

THE REVITALIZATION OF RADAR SYSTEM AS A CASE OF FUNCTIONAL AND INFORMATION SECURITY PROBLEMS

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Abstract: The paper presents selected problems of design of machinery retrofit in Industry 4.0 era. In order to show the diversity of applications of new technological achievements, the case of radar revitalization as a museum exhibit has been shown. Ensuring functional safety and staff work safety has been changed into the safety of visitors to the museum and bystanders. Different approaches to the implementation of the safe stop function in both the internal adjustable frequency drive and the safety terrain zone are presented in the article.

Keywords: industry 4.0, machinery retrofit, radar system, safety

1. INTRODUCTION

Nowadays, the term Industry 4.0 is entrenched in various areas of life. It involves achieving maximum benefits through the use of such acquisitions of Information and Communication Technologies (ICT) (US Access Board, 2015) as Internet or (Industrial) Internet of Things (IIoT) (Misra et al., 2017). The basic problem is the lack of understanding of the subject of security by current designers as well as industrial automation of the Industry 3.0 era. Classical IT designers and programmers who are well-versed in the field of computer network security (Ghorbani et al., 2010), however, lack knowledge in the field of mechanics, electronics, automation and industrial networks. One of the new challenges is to adapt the machines currently used in industry to the requirements of working in an industrial network with new hazards (Colbert and Hutchinson, 2016). Retrofit can refer to both machine and control construction. This is especially so in the case of new control systems created for old machines where special attention should be paid in ensuring an adequate level of functional safety and network security.

When analyzing the issues of functional safety and security in the field of ICT in the implementation of industrial projects, the safety of work, process and product should be taken into account (Cierniak-Emerych et al., 2017).

In the presented case study, work safety has been redefined for the safety of museum visitors. The authors have worked on the concept of revitalization of the airport radar system (without a wave transmitter mounted) as a museum display unit mounted

outside in the public space as shown in Fig. 1. This is an example of partial use of a mechanical device with its adaptation to perform a new function in new environmental conditions.

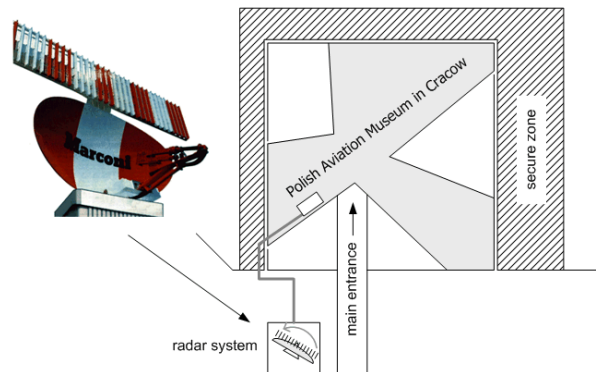


Fig. 1. Location of radar system (photo: The Controller, IFATCA, June 1985, pp.13)

Both the new use of radar and new functionality define different problems and risks. Airport radar devices should ensure reliable operation, and the device is mounted in a safe zone without access by unauthorized persons. The change of functionality as a museum exhibit makes human security the most important and reliability ceases to be crucial. In particular, the new control system must implement many restrictive standards dedicated to the industries where employees can have contact with machines with moving parts e.g. EN/ISO 13850.

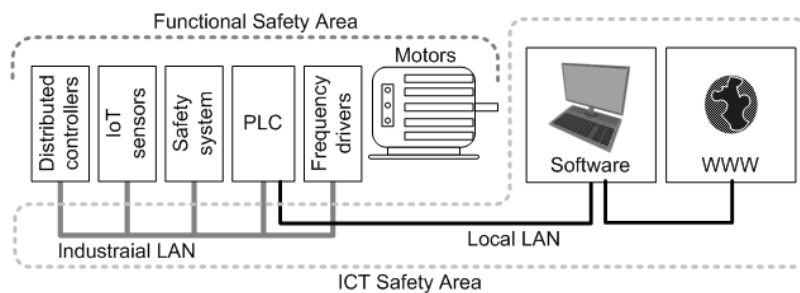


Fig. 2. Basic areas of functional and ICT security

The example presented in Fig. 2 highlights the problem of the separation of activities in the area of Functional Safety and ICT security. Functional Safety refer to the electromechanical part of machines and devices and is well described by standards. ICT Safety for industry does not have identical well-described standards. As shown in Fig. 2, these two topics complement each other, which is why it is necessary to implement Intrusion Detection System / Intrusion Prevention System (IDS/IPS) (Ghorbani et al., 2010; Colbert and Hutchinson, 2016) solutions for the industrial network (industrial LAN).

2. MATERIALS AND METHODS

As part of the mutual cooperation between the Institute of Applied Informatics and the Polish Aviation Museum in Cracow, a concept for renewal and motorization of the airport radar was created. The primary element of the project is the Marconi Radar Systems radar set consisting of a mounting base with 2 electric motors and a master antenna – Airport Surveillance Radar (ASR) and Secondary Surveillance Radar

antenna (SSR) (Lynn, 1987). The ASR antenna has a parabolic structure and dimensions less than 6 m wide, while the SSR antenna is placed above the primary radar survey and has a width of about 9 m.

As well as the basic problems (as described in more detail in Table 1), by using the EN ISO 12100 standard, the following issues have been defined:

- bad technical condition of the drive parts and lack of spare parts,
- lack of any control system,
- the need to mount the radar outside the protected area of the museum in close proximity to the city park with 24/7 access by outsiders.

Table 1
Examples of identified hazards and corrective actions

Potential hazard	Action
Open area - exposure of bystanders to health loss in the antenna rotation field	Construction of a fence with a side that is larger than the radius of the antenna
Possibility of the intruder intruding through the fence during operation of the drive	Installation of optical or microwave barriers in the internal protection zone of antennas
Non-existent control and monitoring system of the device	Design and construction of a control system based on modern PLC devices and Internet communication protocols with the ability to operate with IIoT devices
The ability to inclination of the SSR antenna by foreign objects - the action of vandals or atmospheric factors	Installation of IIoT spatial position sensors on rotary antenna
Control and monitoring from inside the building and from the Internet - double control	Implementation of the control algorithm with the exclusive control blocking
Monitoring and control via a Internet remote HMI	Implementation of Intrusion Prevention System
Non-existent driver for electric engine	Select adjustable frequency drive with Safe Stop function

The radar mounting base has two redundant AC motors of 5.5 kW and a rated nominal current of 11 A with motoredutors ensuring the 15 rpm rotational speed of the antennas. In addition to the nominal factors, the most important matter was the choice of emergency stop solutions in the event of unauthorized persons entering the antenna motion zone in accordance with industry standards EN IEC 61800-5-21 and EN/ISO 13850 defining stop types as:

- Stop Category 0 – stopping by immediate removal of electrical power to the motors and then stopping of machine motion,
- Stop Category 1 – a controlled stopping of machine motion with electrical power to machine motors to achieve the stop and then removal electrical power,
- Stop Category 2 – a controlled stopping of machine motion with electrical power left available after stop of machine motion.

Analyzing the specifics of the Marconi ASR radar propulsion solution and the forecasted high inertia of the antenna, it was necessary to select an adjustable frequency drive with a reserve of a power for controlling the drive. It was also required to provide Safe Torque Off (STO) functionality as defined by EN IEC 61800-5-21 and Stop Category 0 as defined in EN 60204-12, known as Safe Stop. After further analyzing the needs and requirements, the adjustable frequency Danfoss VLT drive

model FC302P7K5 ($P = 7.5 \text{ kW}$ and $I_n = 16 \text{ A}$) with integrated Safe Stop functionality was selected.

Due to uninterrupted rotary motion, devices type IIoT with IoT Hub in the radar mounting base were proposed as position sensors.

3. RESULTS

As elements of the project implementation, many activities are planned, such as:

1. Selection of the exact location of the radar and selection of the location of the control cabinet inside the building and the location of the control panel (START/STOP, Emergency-STOP, Emergency-RESET buttons).
2. Repair of mechanical parts including motoredactors and the radar main bearing.
3. Selection, design and assembly of new sensors for the motoredactors, rotary encoder and spatial position sensors of the antennas to detect anomalies.
4. Selection and design of a functional security system and a control system based on a PLC controller and a distributed input/output with Safe Mode module.
5. Design of a remote monitoring and control system including internal network security, software and others.

Selected Danfoss VLT drive is approved to be suitable for the fulfillment of many standards:

- Level SIL 2 capability according to IEC 61508 and IEC 61800-5-2 standards,
- Level SILCL 2 according to EN 62061,
- Performance Level "d" according to EN ISO 13849-1:2008 and
- Safety Category 3 according to EN ISO 13849-1.

This choice implements the requirements defined in accordance with EN ISO 12100 standard.

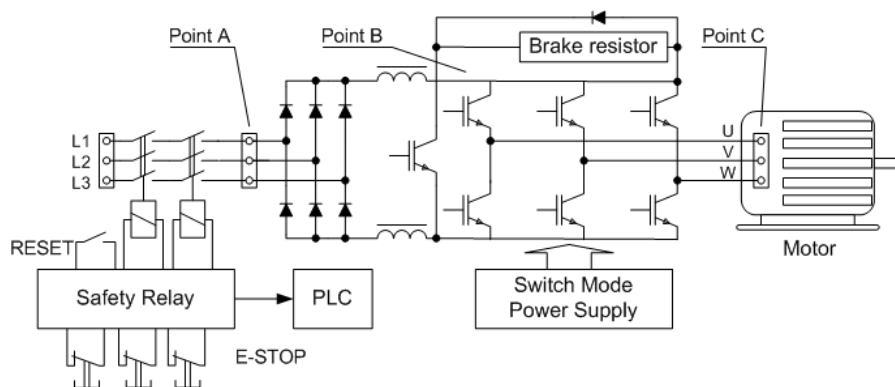


Fig. 3. Simplified, "classic" adjustable frequency drive layout with emergency power disconnection function

While selecting the available emergency stop solutions, possible solutions of the power off points for STO Category 0 were analyzed. As shown in Fig. 3, removal of electrical power can occur at the frequency driver input at point A. Information on the operation of protection in the form of a status change is also sent to the PLC. This solution ensures complete removal of dangerous voltage from the machine. However, it has disadvantages in the form of working on high voltage and high current values. The data from the frequency driver is also lost. In an emergency situation, it is also possible to immediately shut off the power source before the engine at point C.

However, this is not recommended and does not solve the problem of the lack of frequency driver monitoring.

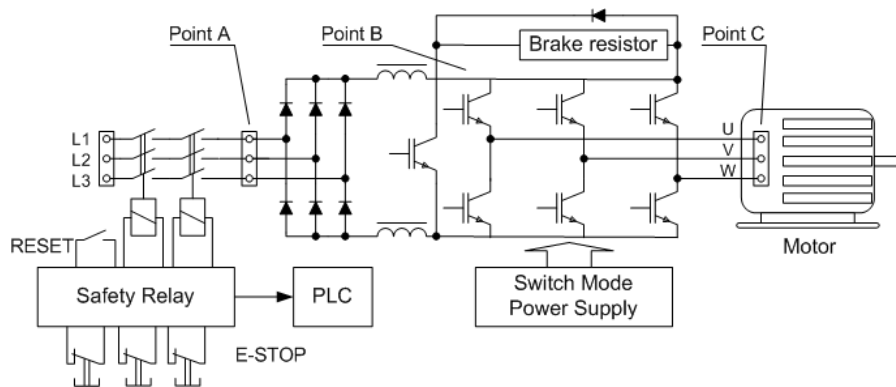


Fig. 4. Simplified adjustable frequency drive layout to implement selected Safe Torque Off function as monitored emergency stop

Modern adjustable frequency drives as proposed by Danfoss VLT series drive, have the ability to immediately cut off power by switching off in IGBT transistors marked as point B in fig. 4. Such solutions can use external safety relays or modules mounted inside the drive. There is no loss of communication between drive and PLC using dedicated digital I/O and industrial LAN over e.g. Profinet protocol.

The use of electromagnetic brake control (shown in Fig. 4) not used in the original is also available. Electromagnetic brake extend STO Category 0 function to control and speeding of stop machine movement.

In the area of ICT security, possible network threats were analysed and planned to be protected by continuous monitoring. It is planned to use encryption of communication in particular in the IoT sensor operating in a wireless network in public space. Taking control of one sensor can permit control of the industry LAN and all connected devices.

4. DISCUSSION

The problem of device revitalization, especially if their functionality changes, requires re-analyzing functional and non-functional requirements. The example indicates a change from the system without functional protection to protection at SIL2 security level. The Machinery Directive (Directive 2006/42/EC, 2006) and current set of standards does not provide for many solutions such as multiplication of machine control panels or simultaneous access from WebHMI devices and classic control panels. The problem is the lack of awareness of the importance of securing even the simplest device such as a wireless distance sensor. IoT era gives huge possibilities for monitoring devices with cable elimination, but at the same time significantly increases the risk of cyber hacking and taking control even over the entire factory. In the presented example, we can imagine a situation in which the hacker changes the values of the frequency drive factors and accelerates the radar to a speed that is dangerous for the integrity of the structure. The control concepts in the field of functional safety also change. The shift of the safety relay functionality to frequency drive provides better monitoring of the control system and increase the life of switching elements. The presented examples are only an introduction to the subject presented in the title.

5. POSSIBLE REUSABILITY

Presented approach to the issue of a safety may be directly used in many other areas of activity, especially at large scale facilities with a huge infrastructure e.g. FAIR at Darmstadt (Singh et al., 2016a; Singh et al., 2016b; Singh et al., 2017), however it is still usable at smaller, but also potentially dangerous stands, industrial or research, e.g. hydraulic test stands (Lisowski and Filo, 2017; Krawczyk et al., 2018), biotechnological laboratories (Skrzypczak-Pietraszek and Pietraszek, 2009; Skrzypczak-Pietraszek et al., 2018) or chemical labs, especially with critically toxic heavy metals (Ulewicz et al., 2003; Ulewicz et al., 2007; Ulewicz et al., 2010; Radzyminska et al., 2014). Materials science laboratory or test stands are also potentially dangerous because of a very high (Opydo et al., 2016; Klimecka-Tatar, 2017) or ultra-low temperature (Wlodarczyk et al., 2011), a high pressure (Dudek and Wlodarczyk, 2010), high forces (Ulewicz et al., 2014; Mazur and Mikova, 2016; Sygut et al., 2016; Mazur et al., 2018), aggressive reagents (Szabracki and Lipinski, 2014), a laser emission (Radek et al., 2018) or a nanoparticles dust hazard (Korzekwa et al., 2018). The same situation may be observed at mechanical test stands e.g. resonance vibrations (Ferdek and Koziem, 2013). In general, it can be noted that such situations should be identified during the analysis of processes in enterprises and laboratories, and appropriate action should be taken to improve safety (Koziem and Koziem, 2017; Maszke et al., 2018). If possible, real experiments and dangerous tests should be replaced with numerical simulations of flows (Domagala et al., 2018a; Domagala et al., 2018b), high pressure devices (Filo et al., 2018) or a high temperature effects (Osocha et al., 2004; Osocha, 2018) with application of the statistical methods (Goroshko et al., 2014; Goroshko and Royzman, 2015) and an appropriate estimation of the uncertainty (Dwornicka et al., 2017; Gadek-Moszczak, 2017; Pietraszek et al., 2017).

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