




AN OPERATIONAL CALCULUS MODEL WITH THE (m, n) -SYMMETRIC DIFFERENCE

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ABSTRACT

The paper determines a non-classical Bittner operational calculus model, in which the derivative is understood as an (m, n) -symmetric difference $D_{m,n}\{x(k)\} := \{x(k+m) - x(k-n)\}$. By considering an operation $D_{m,n,b}\{x(k)\} := \{x(k+m) - b(k)x(k-n)\}$, the formulated model has been generalized.

Key words:

operational calculus, derivative, integrals, limit conditions, (m, n) -symmetric difference.

Research article

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FOUNDATIONS OF THE NON-CLASSICAL BITTNER OPERATIONAL CALCULUS

The *Bittner operational calculus* [1–4] is referred to as a system

$$CO(L^0, L^1, S, T_q, s_q, Q), \quad (1)$$

where L^0 and L^1 are linear spaces (over the same field Γ of scalars) such that $L^1 \subset L^0$. The linear operation $S : L^1 \rightarrow L^0$ (denoted as $S \in \mathcal{L}(L^1, L^0)$), called the (abstract) *derivative*, is a surjection. Moreover, Q is a set of indices q for the operations $T_q \in \mathcal{L}(L^0, L^1)$ such that $ST_q f = f$, $f \in L^0$, called *integrals* and for the operations $s_q \in \mathcal{L}(L^1, L^1)$ such that $s_q x = x - T_q S x$, $x \in L^1$, called *limit conditions*. The kernel of S , i.e. $\text{Ker } S$ is called a set of *constants* for the derivative S .

It is easy to verify that the limit conditions s_q , $q \in Q$ are projections of L^1 onto the subspace $\text{Ker } S$.

If we define the objects (1), then we have in mind a *representation*, or a *model* of the operational calculus. In particular, representations of the operational calculus (1) are *discrete* models in which the derivative S can be understood as: an n^{th} -order forward difference [16]

$$\Delta_n x(k) := x(k+n) - x(k), \quad (2)$$

an n^{th} -order backward difference [15]

$$\nabla_n x(k) := x(k) - x(k-n) \quad (3)$$

or a $2n^{\text{th}}$ -order central difference [17]

$$D_n x(k) := x(k+n) - x(k-n), \quad (4)$$

where n is a given natural number.

An (m, n) -symmetric difference¹

$$D_{m,n} x(k) := x(k+m) - x(k-n), \quad (5)$$

where m, n are given non-negative integers such that $m^2 + n^2 > 0$, is a generalization of the operations (2)–(4).

In this paper, one shall determine such an operational calculus model, in which the operation (5) will be the derivative S . Next, based on this model, we shall develop a more general representation with a derivative

¹ This notion is related to the α, β -symmetric difference derivative considered in [5,6].

$$D_{m,n,b}x(k) := x(k + m) - b(k)x(k - n)^2. \tag{6}$$

Certain specific models related to (6) were considered in literature before: a model with a derivative

$$D_{1,0,b}x(k) = x(k + 1) - b(k)x(k)$$

was constructed in [10], whereas a model with a derivative

$$D_{0,1,b}x(k) = x(k) - b(k)x(k - 1)$$

was considered in [13].

For b being a constant sequence, representations of operational calculus with derivatives

$$\begin{aligned} D_{n,0,b}x(k) &= x(k + n) - bx(k), \\ D_{0,n,b}x(k) &= x(k) - bx(k - n), \\ D_{n,n,b}x(k) &= x(k + n) - bx(k - n) \end{aligned}$$

were discussed in [16], [15], [17].

(m, n) -SYMMETRIC DIFFERENCE MODEL

Let \mathbb{Z} and \mathbb{C} denote sets of integers and complexes, respectively. Moreover, let $C(\mathbb{Z}, \mathbb{C})$ be a linear space of two-sided complex sequences $x = \{x(k)\}_{k \in \mathbb{Z}}$ with a common sequences addition, and sequences multiplication by complex numbers. Further, let

$$\varepsilon_0, \varepsilon_1, \dots, \varepsilon_{\nu-1} \tag{7}$$

be roots of unity of order $\nu := m + n$, i.e.

$$\varepsilon_j = \cos \frac{2j\pi}{\nu} + i \sin \frac{2j\pi}{\nu}, \quad j \in \overline{0, \nu - 1}^3,$$

where ‘ i ’ is the imaginary unit.

² The sequences multiplication in (6) means a usual coordinate-wise (Hadamard) multiplication.

³ $\overline{0, \nu - 1} := \{0, 1, \dots, \nu - 1\}$.

Using the following properties of the sequence (7):

$$\begin{aligned} \varepsilon_j^{k+\ell v} &= \varepsilon_j^k, \quad j \in \overline{0, v-1}, \quad k, \ell \in \mathbb{Z}, \\ \varepsilon_0^r + \varepsilon_1^r + \dots + \varepsilon_{v-1}^r &= 0, \quad r \neq \ell v, v > 1, \ell, r \in \mathbb{Z} \end{aligned}$$

we shall prove the below

Theorem 1. A system (1), where $x = \{x(k)\} \in L^0 = L^1 := C(\mathbb{Z}, \mathbb{C}), k_0 \equiv q \in Q := \mathbb{Z}$ and

$$Sx := \{x(k+m) - x(k-n)\}^4 \tag{8}$$

$$T_{k_0}x := \begin{cases} -\frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k+n}^{k_0+n-1} \varepsilon_j^{k+n-i} x(i) & \text{for } k < k_0 \\ 0 & \text{for } k = k_0 \\ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0+n}^{k+n-1} \varepsilon_j^{k+n-i} x(i) & \text{for } k > k_0 \end{cases}, \quad k \in \mathbb{Z}, \tag{9}$$

$$s_{k_0}x := \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0}^{k_0+v-1} \varepsilon_j^{k-i} x(i) \right\} \tag{10}$$

forms a discrete model of the Bittner operational calculus⁵.

Proof. Obviously, the operations (8)–(10) are linear. Let $\{y(k)\} := T_{k_0}\{x(k)\}$. Hence, for $k = k_0$ we obtain

$$\begin{aligned} S\{y(k)\}|_{k=k_0} &= \{y(k_0+m) - y(k_0-n)\} \\ &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0+n}^{k_0+v-1} \varepsilon_j^{k_0-i} x(i) + \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0}^{k_0+n-1} \varepsilon_j^{k_0-i} x(i) \right\} = \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0}^{k_0+v-1} \varepsilon_j^{k_0-i} x(i) \right\} \\ &= \left\{ x(k_0) + \frac{1}{v} \sum_{i=k_0+1}^{k_0+v-1} (\varepsilon_0^{k_0-i} + \varepsilon_1^{k_0-i} + \dots + \varepsilon_{v-1}^{k_0-i}) x(i) \right\} = \{x(k)\}|_{k=k_0}. \end{aligned}$$

For $k < k_0$ and $k+m = k_0$ (i.e. $k = k_0 - m$), we have in turn

⁴ $\{x(k)\}$ means a symbol of the sequence x , i.e. $x = \{x(k)\}$, whereas $x(k)$ means the k^{th} -term of the sequence $\{x(k)\}$, where $k \in \mathbb{Z}$. This notation originates from J. Mikusiński [11].

⁵ Due to the definition of T_{k_0} , we assume that $\sum_{i=k_0+n}^{k_0+n-1} x(i) := 0$.

$$\begin{aligned}
 S\{y(k)\} &= \{y(k+m) - y(k-n)\} = \{y(k_0) - y(k_0 - \nu)\} \\
 &= \left\{0 + \frac{1}{\nu} \sum_{j=0}^{\nu-1} \sum_{i=k_0-m}^{k_0+n-1} \varepsilon_j^{k_0-m-i} x(i)\right\} \\
 &= \left\{x(k_0 - m) + \frac{1}{\nu} \sum_{i=k_0-m+1}^{k_0+n-1} (\varepsilon_0^{k_0-m-i} + \varepsilon_1^{k_0-m-i} + \dots + \varepsilon_{\nu-1}^{k_0-m-i}) x(i)\right\} = \{x(k_0 - m)\}.
 \end{aligned}$$

Therefore,

$$S\{y(k)\} = \{x(k_0 - m)\} \quad \text{that is} \quad S\{y(k)\} = \{x(k)\}.$$

For $k < k_0$ and $k + m < k_0$ (i.e. $k + \nu < k_0 + n$), we get

$$\begin{aligned}
 S\{y(k)\} &= \{y(k+m) - y(k-n)\} \\
 &= \left\{\frac{1}{\nu} \sum_{j=0}^{\nu-1} \sum_{i=k}^{k_0+n-1} \varepsilon_j^{k-i} x(i) - \frac{1}{\nu} \sum_{j=0}^{\nu-1} \sum_{i=k+\nu}^{k_0+n-1} \varepsilon_j^{k-i} x(i)\right\} = \left\{\frac{1}{\nu} \sum_{j=0}^{\nu-1} \sum_{i=k}^{k+\nu-1} \varepsilon_j^{k-i} x(i)\right\} \\
 &= \left\{x(k) + \frac{1}{\nu} \sum_{i=k+1}^{k+\nu-1} (\varepsilon_0^{k-i} + \varepsilon_1^{k-i} + \dots + \varepsilon_{\nu-1}^{k-i}) x(i)\right\} = \{x(k)\}. \tag{11}
 \end{aligned}$$

When $k > k_0$ and $k + m > k_0$ (i.e. $k + \nu > k_0 + n$), we obtain in turn

$$\begin{aligned}
 S\{y(k)\} &= \{y(k+m) - y(k-n)\} \\
 &= \left\{\frac{1}{\nu} \sum_{j=0}^{\nu-1} \sum_{i=k_0+n}^{k+\nu-1} \varepsilon_j^{k-i} x(i) + \frac{1}{\nu} \sum_{j=0}^{\nu-1} \sum_{i=k}^{k_0+n-1} \varepsilon_j^{k-i} x(i)\right\} = \left\{\frac{1}{\nu} \sum_{j=0}^{\nu-1} \sum_{i=k}^{k+\nu-1} \varepsilon_j^{k-i} x(i)\right\},
 \end{aligned}$$

so, by analogy to (11), we have $S\{y(k)\} = \{x(k)\}$.

If $k > k_0$ and $k - n = k_0$ (i.e. $k + m = k_0 + \nu$), then

$$\begin{aligned}
 S\{y(k)\} &= \{y(k+m) - y(k-n)\} = \{y(k_0 + \nu) - y(k_0)\} \\
 &= \left\{\frac{1}{\nu} \sum_{j=0}^{\nu-1} \sum_{i=k_0+n}^{k_0+\nu+n-1} \varepsilon_j^{k_0+n-i} x(i) - 0\right\} \\
 &= \left\{x(k_0 + n) + \frac{1}{\nu} \sum_{i=k_0+n+1}^{k_0+\nu+n-1} (\varepsilon_0^{k_0+n-i} + \varepsilon_1^{k_0+n-i} + \dots + \varepsilon_{2n-1}^{k_0+n-i}) x(i)\right\} = \{x(k_0 + n)\},
 \end{aligned}$$

that is $S\{y(k)\} = \{x(k)\}$.

For $k > k_0$ and $k - n > k_0$ (i.e. $k > k_0 + n$), we have

$$\begin{aligned}
 S\{y(k)\} &= \{y(k+m) - y(k-n)\} \\
 &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0+n}^{k+v-1} \varepsilon_j^{k-i} x(i) - \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0+n}^{k-1} \varepsilon_j^{k-i} x(i) \right\} = \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k}^{k+v-1} \varepsilon_j^{k-i} x(i) \right\},
 \end{aligned}$$

which, similarly to (11), also means that $S\{y(k)\} = \{x(k)\}$.

Now, if $k > k_0$ and $k - n < k_0$ (i.e. $k < k_0 + n$), then

$$\begin{aligned}
 S\{y(k)\} &= \{y(k+m) - y(k-n)\} \\
 &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0+n}^{k+v-1} \varepsilon_j^{k-i} x(i) + \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k}^{k_0+n-1} \varepsilon_j^{k-i} x(i) \right\} = \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k}^{k+v-1} \varepsilon_j^{k-i} x(i) \right\} = \{x(k)\}.
 \end{aligned}$$

Finally, we can confirm that the property $ST_{k_0}x = x$ is fulfilled.

Let $\{f(k)\} := S\{x(k)\} = \{x(k+m) - x(k-n)\}$. Then, for $k < k_0$ we get

$$\begin{aligned}
 T_{k_0}S\{x(k)\} &= T_{k_0}\{f(k)\} = \left\{ -\frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k+n}^{k_0+n-1} \varepsilon_j^{k+n-i} f(i) \right\} \\
 &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \left[\sum_{i=k+n}^{k_0+n-1} \varepsilon_j^{k+n-i} x(i-n) - \sum_{i=k+n}^{k_0+n-1} \varepsilon_j^{k+n-i} x(i+m) \right] \right\} \\
 &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \left[\sum_{i=k}^{k_0-1} \varepsilon_j^{k-i} x(i) - \sum_{i=k+v}^{k_0+v-1} \varepsilon_j^{k-i} x(i) \right] \right\} \\
 &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \left[\sum_{i=k}^{k_0-1} \varepsilon_j^{k-i} x(i) + \sum_{i=k_0}^{k+v-1} \varepsilon_j^{k-i} x(i) - \left(\sum_{i=k_0}^{k+v-1} \varepsilon_j^{k-i} x(i) + \sum_{i=k+v}^{k_0+v-1} \varepsilon_j^{k-i} x(i) \right) \right] \right\} \\
 &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k}^{k+v-1} \varepsilon_j^{k-i} x(i) \right\} - \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0}^{k_0+v-1} \varepsilon_j^{k-i} x(i) \right\}.
 \end{aligned}$$

Hence, on the basis of (11), we eventually obtain

$$T_{k_0}S\{x(k)\} = \{x(k)\} - \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0}^{k_0+v-1} \varepsilon_j^{k-i} x(i) \right\} = \{x(k)\} - s_{k_0}\{x(k)\}.$$

Similarly, if $k > k_0$, then

$$\begin{aligned}
 T_{k_0} S \{x(k)\} &= T_{k_0} \{f(k)\} = \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0+n}^{k+n-1} \varepsilon_j^{k+n-i} f(i) \right\} \\
 &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \left[\sum_{i=k_0+n}^{k+n-1} \varepsilon_j^{k+n-i} x(i+m) - \sum_{i=k_0+n}^{k+n-1} \varepsilon_j^{k+n-i} x(i-n) \right] \right\} \\
 &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \left[\sum_{i=k_0+v}^{k+v-1} \varepsilon_j^{k-i} x(i) - \sum_{i=k_0}^{k-1} \varepsilon_j^{k-i} x(i) \right] \right\} \\
 &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \left[\sum_{i=k}^{k_0+v-1} \varepsilon_j^{k-i} x(i) + \sum_{i=k_0+v}^{k+v-1} \varepsilon_j^{k-i} x(i) - \left(\sum_{i=k_0}^{k-1} \varepsilon_j^{k-i} x(i) + \sum_{i=k}^{k_0+v-1} \varepsilon_j^{k-i} x(i) \right) \right] \right\} \\
 &= \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k}^{k+v-1} \varepsilon_j^{k-i} x(i) \right\} - \left\{ \frac{1}{v} \sum_{j=0}^{v-1} \sum_{i=k_0}^{k_0+v-1} \varepsilon_j^{k-i} x(i) \right\} = \{x(k)\} - s_{k_0} \{x(k)\}.
 \end{aligned}$$

Therefore, the property $T_{k_0} S x = x - s_{k_0} x$ is also fulfilled. \square

Since for $k \in \overline{k_0 + 1, k_0 + v - 1}$ we have

$$\sum_{i=k_0+n}^{k+n-1} (\varepsilon_0^{k+n-i} + \varepsilon_1^{k+n-i} + \dots + \varepsilon_{v-1}^{k+n-i}) = 0,$$

then, from the definition (9) of the integrals T_{k_0} , we get the following

Corollary 1. *If $\{y(k)\} := T_{k_0} \{x(k)\}$, then*

$$y(k) = 0 \quad \text{for } k \in \overline{k_0, k_0 + v - 1}.$$

Example 1. We will list terms of the sequence $\{y(k)\} := T_{k_0} \{x(k)\}$ for $k \in \overline{-17, 24}$ when $m = 3, n = 2$ and $k_0 = 4$. Using (9), we obtain⁶

⁶ *Mathematica*[®] was used for all computations in this paper.

k	$y(k)$	k	$y(k)$
-17	$-x(-15) - x(-10) - x(-5) - x(0) - x(5)$	4	0
-16	$-x(-14) - x(-9) - x(-4) - x(1)$	5	0
-15	$-x(-13) - x(-8) - x(-3) - x(2)$	6	0
-14	$-x(-12) - x(-7) - x(-2) - x(3)$	7	0
-13	$-x(-11) - x(-6) - x(-1) - x(4)$	8	0
-12	$-x(-10) - x(-5) - x(0) - x(5)$	9	$x(6)$
-11	$-x(-9) - x(-4) - x(1)$	10	$x(7)$
-10	$-x(-8) - x(-3) - x(2)$	11	$x(8)$
-9	$-x(-7) - x(-2) - x(3)$	12	$x(9)$
-8	$-x(-6) - x(-1) - x(4)$	13	$x(10)$
-7	$-x(-5) - x(0) - x(5)$	14	$x(6) + x(11)$
-6	$-x(-4) - x(1)$	15	$x(7) + x(12)$
-5	$-x(-3) - x(2)$	16	$x(8) + x(13)$
-4	$-x(-2) - x(3)$	17	$x(9) + x(14)$
-3	$-x(-1) - x(4)$	18	$x(10) + x(15)$
-2	$-x(0) - x(5)$	19	$x(6) + x(11) + x(16)$
-1	$-x(1)$	20	$x(7) + x(12) + x(17)$
0	$-x(2)$	21	$x(8) + x(13) + x(18)$
1	$-x(3)$	22	$x(9) + x(14) + x(19)$
2	$-x(4)$	23	$x(10) + x(15) + x(20)$
3	$-x(5)$	24	$x(6) + x(11) + x(16) + x(21)$

□

Each sequence $c = \{c(k)\}$ that is a constant for the derivative (8) is a ν -periodic sequence. Therefore, from the definition (10) of limit conditions s_{k_0} there follows the below

Corollary 2. *The numbers $x(k_0), x(k_0 + 1), \dots, x(k_0 + \nu - 1)$ form a cycle of the ν -periodic sequence $\{c(k)\} = s_{k_0}\{x(k)\}$, i.e.*

$$c(k) = c(k + \ell\nu) = x(k), \quad k \in \overline{k_0, k_0 + \nu - 1}, \ell \in \mathbb{Z}.$$

PARTICULAR CASES

From Theorem 1 follow difference representations of the Bittner operational calculus mentioned at the beginning of this paper. Namely, for $n = 0$ we obtain the model with the forward difference (2) described in [16]. When $m = n$, we get in turn the model with the central difference (4) constructed in [17]. In [15] there was presented a model, in which to the backward difference (3) there correspond the following limit conditions

$$s_{\nabla_n, k_0}\{x(k)\} = \left\{ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0-n+1}^{k_0} \varepsilon_j^{k-i} x(i) \right\} \quad (12)$$

and integrals

$$T_{\nabla_n, k_0}\{x(k)\} = \begin{cases} -\frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k+1}^{k_0} \varepsilon_j^{k-i} x(i) & \text{for } k < k_0 \\ 0 & \text{for } k = k_0 \\ \frac{1}{n} \sum_{j=0}^{n-1} \sum_{i=k_0+1}^k \varepsilon_j^{k-i} x(i) & \text{for } k > k_0 \end{cases}, \quad k \in \mathbb{Z}. \quad (13)$$

This model is different to the one obtained from Theorem 1 for $m = 0$. The limit conditions (10) are uniquely determined by the initial conditions

$$x(k_0), x(k_0 + 1), \dots, x(k_0 + n - 1),$$

while the limit conditions (12) depend on

$$x(k_0 - n + 1), x(k_0 - n + 2), \dots, x(k_0).$$

Hence, the integrals (9) and (13) are also different, so

$$T_{k_0} T_{\nabla_n, k_0} \neq T_{\nabla_n, k_0} T_{k_0}.$$

GENERALIZATIONS

Let us consider the following generalization of the symmetric difference (8):

$$S_b\{x(k)\} := \{x(k + m) - b(k)x(k - n)\}, \quad (14)$$

where $b := \{b(k)\}$ is a real sequence satisfying the condition

$$\bigwedge_{k \in \mathbb{Z}} b(k) > 0.$$

In the spirit of the method described in [18], we shall define the integrals T_{b, k_0} and the limit conditions s_{b, k_0} corresponding to the derivative (14), called an (m, n) -symmetric difference with the base $b = \{b(k)\}$. In order to do this, we shall also use the following auxiliary theorems:

Lemma 1 (Th. 3 [4]). *An abstract differential equation*

$$Sx = f, \quad f \in L^0, x \in L^1$$

with a limit condition

$$s_q x = x_{0,q}, \quad x_{0,q} \in \text{Ker } S$$

has exactly one solution

$$x = x_{0,q} + T_q f.$$

Lemma 2 (Th. 4 [4]). *With the given derivative $S \in \mathcal{L}(L^1, L^0)$, the projection $s_q \in \mathcal{L}(L^1, \text{Ker } S)$ determines an integral $T_q \in \mathcal{L}(L^0, L^1)$ from the condition*

$$x = T_q f \quad \text{if and only if} \quad Sx = f, s_q x = 0.$$

Moreover, the projection s_q is a limit condition corresponding to the integral T_q .

First, we will determine a positive sequence $d = \{d(k)\}$ such that $d \in \text{Ker } S_b$ and

$$d(0) = d(1) = \dots = d(v-1) = 1.$$

Thus, we have

$$\ln(d(k+m)) - \ln(d(k-n)) = \ln(b(k)), \quad k \in \mathbb{Z},$$

so

$$h(k+m) - h(k-n) = u(k), \quad k \in \mathbb{Z} \tag{15}$$

and

$$h(0) = h(1) = \dots = h(v-1) = 0, \tag{16}$$

where

$$h = \{h(k)\} := \{\ln(d(k))\}, \quad u = \{u(k)\} := \{\ln(b(k))\}.$$

The initial value problem (15), (16) can be presented in the form of

$$Sh = u, \quad s_0 h = 0,$$

where S is the symmetric difference (8), whereas s_0 is the limit condition (10) for $k_0 := 0$. A solution to this problem, based on Lemma 1, is of the following form:

$$h = T_0 u,$$

where T_0 is the integral (9) for $k_0 := 0$.

Finally, the sequence

$$d = \exp(T_0 u) \tag{17}$$

is the desired constant for the derivative (14), i.e.

$$d(k + m) = b(k)d(k - n), \quad k \in \mathbb{Z}.$$

Example 2. If b is a constant sequence and $m := 2, n := 1$ or $m := 1, n := 2$, then from (17) we obtain

$$\{d(k)\} = \{\dots, b^{-3}, b^{-3}, b^{-3}, b^{-2}, b^{-2}, b^{-2}, b^{-1}, b^{-1}, b^{-1}, \underset{k=0}{1}, 1, 1, b, b, b, b^2, b^2, b^2, b^3, b^3, b^3, \dots\}.$$

Generally, we have

$$d(k) = b^{\lfloor k/\nu \rfloor}, \quad k \in \mathbb{Z}^7. \quad \square$$

Let us consider a difference equation

$$S_b\{x(k)\} = \{f(k)\},$$

i.e.

$$x(k + m) - b(k)x(k - n) = f(k), \quad k \in \mathbb{Z}. \tag{18}$$

Hence, we have

$$\frac{x(k + m)}{d(k + m)} - \frac{x(k - n)}{d(k - n)} = \frac{f(k)}{d(k + m)}, \quad k \in \mathbb{Z},$$

so

$$y(k + m) - y(k - n) = g(k), \quad k \in \mathbb{Z}, \tag{19}$$

where

$$y(k) := \frac{x(k)}{d(k)}, \quad g(k) := \frac{f(k)}{d(k + m)}, \quad k \in \mathbb{Z}. \tag{20}$$

The equation (19) can be presented in the form of

$$S\{y(k)\} = \{g(k)\}, \tag{21}$$

where $S \equiv D_{m,n}$ is the operation (8).

From Lemma 1 it follows that the below sequence

$$\{y(k)\} = s_{k_0}\{y(k)\} + T_{k_0}\{g(k)\},$$

where T_{k_0} and s_{k_0} are operations (9) and (10), is the solution to (21).

⁷ $\lfloor r \rfloor$ means the floor (the integer part) of a real number r .

From (20) we obtain $x(k) = d(k)y(k)$, $k \in \mathbb{Z}$. Finally,

$$\{x(k)\} = \{d(k)\} s_{k_0} \left\{ \frac{x(k)}{d(k)} \right\} + \{d(k)\} T_{k_0} \left\{ \frac{f(k)}{d(k+m)} \right\} \quad (22)$$

is the solution to (18).

If we assume that

$$\{\tilde{c}(k)\} := s_{k_0} \left\{ \frac{x(k)}{d(k)} \right\},$$

then $\{\tilde{c}(k)\} \in \text{Ker } S$, so

$$\tilde{c}(k+m) = \tilde{c}(k-n), \quad k \in \mathbb{Z}.$$

Let

$$s_{b,k_0} \{x(k)\} := \{d(k)\} s_{k_0} \left\{ \frac{x(k)}{d(k)} \right\}, \quad k_0 \in Q := \mathbb{Z}, \{x(k)\} \in L^1. \quad (23)$$

Thus, for each $k \in \mathbb{Z}$ we get

$$\begin{aligned} S_b s_{b,k_0} x(k) &= d(k+m) \tilde{c}(k+m) - b(k) d(k-n) \tilde{c}(k-n) \\ &= d(k+m) (\tilde{c}(k+m) - \tilde{c}(k-n)) = d(k+m) \cdot 0 = 0, \end{aligned}$$

that is $s_{b,k_0} \in \mathcal{L}(L^1, \text{Ker } S_b)$. Moreover, since $s_{k_0} \{\tilde{c}(k)\} = \{x(k)\}$, for each $k \in \mathbb{Z}$ we have

$$\begin{aligned} s_{b,k_0}^2 x(k) &= s_{b,k_0} [d(k) \tilde{c}(k)] = e(k) s_{k_0} \left[\frac{d(k) \tilde{c}(k)}{d(k)} \right] \\ &= d(k) s_{k_0} \tilde{c}(k) = d(k) \tilde{c}(k) = s_{b,k_0} x(k). \end{aligned}$$

Eventually, s_{b,k_0} is a projection of L^1 onto $\text{Ker } S_b$ for each $k_0 \in \mathbb{Z}$. From Lemma 2 it follows that the projection s_{b,k_0} determines an *integral* T_{b,k_0} from (22). Namely,

$$T_{b,k_0} \{f(k)\} := \{d(k)\} T_{k_0} \left\{ \frac{f(k)}{d(k+m)} \right\}, \quad k_0 \in Q, \{f(k)\} \in L^0. \quad (24)$$

What is more, s_{b,k_0} is a *limit condition* corresponding to the integral (24).

Finally, we arrive at the

Corollary 3. *The system (14), (23), (24) forms a discrete model of the Bittner operational calculus.*

Example 3. Let us consider an initial value problem

$$x(k+1) - e^k x(k-2) = 0, \quad k \in \mathbb{Z} \quad (25)$$

$$x(0) = 3, x(1) = x(2) = 0. \quad (26)$$

The homogeneous equation (25) takes the form of $S_b x = 0$, where S_b is the forward difference (14) for $m := 1, n := 2, b := \{e^k\}$. From (22) we get the solution to (25) expressed by the limit condition (23), i.e.

$$\{x(k)\} = s_{\{e^k\},0}\{x(k)\} = \{d(k)\}s_0\left\{\frac{x(k)}{d(k)}\right\},$$

which depends of the sequence

$$\{d(k)\} = \exp(T_0\{k\})$$

and initial conditions (26).

Therefore,

$$x(k) = \begin{cases} \left(1 + 2 \cos\left(\frac{2k\pi}{3}\right)\right) \exp\left(-\frac{1}{3} \sum_{j=0}^2 \sum_{i=k+2}^1 i \varepsilon_j^{k+2-i}\right) & \text{for } k < 0 \\ \left(1 + 2 \cos\left(\frac{2k\pi}{3}\right)\right) \exp\left(\frac{1}{3} \sum_{j=0}^2 \sum_{i=2}^{k+1} i \varepsilon_j^{k+2-i}\right) & \text{for } k \geq 0 \end{cases}, \quad k \in \mathbb{Z}, \quad (27)$$

i.e.

$$\{x(k)\} = \{\dots, 0, 0, 3e^{12}, 0, 0, 3e^5, 0, 0, 3e, 0, 0, \underset{k=0}{3}, 0, 0, 3e^2, 0, 0, 3e^7, 0, 0, 3e^{15}, 0, 0, \dots\}.$$

□

Example 4. Referring to the previous example, let us consider the Cauchy problem

$$x(k + 1) - e^k x(k - 2) = 1, \quad k \in \mathbb{Z} \quad (28)$$

$$x(0) = 3, x(1) = x(2) = 0. \quad (29)$$

From (24) and (22) it follows that the sequence

$$\{x(k)\} = T_{\{e^k\},0}\{1\} = \{d(k)\}T_0\left\{\frac{1}{d(k+1)}\right\}$$

is a solution to the nonhomogeneous equation (28) with the conditions $x(0) = x(1) = x(2) = 0$. Thus,

$$x(k) = \begin{cases} -\frac{1}{3} \exp\left(-\frac{1}{3} \sum_{j=0}^2 \sum_{i=k+2}^1 i \varepsilon_j^{k+2-i}\right) \sum_{j=0}^2 \sum_{i=k+2}^1 \exp\left(-\frac{1}{2}(i+1)(i+4)\right) \varepsilon_j^{k+2-i} & \text{for } k < 0 \\ \frac{1}{3} \exp\left(\frac{1}{3} \sum_{j=0}^2 \sum_{i=2}^{k+1} i \varepsilon_j^{k+2-i}\right) \sum_{j=0}^2 \sum_{i=2}^{k+1} \exp\left(-\frac{1}{2}(i+1)(i+4)\right) \varepsilon_j^{k+2-i} & \text{for } k \geq 0 \end{cases}, \quad k \in \mathbb{Z}. \quad (30)$$

Eventually, basing on (22), the sum of the sequences (27) and (30) is a solution to the problem (28),(29), the values of which (for $k \in \overline{-17, 16}$) are presented in the table below:

k	$x(k)$	k	$x(k)$
-17	$-e^{15} - e^{27} - e^{36} - e^{42} - 2e^{45}$	0	3
-16	$-e^{14} - e^{25} - e^{33} - e^{38} - e^{39} - e^{40}$	1	0
-15	$-e^{13} - e^{23} - e^{30} - e^{34} - 2e^{35}$	2	0
-14	$-e^{12} - e^{21} - e^{27} - 2e^{30}$	3	$1 + 3e^2$
-13	$-e^{11} - e^{19} - e^{24} - e^{25} - e^{26}$	4	1
-12	$-e^{10} - e^{17} - e^{21} - 2e^{22}$	5	1
-11	$-e^9 - e^{15} - 2e^{18}$	6	$1 + e^5 + 3e^7$
-10	$-e^8 - e^{13} - e^{14} - e^{15}$	7	$1 + e^6$
-9	$-e^7 - e^{11} - 2e^{12}$	8	$1 + e^7$
-8	$-e^6 - 2e^9$	9	$1 + e^8 + e^{13} + 3e^{15}$
-7	$-e^5 - e^6 - e^7$	10	$1 + e^9 + e^{15}$
-6	$-e^4 + 2e^5$	11	$1 + e^{10} + e^{17}$
-5	$-2e^3$	12	$1 + e^{11} + e^{19} + e^{24} + 3e^{26}$
-4	$-e - e^2$	13	$1 + e^{12} + e^{21} + e^{27}$
-3	$2e$	14	$1 + e^{13} + e^{23} + e^{30}$
-2	-1	15	$1 + e^{14} + e^{25} + e^{33} + e^{38} + 3e^{40}$
-1	$-e^{-1}$	16	$1 + e^{15} + e^{27} + e^{36} + e^{42}$

□

Basing on Theorem 1, it is not difficult to determine the integrals T_{a,b,k_0} and the limit conditions s_{a,b,k_0} corresponding to an (m, n) -symmetric difference with the bases $a = \{a(k)\}, b = \{b(k)\}$:

$$S_{a,b}\{x(k)\} := \{a(k)x(k+m) - b(k)x(k-n)\}, \tag{31}$$

where

$$\bigwedge_{k \in \mathbb{Z}} a(k)b(k) > 0 \quad (\text{cf. [14]}).$$

Namely, by representing the derivative (31) in the form of

$$S_{a,b}\{x(k)\} = \{a(k)\} \left\{ x(k+m) - \frac{b(k)}{a(k)} x(k-n) \right\} = \{a(k)\} S_{b/a}\{x(k)\},$$

we obtain

$$T_{a,b,k_0}\{x(k)\} = T_{b/a,k_0} \left\{ \frac{x(k)}{a(k)} \right\}, \quad s_{a,b,k_0}\{x(k)\} = s_{b/a,k_0}\{x(k)\},$$

where $S_{b/a}$ and $T_{b/a,k_0}, s_{b/a,k_0}$ are operations (14),(24),(23), in which the sequence b needs to be replaced with the sequence b/a .

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MODEL RACHUNKU OPERATORÓW Z RÓŻNICĄ (m, n) -SYMETRYCZNĄ

STRESZCZENIE

W pracy określono model dyskretny nieklasycznego rachunku operatorów Bittnera, w którym pochodna rozumiana jest jako różnica (m, n) -symetryczna $D_{m,n}\{x(k)\} := \{x(k+m) - x(k-n)\}$. Dokonano uogólnienia opracowanego modelu rozważając operację $D_{m,n,b}\{x(k)\} := \{x(k+m) - b(k)x(k-n)\}$.

Słowa kluczowe:

rachunek operatorów, pochodna, pierwotne, warunki graniczne, różnica (m, n) -symetryczna.