsilon_j = \cos \frac{2j\pi}{n} + i \sin \frac{2j\pi}{n}, \quad j \in \overline{0, n-1}^2,$$

whereas 'i' means the imaginary unit.

² $\overline{0, n-1} := \{0, 1, \dots, n-1\}$.

In what follows, we shall use the below properties of the sequence (7):

$$\begin{aligned} \varepsilon_j^{k \pm n} &= \varepsilon_j^k, \quad j \in \overline{0, n-1}, k \in \mathbb{Z}, \\ \varepsilon_0^m + \varepsilon_1^m + \dots + \varepsilon_{n-1}^m &= 0, \quad m \neq \ell n, \ell, m \in \mathbb{Z}, n \in \mathbb{N} \setminus \{1\}. \end{aligned}$$

We shall prove the following.

Theorem. The system (1), where $x = \{x(k)\} \in L^0 = L^1 := C(\mathbb{Z}, \mathbb{C})$, $k_0 \equiv q \in Q := \mathbb{Z}$ and

$$Sx := \{x(k) - x(k-n)\}, \quad (8)$$

$$T_{k_0}x := \begin{cases} -\frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k+1}^{k_0} \varepsilon_j^{k-i} x(i) & \text{for } k < k_0 \\ 0 & \text{for } k = k_0 \\ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0+1}^k \varepsilon_j^{k-i} x(i) & \text{for } k > k_0 \end{cases}, \quad k \in \mathbb{Z}, \quad (9)$$

$$s_{k_0}x := \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0-n+1}^{k_0} \varepsilon_j^{k-i} x(i) \right\} \quad (10)$$

constitutes the discrete Bittner operational calculus model.

Proof. It is obvious that the operations (8)–(10) are linear. Let $\{y(k)\} := T_{k_0}\{x(k)\}$. Therefore, for $k = k_0$ we get

$$\begin{aligned} S\{y(k)\}|_{k=k_0} &= \{y(k_0) - y(k_0 - n)\} = \left\{ 0 + \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0-n+1}^{k_0} \varepsilon_j^{k_0-n-i} x(i) \right\} \\ &= \left\{ \frac{1}{n} \sum_{i=k_0-n+1}^{k_0-1} [\varepsilon_0^{k_0-i} + \varepsilon_1^{k_0-i} + \dots + \varepsilon_{n-1}^{k_0-i}] x(i) + x(k_0) \right\} = \{x(k)\}|_{k=k_0}. \end{aligned} \quad (11)$$

For $k < k_0$, we have

$$\begin{aligned} S\{y(k)\} &= \{y(k) - y(k-n)\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k-n+1}^{k_0} \varepsilon_j^{k-n-i} x(i) - \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k+1}^{k_0} \varepsilon_j^{k-i} x(i) \right\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k-n+1}^k \varepsilon_j^{k-i} x(i) \right\}. \end{aligned} \quad (12)$$

It is easy to notice that for $n = 1$ we get $S\{y(k)\} = \{x(k)\}$. This also holds for $n > 1$. Namely, by analogy with (11), we obtain

$$S\{y(k)\} = \frac{1}{n} \left\{ \sum_{i=k-n+1}^{k-1} [\varepsilon_0^{k-i} + \varepsilon_1^{k-i} + \dots + \varepsilon_{n-1}^{k-i}] x(i) \right\} + \{x(k)\} = \{x(k)\}. \quad (13)$$

For $k > k_0$ and $k - n > k_0$, we have

$$\begin{aligned} S\{y(k)\} &= \{y(k) - y(k - n)\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0+1}^k \varepsilon_j^{k-i} x(i) - \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0+1}^{k-n} \varepsilon_j^{k-n-i} x(i) \right\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k-n+1}^k \varepsilon_j^{k-i} x(i) \right\}. \end{aligned}$$

Hence, similarly to (12) and (13), we infer that $S\{y(k)\} = \{x(k)\}$.

When, in turn, $k > k_0$ and $k - n = k_0$, then

$$\begin{aligned} S\{y(k)\} &= \{y(k) - y(k - n)\} = \{y(k_0 + n) - y(k_0)\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0+1}^{k_0+n} \varepsilon_j^{k_0+n-i} x(i) - 0 \right\}. \end{aligned}$$

By analogy with (11), we further get

$$S\{y(k)\} = \{x(k_0 + n)\}, \quad \text{that is} \quad S\{y(k)\} = \{x(k)\}.$$

For $k > k_0$ and $k - n < k_0$, we obtain

$$\begin{aligned} S\{y(k)\} &= \{y(k) - y(k - n)\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0+1}^k \varepsilon_j^{k-i} x(i) + \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k-n+1}^{k_0} \varepsilon_j^{k-n-i} x(i) \right\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k-n+1}^k \varepsilon_j^{k-i} x(i) \right\}. \end{aligned}$$

Hence, on the basis of (12) and (13), we deduce that $S\{y(k)\} = \{x(k)\}$.

Finally, we can state that the axiom $ST_{k_0}x = x$ is satisfied.

Let $\{f(k)\} := S\{x(k)\} = \{x(k) - x(k-n)\}$. Then, for $k < k_0$ we have

$$\begin{aligned} T_{k_0}S\{x(k)\} &= T_{k_0}\{f(k)\} = \left\{ -\frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k+1}^{k_0} \varepsilon_j^{k-i} f(i) \right\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \left[\sum_{i=k+1}^{k_0} \varepsilon_j^{k-i} x(i-n) - \sum_{i=k+1}^{k_0} \varepsilon_j^{k-i} x(i) \right] \right\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \left[\sum_{i=k-n+1}^{k_0-n} \varepsilon_j^{k-i} x(i) + \sum_{i=k_0-n+1}^k \varepsilon_j^{k-i} x(i) \right. \right. \\ &\quad \left. \left. - \left(\sum_{i=k_0-n+1}^k \varepsilon_j^{k-i} x(i) + \sum_{i=k+1}^{k_0} \varepsilon_j^{k-i} x(i) \right) \right] \right\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k-n+1}^k \varepsilon_j^{k-i} x(i) \right\} - \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0-n+1}^{k_0} \varepsilon_j^{k-i} x(i) \right\}. \end{aligned}$$

Proceeding by analogy with (12), we eventually get

$$T_{k_0}S\{x(k)\} = \{x(k)\} - \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0-n+1}^{k_0} \varepsilon_j^{k-i} x(i) \right\} = \{x(k)\} - s_{k_0}\{x(k)\}.$$

Similarly, if $k > k_0$, then

$$\begin{aligned} T_{k_0}S\{x(k)\} &= T_{k_0}\{f(k)\} = \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0+1}^k \varepsilon_j^{k-i} f(i) \right\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \left[\sum_{i=k_0+1}^k \varepsilon_j^{k-i} x(i) - \sum_{i=k_0+1}^k \varepsilon_j^{k-i} x(i-n) \right] \right\} \\ &= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \left[\sum_{i=k-n+1}^{k_0} \varepsilon_j^{k-i} x(i) + \sum_{i=k_0+1}^k \varepsilon_j^{k-i} x(i) \right. \right. \\ &\quad \left. \left. - \left(\sum_{i=k_0-n+1}^{k-n} \varepsilon_j^{k-i} x(i) + \sum_{i=k-n+1}^{k_0} \varepsilon_j^{k-i} x(i) \right) \right] \right\} \end{aligned}$$

$$= \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k-n+1}^k \varepsilon_j^{k-i} x(i) \right\} - \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0-n+1}^{k_0} \varepsilon_j^{k-i} x(i) \right\} = \{x(k)\} - s_{k_0}\{x(k)\}.$$

Thus, the axiom $T_{k_0} S x = x - s_{k_0} x$ is also fulfilled.

Let us observe that (2)–(4) constitute the particular case of the above model for $n = 1$.

Example. The limit condition (10) allows to present any n -periodic two-sided sequence $c = \{c(k)\}$ with a recurring cycle $(c_{-n+1}, c_{-n+2}, \dots, c_0)$, i.e.

$$c = \{(c_{-n+1}, c_{-n+2}, \dots, c_0)\} \\ := \{\dots, c_{-n+1}, c_{-n+2}, \dots, c_0, c_{-n+1}, c_{-n+2}, \dots, c_0, \dots\}$$

in the form of (6). For $c \in \text{Ker } \nabla_n$ we have $s_{k_0} c = c$, thus for $k_0 = 0$ we get

$$c = \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=-n+1}^0 \varepsilon_j^{k-i} c_i \right\}. \tag{14}$$

The following table presents general terms of sequences $\{c(k)\}$ for which

$$c_{-i} = n - 1 - i, \quad i \in \overline{0, n-1}.$$

They have been obtained basing on (14) and using the *Mathematica*[®] program for $n = 2, 3, \dots, 10$, respectively.

n	cycle	$c(k)$
2	(0, 1)	$\frac{1}{2}(1 + (-1)^k)$
3	(0, 1, 2)	$1 + \cos \frac{2k\pi}{3} - \frac{1}{\sqrt{3}} \sin \frac{2k\pi}{3}$
4	(0, 1, 2, 3)	$\frac{1}{2}(3 + (-1)^k) + \cos \frac{k\pi}{2} - \sin \frac{k\pi}{2}$
5	(0, 1, 2, 3, 4)	$\frac{2}{5} \left(5 + 4 \cos \frac{2k\pi}{5} + 4 \cos \frac{4k\pi}{5} + 3 \cos \frac{2(k+1)\pi}{5} + 3 \cos \frac{4(k+1)\pi}{5} + 2 \cos \frac{2(k+2)\pi}{5} + 2 \cos \frac{4(k+2)\pi}{5} + \cos \frac{2(k+3)\pi}{5} + \cos \frac{4(k+3)\pi}{5} \right)$
6	(0, 1, 2, 3, 4, 5)	$\frac{1}{2}(5 + (-1)^k) + \cos \frac{k\pi}{3} + \cos \frac{2k\pi}{3} - \sqrt{3} \sin \frac{k\pi}{3} - \frac{1}{\sqrt{3}} \sin \frac{2k\pi}{3}$

n	cycle	$c(k)$
7	(0, 1, 2, 3, 4, 5, 6)	$\frac{1}{7} \left(21 + 12 \cos \frac{2k\pi}{7} + 12 \cos \frac{4k\pi}{7} + 12 \cos \frac{6k\pi}{7} \right.$ $+ 10 \cos \frac{2(k+1)\pi}{7} + 10 \cos \frac{4(k+1)\pi}{7} + 10 \cos \frac{6(k+1)\pi}{7}$ $+ 8 \cos \frac{2(k+2)\pi}{7} + 8 \cos \frac{4(k+2)\pi}{7} + 8 \cos \frac{6(k+2)\pi}{7}$ $+ 6 \cos \frac{2(k+3)\pi}{7} + 6 \cos \frac{4(k+3)\pi}{7} + 6 \cos \frac{6(k+3)\pi}{7}$ $+ 4 \cos \frac{2(k+4)\pi}{7} + 4 \cos \frac{4(k+4)\pi}{7} + 4 \cos \frac{6(k+4)\pi}{7}$ $\left. + 2 \cos \frac{2(k+5)\pi}{7} + 2 \cos \frac{4(k+5)\pi}{7} + 2 \cos \frac{6(k+5)\pi}{7} \right)$
8	(0, 1, 2, 3, 4, 5, 6, 7)	$\frac{1}{2} (7 + (-1)^k) + \cos \frac{k\pi}{4} + \cos \frac{k\pi}{2} + \cos \frac{3k\pi}{4}$ $- (1 + \sqrt{2}) \sin \frac{k\pi}{4} - \sin \frac{k\pi}{2} - (-1 + \sqrt{2}) \sin \frac{3k\pi}{4}$
9	(0, 1, 2, 3, 4, 5, 6, 7, 8)	$\frac{1}{9} \left(36 + 12 \cos \frac{2(4k-1)\pi}{9} + 8 \cos \frac{4(2k-1)\pi}{9} \right.$ $+ 2 \cos \frac{2(k-2)\pi}{9} + 9 \cos \frac{2k\pi}{9} + 9 \cos \frac{4k\pi}{9} + 9 \cos \frac{2k\pi}{3}$ $+ 9 \cos \frac{8k\pi}{9} + 14 \cos \frac{2(k+1)\pi}{9} + 14 \cos \frac{4(k+1)\pi}{9}$ $+ 12 \cos \frac{2(k+2)\pi}{9} - 14 \cos \frac{(8k-1)\pi}{9} - 6 \cos \frac{(2k+1)\pi}{9}$ $+ 6 \cos \frac{2(2k+1)\pi}{9} + 6 \cos \frac{4(2k+1)\pi}{9} - 2 \cos \frac{(4k+1)\pi}{9}$ $+ 2 \cos \frac{2(4k+1)\pi}{9} - 3\sqrt{3} \sin \frac{2k\pi}{9} + 3\sqrt{3} \sin \frac{4k\pi}{9}$ $- 3\sqrt{3} \sin \frac{2k\pi}{3} - 3\sqrt{3} \sin \frac{8k\pi}{9} - 8 \sin \frac{(4k+7)\pi}{18}$ $\left. + 8 \sin \frac{(8k+5)\pi}{18} - 12 \sin \frac{(8k+7)\pi}{18} \right)$
10	(0, 1, 2, 3, 4, 5, 6, 7, 8, 9)	$\frac{1}{2} (9 + (-1)^k) - \cos \frac{(k-2)\pi}{5} + \cos \frac{2(k-1)\pi}{5}$ $+ \cos \frac{k\pi}{5} + \frac{13}{5} \cos \frac{2k\pi}{5} + \cos \frac{3k\pi}{5} + \frac{13}{5} \cos \frac{4k\pi}{5}$ $+ \cos \frac{(k+1)\pi}{5} + \frac{11}{5} \cos \frac{2(k+1)\pi}{5} + \cos \frac{(k+2)\pi}{5}$ $+ \cos \frac{(3k+2)\pi}{5} - \frac{7}{5} \cos \frac{(2k+1)\pi}{5} + \frac{7}{5} \cos \frac{2(2k+1)\pi}{5}$ $- \cos \frac{(3k+1)\pi}{5} - \cos \frac{(4k+1)\pi}{5} - \sin \frac{(2k+3)\pi}{5}$ $- \frac{9}{5} \sin \frac{(4k+3)\pi}{5} - \frac{11}{5} \sin \frac{(8k+3)\pi}{5} + \sin \frac{10(2k+1)\pi}{10}$ $- \sin \frac{(6k+1)\pi}{10} + \frac{9}{5} \sin \frac{(8k+1)\pi}{10}$

It is not difficult to see that

$$c(k) = k + n - 1 \pmod{n}, \quad k \in \mathbb{Z}.$$

Hence,

$$a(k) := c(k - n + 1) = k \pmod{n}, \quad k \in \mathbb{Z}. \tag{15}$$

The sequences $\{a(k)\}$ (for $n \in \overline{2, 10}$ and $k \in \mathbb{N}_0 := \mathbb{N} \cup \{0\}$) are included in *The On-Line Encyclopedia of Integer Sequences* OEIS³.

The below table contains the general terms of $a(k)$, $k \in \mathbb{Z}$ obtained on the basis of (15), again by using *Mathematica*[®].

n	OEIS [®] ID No.	$a(k) = k \pmod{n}$
2	A000035	$\frac{1}{2}(1 - (-1)^k)$
3	A010872	$1 - \cos \frac{2k\pi}{3} - \frac{1}{\sqrt{3}} \sin \frac{2k\pi}{3}$
4	A010873	$\frac{1}{2}(3 - (-1)^k) - \cos \frac{k\pi}{2} - \sin \frac{k\pi}{2}$
5	A010874	$\frac{2}{5} \left(5 + 4 \cos \frac{4(k-4)\pi}{5} + 3 \cos \frac{2(k-3)\pi}{5} + 3 \cos \frac{4(k-3)\pi}{5} \right. \\ \left. + 2 \cos \frac{2(k-2)\pi}{5} + 2 \cos \frac{4(k-2)\pi}{5} + \cos \frac{2(k-1)\pi}{5} \right. \\ \left. + \cos \frac{4(k-1)\pi}{5} + 4 \cos \frac{2(k+1)\pi}{5} \right)$
6	A010875	$\frac{1}{2}(5 - (-1)^k) - \cos \frac{k\pi}{3} - \cos \frac{2k\pi}{3} \\ - \sqrt{3} \sin \frac{k\pi}{3} - \frac{1}{\sqrt{3}} \sin \frac{2k\pi}{3}$
7	A010876	$\frac{1}{7} \left(21 + 12 \cos \frac{4(k-6)\pi}{7} + 12 \cos \frac{6(k-6)\pi}{7} \right. \\ \left. + 12 \cos \frac{2(k+1)\pi}{7} + 10 \cos \frac{2(k-5)\pi}{7} + 10 \cos \frac{4(k-5)\pi}{7} \right. \\ \left. + 10 \cos \frac{6(k-5)\pi}{7} + 8 \cos \frac{2(k-4)\pi}{7} + 8 \cos \frac{4(k-4)\pi}{7} \right. \\ \left. + 8 \cos \frac{6(k-4)\pi}{7} + 6 \cos \frac{2(k-3)\pi}{7} + 6 \cos \frac{4(k-3)\pi}{7} \right. \\ \left. + 6 \cos \frac{6(k-3)\pi}{7} + 4 \cos \frac{2(k-2)\pi}{7} + 4 \cos \frac{4(k-2)\pi}{7} \right. \\ \left. + 4 \cos \frac{6(k-2)\pi}{7} + 2 \cos \frac{2(k-1)\pi}{7} + 2 \cos \frac{4(k-1)\pi}{7} \right. \\ \left. + 2 \cos \frac{6(k-1)\pi}{7} \right)$

³ <https://oeis.org>.

n	OEIS® ID No.	$a(k) = k \pmod n$
8	A010877	$\frac{1}{2}(7 - (-1)^k) - \cos \frac{k\pi}{4} - \cos \frac{k\pi}{2} - \cos \frac{3k\pi}{4}$ $-(1 + \sqrt{2}) \sin \frac{k\pi}{4} - \sin \frac{k\pi}{2} - (-1 + \sqrt{2}) \sin \frac{3k\pi}{4}$
9	A010878	$\frac{1}{9} \left(36 - 3\sqrt{3} \sin \frac{2(k-8)\pi}{3} - 3\sqrt{3} \sin \frac{8(k-8)\pi}{9} \right.$ $- 3\sqrt{3} \sin \frac{2(k+1)\pi}{9} + 3\sqrt{3} \sin \frac{4(k+1)\pi}{9} + 9 \cos \frac{2(k-8)\pi}{9}$ $+ 9 \cos \frac{8(k-8)\pi}{9} + 14 \cos \frac{4(k-7)\pi}{9} + 12 \cos \frac{2(k-6)\pi}{9}$ $+ 2 \cos \frac{2(k-1)\pi}{9} + 2 \cos \frac{4(k-1)\pi}{9} + 9 \cos \frac{2(k+1)\pi}{9}$ $+ 9 \cos \frac{4(k+1)\pi}{9} + 14 \cos \frac{2(k+2)\pi}{9} + 6 \cos \frac{2(2k-15)\pi}{9}$ $- 8 \cos \frac{(2k+1)\pi}{9} + 8 \cos \frac{2(2k+1)\pi}{9} + 8 \cos \frac{4(2k+1)\pi}{9}$ $- 6 \cos \frac{(2k+3)\pi}{9} - 12 \cos \frac{(4k+3)\pi}{9} - 2 \cos \frac{(8k+1)\pi}{9}$ $\left. - 6 \cos \frac{(8k+3)\pi}{9} + 14 \cos \frac{2(4k-1)\pi}{9} - 12 \cos \frac{(8k-3)\pi}{9} \right)$
10	A010879	$\frac{1}{2}(9 - (-1)^k) + \sin \frac{3(2k+1)\pi}{10} + \frac{11}{5} \sin \frac{(8k+1)\pi}{10}$ $- \cos \frac{k\pi}{5} + \cos \frac{2k\pi}{5} - \cos \frac{3k\pi}{5} + \cos \frac{4k\pi}{5} - \cos \frac{(k-11)\pi}{5}$ $+ \cos \frac{3(k-9)\pi}{5} + \frac{13}{5} \cos \frac{4(k-9)\pi}{5} + \frac{11}{5} \cos \frac{2(k-8)\pi}{5}$ $+ \cos \frac{(k-7)\pi}{5} + \frac{7}{5} \cos \frac{2(k-1)\pi}{5} + \cos \frac{(k+1)\pi}{5}$ $+ \frac{13}{5} \cos \frac{2(k+1)\pi}{5} + \cos \frac{(k+2)\pi}{5} - \frac{9}{5} \cos \frac{(2k+1)\pi}{5}$ $+ \frac{9}{5} \cos \frac{2(2k+1)\pi}{5} - \cos \frac{(3k+1)\pi}{5} + \cos \frac{(3k+2)\pi}{5}$ $- \frac{7}{5} \cos \frac{(4k+1)\pi}{5}$

A CERTAIN GENERALIZATION

The operation

$$S_b\{x(k)\} := \{x(k) - b x(k-n)\}, \quad (16)$$

where $\{x(k)\} \in L^0 = L^1 := C(\mathbb{Z}, \mathbb{C})$, $b \in \mathbb{C} \setminus \{0\}$, is a generalization of the derivative (8).

While constructing an operational calculus model corresponding to the derivative (16), we shall use the method of solving the equation $x(k + 1) - b(k)x(k) = f(k)$, described in [6], as well as the following auxiliary theorems:

Lemma 1 (Th. 3 [5]). *An abstract differential equation*

$$Sx = f, \quad f \in L^0, x \in L^1$$

with the limit condition

$$s_q x = x_{0,q}, \quad x_{0,q} \in \text{Ker } S$$

has exactly one solution

$$x = x_{0,q} + T_q f. \tag{17}$$

Lemma 2 (Th. 4 [5]). *With a given derivative $S \in \mathcal{L}(L^1, L^0)$, the projection $s_q \in \mathcal{L}(L^1, \text{Ker } S)$ determines the integral $T_q \in \mathcal{L}(L^0, L^1)$ from the condition*

$$x = T_q f \quad \text{if and only if} \quad Sx = f, s_q x = 0.$$

Moreover, s_q is a limit condition corresponding to the integral T_q

One of the elements of the space $\text{Ker } S_b$ is the sequence

$$e(k) := b^{\frac{k}{n}}, \quad k \in \mathbb{Z}.$$

Then

$$e(k) = b e(k - n), \quad k \in \mathbb{Z}.$$

Let us consider the below difference equation

$$S_b \{x(k)\} = \{f(k)\},$$

i.e.

$$x(k) - b x(k - n) = f(k), \quad k \in \mathbb{Z}. \tag{18}$$

Hence we obtain

$$\frac{x(k)}{e(k)} - \frac{x(k - n)}{e(k - n)} = \frac{f(k)}{e(k)}, \quad k \in \mathbb{Z},$$

so

$$y(k) - y(k - n) = g(k), \quad k \in \mathbb{Z}, \tag{19}$$

where

$$y(k) := \frac{x(k)}{e(k)}, \quad g(k) := \frac{f(k)}{e(k)}, \quad k \in \mathbb{Z}. \quad (20)$$

The equation (19) can be presented as

$$S\{y(k)\} = \{g(k)\}, \quad (21)$$

where $S \equiv \nabla_n$ is the operation (8).

From Lemma 1 it follows that the sequence

$$\{y(k)\} = s_{k_0}\{y(k)\} + T_{k_0}\{g(k)\},$$

where T_{k_0} and s_{k_0} are operations (9) and (10), constitutes the solution of the equation (21).

From (20) we get $x(k) = e(k)y(k)$, $k \in \mathbb{Z}$. Eventually,

$$\{x(k)\} = \{e(k)\}s_{k_0}\left\{\frac{x(k)}{e(k)}\right\} + \{e(k)\}T_{k_0}\left\{\frac{f(k)}{e(k)}\right\} \quad (22)$$

is the solution of (18).

If we take

$$\{\tilde{c}(k)\} := s_{k_0}\left\{\frac{x(k)}{e(k)}\right\},$$

then it follows that the sequence $\{\tilde{c}(k)\} \in \text{Ker } S$ is n -periodic, that is

$$\tilde{c}(k) = \tilde{c}(k - n), \quad k \in \mathbb{Z}.$$

Let

$$s_{b,k_0}\{x(k)\} := \{e(k)\}s_{k_0}\left\{\frac{x(k)}{e(k)}\right\}, \quad k_0 \in Q := \mathbb{Z}, \{x(k)\} \in L^1. \quad (23)$$

Thus, for each $k \in \mathbb{Z}$ we get

$$\begin{aligned} S_b s_{b,k_0} x(k) &= e(k)\tilde{c}(k) - b e(k-n)\tilde{c}(k-n) \\ &= e(k)(\tilde{c}(k) - \tilde{c}(k-n)) = e(k) \cdot 0 = 0, \end{aligned}$$

i.e. $s_{b,k_0} \in \mathcal{L}(L^1, \text{Ker } S_b)$.

What is more, for each $k \in \mathbb{Z}$ holds the following

$$\begin{aligned} s_{b,k_0}^2 x(k) &= s_{b,k_0} [e(k)\widetilde{c}(k)] = e(k)s_{k_0} \left[\frac{e(k)\widetilde{c}(k)}{e(k)} \right] \\ &= e(k)s_{k_0}\widetilde{c}(k) = e(k)\widetilde{c}(k) = s_{b,k_0}x(k), \end{aligned}$$

since $s_{k_0}\{\widetilde{c}(k)\} = \{\widetilde{c}(k)\}$. Finally, s_{b,k_0} is a projection of I^1 onto $\text{Ker } S_b$ for each $k_0 \in \mathbb{Z}$. From Lemma 2 it follows that the projection s_{b,k_0} determines the *integral* T_{b,k_0} from the formula (22).

Namely,

$$T_{b,k_0}\{f(k)\} := \{e(k)\}T_{k_0}\left\{\frac{f(k)}{e(k)}\right\}, \quad k_0 \in \mathbb{Q}, \{f(k)\} \in L^0. \quad (24)$$

Moreover, s_{b,k_0} is the *limit condition* corresponding to the integral (24). Thus, we arrive at the

Corollary. *The system (16), (23), (24) forms the discrete model of the Bittner operational calculus*

$$CO(C(\mathbb{Z}, \mathbb{C}), C(\mathbb{Z}, \mathbb{C}), S_b, T_{b,k_0}, s_{b,k_0}, \mathbb{Z}).$$

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MODEL RACHUNKU OPERATORÓW DLA RÓŻNICY WSTECZNEJ RZĘDU n

STRESZCZENIE

W artykule skonstruowano model nieklasycznego rachunku operatorów Bittnera, w którym pochodna rozumiana jest jako różnica wsteczna $\nabla_n\{x(k)\} := \{x(k) - x(k - n)\}$. Następnie dokonano uogólnienia opracowanego modelu, rozważając operację $\nabla_{n,b}\{x(k)\} := \{x(k) - b x(k - n)\}$, gdzie $b \in \mathbb{C} \setminus \{0\}$.

Słowa kluczowe:

rachunek operatorów, pochodna, pierwotne, warunki graniczne, różnica wsteczna.