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Development of the Design of an Experimental Adsorber and Optimization of its Gas-Dynamic Parameters

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ABSTRACT

Various technologies and equipment are used to reduce greenhouse gas emissions. For example, the method of adsorption is used to capture carbon dioxide (CO_2) from the smoke emissions of cement industries. In the adsorption process using zeolites, devices such as adsorbers are typically employed. Zeolites, a versatile group of aluminosilicate materials, are known for their high surface area and selective adsorption properties, making them effective for CO_2 capture. The effectiveness of the adsorber depends on many factors, including its geometric dimensions and shape. Adsorbers with a central inlet flow have uneven gas distribution at the entrance to the adsorbent layer, which reduces their operational efficiency. To eliminate this disadvantage, various devices installed at the output of the adsorber inlet are usually used. Analysis of such devices shows that they do not provide maximum adsorption efficiency. To study the efficiency of zeolite operation for capturing carbon dioxide contained in the smoke gases of cement industries, the design of a laboratory adsorber was proposed, featuring a cyclone and distribution device in its lower part. The cyclone prevents the adsorbent from being contaminated by drip fluid, which reduces the efficiency of the adsorption process in the gas, and the distribution device reduces the uniformity of gas distribution at the entrance to the adsorbent layer. This paper proposes a computational fluid dynamics (CFD) model and design of the distribution device, which was analyzed and modified to significantly increase the uniform distribution of gas at the entrance to the adsorbent layer. Compared with other designs of distribution devices, the proposed design is simpler and performs better under varying gas flow rates.

Keywords: carbon dioxide, adsorbent, zeolite, adsorber, speed, efficiency, computational fluid dynamics.

INTRODUCTION

Global warming, caused by increasing environmental pollution, necessitates a radical shift toward a more sustainable energy system and environmentally friendly methods of industrial production, in particular those reducing $CO₂$ emissions [1–3]. The capture and storage of CO_2 using the adsorption method are widely employed by various industries, including cement production [4]. The choice of adsorbent for capturing $CO₂$ depends on many factors, such as its efficiency, cost, and availability [3, 5, 6].

Among the variety of materials that are used as adsorbents, one that is inexpensive and commonly used is zeolite [7, 8]. In the adsorption process using zeolite, devices referred to as adsorbers are typically employed. They are divided into different categories: fixed granular adsorbers, moving granular adsorbers, and those with a fluidized (pseudo-liquid) layer of fine dispersed adsorbent [9]. The effectiveness of the adsorber depends on various factors, including its geometric dimensions and shape [10–12].

Vertical adsorbers face challenges in ensuring the uniform distribution of gas flow rates across the cross-section of the inlet to the bulk working layer [13–15]. The gas enters through a nozzle with a cross-sectional area 15–50 times smaller than that of the housing, leading to uneven distribution of speed and pressure [9]. This results in uneven gas flow through the adsorbent layer. In one part of the layer, the movement of gas is accelerated, and in the other, it slows down, which leads to a decrease in the overall efficiency of the adsorber.

Understanding the adsorption properties of different materials is crucial for optimizing the capture and storage of gases. For instance, the nitrogen adsorption–desorption behavior of carbon materials derived from coffee waste, as investigated in other studies, provides insight into the physical sorption characteristics and surface area metrics that are critical for effective adsorption processes [16]. Similarly, porous carbon materials (PCMs) have been studied for their multifunctional applications, including energy storage, owing to their unique structural and electrochemical properties [17]. These studies show that the adsorption isotherms and the specific surface area of the materials play a significant role in their efficiency as adsorbents. By examining such properties, one can draw parallels and improve the selection and design of adsorbents for $CO₂$ capture.

In order to achieve even distribution of the gas flow across the adsorber cross-section before the working layer, distribution devices are placed at the outlet of the gas flow from the inlet nozzle [15]. The most common ones consist of a flat disk screen installed below the input nozzle. The gas stream from the inlet pipe hits the flat screen, changing its direction of movement. The disk screen is attached to the inlet pipe with a special frame or ribs welded to the expansion nozzle or directly to the bottom of the adsorber. The efficiency of gas flow distribution using a distribution device directly depends on its geometric dimensions and the ratio of the cross-sectional area

of the adsorber housing to that of the inlet nozzle [18, 19]. A higher area ratio demands greater efficiency in gas flow distribution created by the device [20]. The efficiency of gas flow distribution also depends on the size of the distribution device and the relative distance between the device (at the stream inlet) and the working layer of the adsorbent. This design does not ensure a uniform distribution of the gas flow across the cross-section of the adsorber at the entrance to the bulk layer of the adsorbent, reducing the adsorption capacity by 30%.

There are also diffuser types of distribution devices [21]. These improve the uniformity of gas flow distribution in the adsorber cross-section in comparison with the disk screen by allowing preliminary expansion of the flow in the diffuser. Smooth output and subsequent expansion in the space beneath the adsorbent layer are crucial. However, diffusers alone cannot achieve sufficiently uniform gas flow distribution, leading to variable speeds at different cross-sectional points and the occurrence of reverse flow in the areas with reduced static pressure [22].

Additionally, a distribution device is used to enhance gas flow distribution at the entrance to the adsorbent layer [23]. This device, placed in the input nozzle, contains two concentric rings of different diameters and a flat disk screen. While this design slightly increases the efficiency of gas flow distribution, it also presents certain disadvantages: 1) the distribution device is too tall; 2) the design becomes more complex [24].

The purpose of the work was to use fluid simulation to design an experimental adsorber with a specific shape and size of internal elements to improve its efficiency. The primary objectives were: 1) to develop the design of the experimental $CO₂$ adsorber based on a comprehensive analysis, with consideration of the unique aspects of cement production; 2) to select and optimize the design of its internal elements for improved performance.

Cement production is an energy-intensive and expensive process that yields one of the most popular and essential building materials [25–27]. Cement can be used both independently and as a component in other materials [28, 29]. During its production, raw materials like limestone and clay are mixed in a specific ratio (75–80% limestone and 20–25% clay). This mixture closely resembles natural marl (a limestone-clay rock) in composition. Cement can be produced in three ways: wet, dry, and combined.

In the wet process, all types of raw materials, after grinding, are mixed and then ground in an aquatic environment in special mills. The resulting sludge (a dense suspension containing 35– 40% water) enters large pools, where it is thoroughly mixed. The cement mixture is then burned in a rotating furnace, shaped like a drum with a diameter of up to 5 meters and lined with refractory material. The sludge is continuously fed into the furnace. The movement of flue gases, a byproduct of combustion, occurs within the system. This motion is facilitated by the inclined orientation and slow rotation of the furnace, directing the resultant mixture toward the combustion point.

As the mixture of calcium carbonate undergoes thermal decomposition, yielding calcium oxide and carbon dioxide, the process of clay decomposition is also initiated. At temperatures of approximately 1500 °C, calcium oxide reacts with the constituents of clay, forming silicates, aluminosilicates, calcium aluminates, and other assorted products. After the firing process, the resultant clinker is pulverized alongside gypsum in specialized cylindrical ball mills, where steel balls facilitate particle size reduction [30–32]. This procedure culminates in the production of cement powder, completing the manufacturing process [33].

Cement production emits various pollutants that negatively impact the environment [34–36]. In order to reduce these emissions, many different technologies and entire equipment complexes have been developed. However, such technologies and complexes are expensive both in the manufacture as well as during operation and maintenance.

When it comes to utilization and application of captured $CO₂$ and other harmful impurities extracted from flue gases, the condensate from flue gases with partially dissolved $CO₂$ and small mechanical harmful particles can be utilized in cement slurry and used both for the production of concrete products as well as in the process of constructing oil and gas wells. Using flue gas condensate for making cement stone results in improved mechanical properties [37, 38]. Another option for CO_2 application is its transportation through pipelines for injection into depleted oil and gas reservoirs [39, 40]. Their advantages include an effective structure that retains hydrocarbons and can also retain carbon dioxide. Among the known methods of using $CO₂$ is its use to enhance hydrocarbon recovery from oil and gas fields at various stages of extraction [41, 42]. This process includes

maintaining reservoir pressure, extracting residual oil from watered-out oil reservoirs, and recovering condensed hydrocarbons from depleted gas-condensate reservoirs [43]. An effective technology is injecting $CO₂$ into formations with high-viscosity oil to increase oil recovery [44]. $CO₂$ has a unique and extremely beneficial property for increasing oil production, namely the ability to increase the viscosity of water when dissolved in it [45]. These properties of carbon dioxide are extremely important when developing fields with high-viscosity oil. Injecting $CO₂$ into oil reservoirs is considered one of the most effective methods for oil extraction and reducing CO_2 emissions [46].

Ensuring the uniform distribution of the incoming gas flow across the adsorber cross-section before the bulk layer of the adsorbent, especially with the central arrangement of the connecting pipe, is a critical objective not only for adsorbers, but also for other devices, such as filters, separators, and furnaces [15]. An analysis of the efficiency of existing distribution devices shows that the known design structures are largely ineffective.

MATERIALS AND METHODS

Adsorber construction

The article proposes to remove the water vapor from the smoke gases of cement production (to obtain smoke condensate). To achieve this, a "method of release of fluid and mechanical impurities from the gas flow" is developed in the work [47]. The main task of this method is to increase the efficiency of the purification of flue gases in large volumes of water vapor and mechanical impurities to ensure environmental safety. When using this method of allocation of water and mechanical particles from high-temperature gas flow $(120-160 \degree C)$ is carried out with minimal energy consumption. The resulting smoke condensate will be disposed of or reused in the process of cement production.

To implement the proposed method, taking into account the composition and various characteristics of the flue gases from cement production, a multinozzle device and a gas-liquid separator have been developed [47]. As the flue gases pass through the multi-nozzle device, their cooling and condensation of water vapor occur, with the condensate being collected using the gas-liquid separator.

To capture carbon dioxide from the cooled flue gases of cement production, it is proposed to pass them through the adsorber structure developed in the laboratory (Figure 1). The main advantages of the developed structure include simplicity, the presence of interchangeable elements, and the ability to capture liquid droplets before the gas flow enters the adsorbent. The presence of liquid droplets in the cooled and purified flue

Figure 1. Adsorber construction. Note: 1—housing; 2—outlet nozzle; 3—lid; 4—stud connection; 5 mesh; 6—zeolite; 7—rectangular inlet nozzle; 8 circular inlet nozzle; 9—liquid drain nozzle; 10 conical part of the cyclone housing; 11—cylindrical part of the cyclone housing; 12—cyclone outlet nozzle; 13—disk; 14—deflector; 15—mesh

gases from cement production may be due to the specific composition of the flue gases, condensation temperatures, and other factors.

The structure of the adsorber is as follows. The cylindrical part of the cyclone housing (11) is connected to the conical part of the housing (10), to which the liquid drain nozzle (9) is attached. Inside the cylindrical part of the cyclone housing (11), a disk (13) is placed, which houses the cyclone outlet nozzle (12). A rectangular inlet nozzle (7) is connected to the outside of the cylindrical cyclone housing (11), smoothly transitioning into a circular inlet nozzle (8). At the top, the cylindrical part of the cyclone housing (11) is connected to the adsorber housing (1), in which a mesh (5) is installed to hold the zeolite (6). This construction includes five such adsorber bodies. The number of adsorber bodies can be increased or decreased as necessary. The last (top) adsorber body has a lid (3) with an outlet nozzle (2). The housing (1), lid (3), and the cylindrical part of the cyclone housing (11) are connected by a stud connection (4).

The principle of operation of the laboratory adsorber construction is as follows: the gasliquid mixture is supplied into the circular inlet nozzle (8) and enters the rectangular inlet nozzle (7). Nozzle (7) is tangentially connected to the cylindrical part of the cyclone housing (11), whereby under the action of centrifugal force and gravitational force, liquid droplets, if present in the gas stream, are separated from it and move downwards, being discharged from the adsorber through the liquid drain nozzle (9).

The gas stream, now free from liquid droplets, moves upwards through the cyclone outlet nozzle (12) and strikes the deflector (14), which alters its direction. After bypassing the deflector (14), the gas stream enters the first adsorption stage, where the adsorbent (zeolite) is located. As the gas passes through the adsorbent, CO_2 is adsorbed, while other components of the gas stream remain unabsorbed.

A distinctive feature of the adsorber construction is the presence of a cyclone in its lower part, which facilitates the removal of liquid from the gas mixture. It is known that the adsorbent used for $CO₂$ adsorption also absorbs water, significantly reducing the efficiency of $CO₂$ adsorption [48]. Since the gas flow distribution at the inlet to the adsorbent layer significantly affects the efficiency of the adsorber operation, the article investigated various options for auxiliary devices that promote its uniform distribution.

Flow simulation

The development of various equipment used to rely heavily on the practical experience of researchers, often supplemented by simplified mathematical models. This approach required significant physical and economic resources and frequently failed to yield the desired results. In modern times, with the advancement of computer technology, addressing complex and pressing challenges is inconceivable without the utilization of software suites capable of simulating operational processes occurring within different apparatuses. The study of these processes was extraordinarily labor-intensive and sometimes deemed impossible in practical terms [49–51]. During the development of equipment, software programs implementing CFD methods have gained widespread adoption [52, 53]. One such program is the Flow Simulation module within the SolidWorks software suite [54, 55].

Flow Simulation solves the Navier–Stokes equations, which represent mass, momentum, and energy conservation laws for fluid flows. These equations are enhanced by state equations and empirical dependencies of fluid properties (density, viscosity, and thermal conductivity) on temperature. The viscosity of inelastic non-Newtonian fluids depends on shear rate and temperature, while the density of compressible liquids depends on pressure. Specific problems are defined by geometry, boundary, and initial conditions.

Flow Simulation predicts both laminar and turbulent flows. Laminar flows occur at low Reynolds numbers, defined by velocity, length scale, and kinematic viscosity. Above a critical Reynolds number, flows become turbulent with random fluctuations. Most engineering flows are turbulent, so Flow Simulation focuses on these, using Favre-averaged Navier–Stokes equations to include turbulence effects and employing the *k*-*ε* model for turbulence closure.

The same system of equations describes both laminar and turbulent flows, allowing transitions between them. For the models with moving walls, appropriate boundary conditions are specified. For the models with rotating parts, the simulation uses rotating coordinate systems, requiring axisymmetric stationary parts. The conservation laws for mass, momentum, and energy can be written in conservation form in local Cartesian coordinates:

$$
\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i) = S_M^p \tag{1}
$$

$$
\frac{\partial \rho u_i}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i u_j) + \frac{\partial p}{\partial x_i} =
$$
\n
$$
= \frac{\partial}{\partial x_i} (\tau_{ij} + \tau_{ij}^R) + S_i + S_{Ii}^P; \ i = 1, 2, 3; j = 1, 2, 3
$$
\n(2)

$$
\frac{\partial \rho H}{\partial t} + \frac{\partial \rho u_i H}{\partial x_i} = \frac{\partial}{\partial x_i} \left[u_j \left(\tau_{ij} + \tau_{ij}^R \right) + q_i \right] + \frac{\partial p}{\partial t} + S_i u_i + S_H^p + Q_H \tag{3}
$$
\n
$$
H = h(P, T, y) + \frac{u^2}{2} + k
$$

where: u – velocity of the fluid; p – density of the fluid; S_i – mass-distributed external force uis
. $\text{distance} \quad (S_i^{porous})$, a gravity $(S_i^{gravity} = \rho g_i)$ per unit mass due to a porous media recomponent along the *i*-th coordinate diwhere g_i is the gravitational acceleration β_i , γ_i court entirely in the foculation $S_i^{rotation}$; *H* – total enthalpy in the local refer- $\frac{1}{2}$ – concentration vector of the fluid mixture
components: k – kinetic energy of turbu- α = concentration vector of the fluid mixture

components; $k -$ kinetic energy of turbu-

lence: $S \times P$, $S \times P$ = additional interfacial particle interaction; Q_H – heat source or lence; S_M^P , S_H^P , S_H^P – additional interfacial
exchange terms due to Euler-Lagrange stress tensor; q_i – diffusive heat flux) (8) rection), and the rotation of the coordinate system $(S_i^{rotation})$, i.e., $S_i = S_i^{proves} + S_i^{gravity} +$ a given $n(Y, I, Y)$ – the
pressure (*P*), tem
xture components fluid mixture components *y*; $y = y_1, ..., y_n$
 \qquad = concentration vector of the fluid mixture a given pressure (P) , temperature (T) and $\sum_{i=1}^{n} S_{i}^{p} S_{i}^{p} S_{i}^{p}$ – additional interfacial exchange terms due to Euler-Lagrange stress tensor; q_i – diffusive heat flux. particle interaction, Q_H – idea source of
sink per unit volume; τ_{ij} – viscous shear
stress tensor: *a* – diffusive heat flux normal

The subscripts denote summation over the three coordinate directions.
When conducting calcu

here coordinate directions.

When conducting calculations with the High $\frac{1}{2}$ ing energy equation is employed: tne
^ When conducting calculations with the High
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Mach number flow option activated, the follow-

$$
\frac{\partial \rho E}{\partial t} + \frac{\partial \rho u_i (E + \frac{p}{\rho})}{\partial x_i} =
$$
\n
$$
= \frac{\partial}{\partial x_i} [u_j (\tau_{ij} + \tau_{ij}^R) + q_i] - \tau_{ij}^R \frac{\partial u_i}{\partial x_i} + \rho \varepsilon + Q_H \quad (4)
$$
\n
$$
E = e(\rho, T, y) + \frac{u^2}{2}
$$

where: $e(\rho, T, y)$ – internal energy at a given fluid mixture of $\text{matrix } (p)$, emperador (1) , and
mixture components (y) . \mathbf{r} (1) , and π density (*ρ*), temperature (*T*), and fluid $\sum_{i=1}^{n}$

For Newtonian fluids, the viscous shear stress tensor is defined as: \mathbf{r}

$$
\tau_{ij} = \mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial t_i} - \frac{2}{3} \delta_{ij} \frac{\partial u_k}{\partial x_k} \right) \tag{5}
$$

 $\mathbb{P}_{\mathcal{M}}$ (1) Following Boussinesq assumption, the Reynolds-stress tensor has the following form:

$$
\tau_{ij}^R = \mu_t \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial t_i} - \frac{2}{3} \delta_{ij} \frac{\partial u_k}{\partial x_k} \right) - \frac{2}{3} \rho k \delta_{ij}
$$
 (6)
where: δ - Kronecker delta function (equal to

 $\frac{1}{2}$ viscos dynamic viscosity coefficient; μ_t – turbuwhere: δ_{ij} – Kronecker delta function (equal to unity when $i = j$ but zero otherwise); $μ$ –
dynamic viscosity coefficient: $μ$ – turbudynamic viscosity coefficient; μ_t – turbu-
lent eddy viscosity coefficient; k – turbulent kinetic energy. kinetic energy. − 2 here: δ_{ij} – Kronecker delta function (equal $\begin{cases} \n\phi \times \cos \theta \\ \n\phi - \sin \theta \end{cases}$ y when $t = f$ but zero of
amic viscosity coefficie \sim \sim \sim where: δ_{ij} – Kronecker delta function (equal $\overline{}$ dynamic viscosity coefficient; $k -$
lent eddy viscosity coefficient; k kinei

 $\frac{1}{2}$ is the unit of the noted that μ and k and μ It should be noted that μ_t and k are equal to the k – turbulence model, μ _{*i*} is determined based
on two fundamental turbulence characteristics on two fundamental turbulence characteristics, $q_i = \left(\frac{\mu}{P_r} + \frac{\mu}{2}\right)$
specifically the turbulent kinetic energy k and the tur $\frac{1}{2}$ $\frac{d}{dx}$ turbulent dissipation ε : It should be hoted that μ_i and κ are equal to
zero for laminar flows. Within the framework of specifically, the turbulent kinetic energy *k* and the Solution of the set of the set of $q_i = \left(\frac{\mu}{P_r} +$

and the set of $\frac{1}{1}$. that μ_i and k are equal to When the Lewis ecifically, the turbulent kin
thulent dissipation ε : exploring the turbulent kinetic energy e noted that *u* and alence model, μ_t is de the k – turbulence model, μ _i is dete
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specifically the turbulent kinetic on $\frac{1}{2}$ two fundamental furolence characteristic
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$$
\mu_t = f_\mu \frac{C_\mu \rho k^2}{\varepsilon} \tag{7}
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 $-$ turbulent ent viscosity factor defined by
between these state Equation 8: where: f_{μ} – turbulent viscosity factor defined by -8 : $\overline{3}$ $\frac{1}{2}$ 8. $\overline{3}$ \overline{z}

$$
f_{\mu} = [1 - exp(-0.0165R_y)]^2 \cdot \left(1 + \frac{20.5}{R_T}\right)(8)
$$

 ν here $R_T = \frac{\rho k^2}{\mu s}, R_y =$ $\sqrt{k}y$ $\sqrt{2}$) lista wh \mathbf{r}_j $R_T = \frac{\mu \varepsilon}{\mu \varepsilon}, R_y = \frac{\varepsilon}{2}$
the wall). $\frac{1}{\mu}$ (y – dis Example from
For comparison where: $R_T = \frac{\rho k^2}{\mu \epsilon}$, $R_y = \frac{\rho \sqrt{k}y}{\mu}$ (*y* – distance from **RES** the wall). $_{\text{ere}}$: $R_T = \frac{\rho}{r}$ $=\frac{\rho k^2}{\mu \varepsilon}, R_y$ $R_y = \frac{\rho \sqrt{k} y}{\mu}$ (y ere: $R_T = \frac{\rho k^2}{\mu \varepsilon}$, $R_y = \frac{\rho \sqrt{k}y}{\mu}$ (y – distance from **RESULTS AN** $=\frac{\rho k^2}{\mu \varepsilon}, R_y$ $R_y = \frac{\rho \sqrt{k} y}{\mu}$ (y where: $R_T = \frac{\rho k^2}{\mu \varepsilon}$, $R_y = \frac{\rho \sqrt{k}y}{\mu}$ (y – distance from **RESULTS AN** $=\frac{\rho k^2}{\mu \varepsilon}$, R_y
wall). \mathcal{L} $=\frac{\rho\sqrt{k}}{\mu}$ $\mathcal{L}_{\mathbf{a}}$ $\mathcal{L}_{\mathcal{L}}$ − distance from **RESULTS AND D** $\frac{1}{2}$ the wall).

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$$
\frac{\partial \rho k}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i k) = \frac{\partial}{\partial x_i} \left[\left(\mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_i} \right] + S_k \quad (9)
$$

$$
\frac{\partial \rho \varepsilon}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i \varepsilon) = \frac{\partial}{\partial x_i} \left[\left(\mu + \frac{\mu_t}{\sigma_{\varepsilon}} \right) \frac{\partial \varepsilon}{\partial x_i} \right] + S_{\varepsilon} \tag{10}
$$

 $\frac{1}{k}$ and 12: where: S_k and S_e are defined as in Equations 11 \overline{a} \mathbb{R}^2 $\frac{1}{2}$ hed as in \overline{a} .
Ec ا L here: S_k and S_e are defined as in Equations 11 to be 0.13 m³/s
and 12.

$$
S_k = \tau_{ij}^R \frac{\partial u_i}{\partial x_j} - \rho \varepsilon + \mu_y P_B \tag{11}
$$

$$
S_{\varepsilon} = C_{\varepsilon_1} \frac{\varepsilon}{k} \left(f_1 \tau_{ij}^R \frac{\partial u_i}{\partial x_j} + \mu_t C_B P_B \right) - C_{\varepsilon_2} f_2 \frac{\rho \varepsilon^2}{k} (12)
$$

where: P_B – turbulent generation caused by buoyancy forces. It can be written as Equation 13:

$$
P_B = \frac{g_i}{\sigma_B} \frac{1}{\rho} \frac{\partial \rho}{\partial x_i} \tag{13}
$$

 $\frac{1}{2}$ tion in $\frac{m}{\text{div}\epsilon}$ C_B is defined as: $C_B = 1$ when $P_B > 0$, and tion in direction x_i ; $\sigma_B = 0.9$, and constant $\frac{1}{2}$ where: g_i – component of gravitational accelera-0 otherwise.

$$
\frac{2}{3}\rho k \delta_{ij} \tag{6} \qquad f_1 = 1 + \left(\frac{0.05}{f_\mu}\right); f_\mu = 1 - \exp(-R_T^2) \tag{14}
$$

used in Flow Simulation: empirically. The following values are typically The constants $C\mu$, C_{ε} , C_{ε} , σ_k , σ_{ε} are defined initially. The following volves are trained in

 ⁼ Ξ ī $\overline{}$

$$
C\mu = 0.09, Cel = 1.44, Cel = 1.92,\n\sigmak = 1.92, \sigmae = 1.3
$$
\n(15)

al to When the Lewis number $Le = 1$ the diffusive $\frac{1}{2}$. heat flux (q_i) is defined as:

$$
q_i = \left(\frac{\mu}{P_r} + \frac{\mu_t}{\sigma_c}\right) \frac{\partial h}{\partial x_i}; \ i = 1, 2, 3 \tag{16}
$$

enthalpy. $\frac{dy}{dx}$ and the where: $\sigma_c = 0.9$; P_r – Prandtl number; *h* – thermal

These equations encompass both laminar and $\frac{62}{x}$ (between these states. The parameters $\frac{56}{x}$. turbulent flows, with the flexibility for transitions between these states. The parameters k and μ_t are

RESULTS AND DISCUSSION

laminar— butions on the surface of the first adsorbent layer, $\frac{3}{2}$ simulation model in energy stabilization op simulation modeling of the developed laboratory For comparison of velocity and pressure distri-
 $\frac{1}{6}$ (7) stabilization options at the outlet of the inlet nozzle. adsorber was conducted under various gas flow

 $+ S_k$ (9) the use of any stabilization devices. The input pa-In the initial stage of the investigation, simularameters were set to a pressure of 103 kPa at the inlet of the cyclone and a gas temperature of $75 \text{ }^{\circ}\text{C}$ $\left[\frac{1}{s} + S_{\varepsilon}(10)\right]$ The gas flow rate at the device outlet was assumed − determined based on the technological specificaations 11 to be 0.13 m³/s. These input parameter values were $-\rho \varepsilon + \mu_y P_B$ (11) be connected for its experimental trials. ϵ (a) tion modeling of gas flow was performed without \int_{1}^{1} (10) inlet of the cyclone and a gas temperature of 75 °C. tions of the equipment to which the adsorber would

Considering that the parameters of the tech- $\frac{d}{dx}$ of the adsorber, a parametric study was conducted
during the simulation modeling. The gas flow rate $\frac{c}{k}$ (12) of the adsorber, a parametric study was conducted nological process may vary during the operation was varied from 0.065 m³/s to 0.26 m³/s in increments of $0.065 \text{ m}^3\text{/s}.$

utilized during the simulation modeling. Notably, constant tained results, as well as the velocity distribution Figure 2 illustrates the finite element mesh this mesh featured localized refinement in the device zone to obtain more accurate results. The obacross the longitudinal section of the cyclone for different gas flow rates, are presented in Figure 3.

Figure 2. Finite element mesh

To illustrate the dependency of the change in gas velocity in the cross-section of the cyclone, an auxiliary line was added to the three-dimensional model (Figure 4). Figure 5 displays graphical dependencies illustrating the distribution of gas velocity along the auxiliary line.

On the basis of the results obtained from simulation modeling, it is evident that the velocity

Figure 4. Auxiliary line in cross-section of the cyclone, 1 – auxiliary line

distribution across the transverse section of the cyclone is non-uniform. This can be attributed to the operational characteristics of the cyclone, particularly the tangential entry of the gas flow into its housing.

To mitigate this non-uniformity in the velocity distribution across the cross-section of the adsorber, the adoption of a deflector (1) installed

Figure 3. Distribution of gas velocity (m/s) in the cross-section of the cyclone; (a) 0.065 m³/s; (b) 0.13 m³/s; (c) 0.195 m³/s; (d) 0.026 m³/s

Figure 5. Distribution of gas mixture velocity along the auxiliary line

Figure 6. Deflector installed above the outlet nozzle of the cyclone, 1 – deflector

Figure 8. Optimized deflector installed above the outlet nozzle of the cyclone, $1 -$ deflector; $2 -$ hole in the deflector

Figure 7. Distribution of gas mixture velocity along the auxiliary line

Figure 9. Distribution of gas mixture velocity along the auxiliary line

above the outlet nozzle of the cyclone is proposed (Figure 6). Figure 7 illustrates the distribution of gas velocity along the auxiliary line with the implementation of this deflector.

According to the results illustrated in Figure 7, the velocity distribution in the cross-section of the cyclone, where a deflector is installed above the outlet nozzle, remains non-uniform, although it shows significant improvement compared with the cyclone without a deflector. It is important to note that the gas mixture flow rate influences the velocity distribution in the longitudinal section of the cyclone. Specifically, an increase in flow rate exacerbates the non-uniformity in the velocity distribution across the transverse section of the cyclone. Given the operating flow rate of the adsorber, which is $0.13 \text{ m}^3/\text{s}$, the current deflector design in the adsorber is ineffective. To enhance its efficiency, it is proposed to incorporate a through hole in the deflector (Figure 8). Simulations of the cyclone with the improved deflector design are presented in Figure 9.

Hence, the hole in the deflector, installed above the outlet nozzle of the cyclone, significantly changed the velocity distribution along the auxiliary line. By fine-tuning the location, geometry, and size of the aperture, the velocity distribution along the auxiliary line can be made even more uniform, which will be implemented in further studies.

CONCLUSIONS

The current adsorber designs exhibit complexity, large size, and low efficiency. In response to that, a modular laboratory adsorber design has been developed, comprising five sections that can be adjusted in quantity as required. Future iterations of the adsorber may incorporate monitoring and measurement instruments to facilitate laboratory research on carbon dioxide capture from gas mixtures using zeolite as the adsorbent.

To optimize the adsorber efficiency, particularly in achieving uniform gas flow across the transverse section of the cyclone outlet, simulation studies were conducted. These studies examined various factors, such as gas flow rates, shapes, designs, and sizes, both with and without additional distribution elements. Among the proposed solutions, it was found that the installation of a hemispherical deflector above the cyclone outlet, featuring a central hole, achieves the most uniform gas distribution. This design offers simplicity, robust performance across varying gas flow rates, and advanced manufacturing feasibility compared with alternative options.

Further research on the developed adsorber will focus on studying its operation. A full-scale model of the adsorber will be fabricated, and a series of experimental studies will be conducted to determine its technical and technological characteristics, as well as to evaluate the properties of the adsorbents under various gas mixture parameters.

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