

# On the Existence of Continuous Positive Monotonic Solutions of a Self-Reference Quadratic Integral Equation

*Ahmed M.A. EL-Sayed and Hanaa R. Ebead*

**ABSTRACT:** In this work we study the existence of positive monotonic solutions of a self-reference quadratic integral equation in the class of continuous real valued functions. The continuous dependence of the unique solution will be proved. Some examples will be given.

*AMS Subject Classification:* 47H10, 46T20, 39B22.

*Keywords and Phrases:* Self-reference; Quadratic integral equation; Existence of solutions; Uniqueness of solution; Continuous dependence; Schauder fixed point theorem.

## 1. Introduction

Most papers of differential and integral equations with deviating arguments introduce the deviation of the arguments only on the time itself, however, the case of the deviating arguments depend on both the state variable  $x$  and the time  $t$  is important in theory and practice. These kinds of equations play an important role in nonlinear analysis and have many applications (see [1], [7]-[11] and [13]- [16]).

Buică [8] studied the existence, uniqueness and continuous dependence of the solution of the integral equation

$$x(t) = x_0 + \int_a^t f(s, x(x(s)))ds$$

corresponding to the initial value problem

$$\frac{d}{dt}x(t) = f(t, x(x(t))), \quad t \in (a, b], \quad x(a) = x_0$$

where  $f \in C([a, b] \times [a, b])$  and Lipschitz continuous in the second argument. Here we relax the assumptions and generalize the results of [8] for the self-reference quadratic integral equation

$$x(t) = a(t) + \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds + \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds, \quad t \in [0, T]. \quad (1)$$

Quadratic integral equations have been studied by some authors, see for examples [2]-[6] and [9] and references therein.

Let  $C[0, T]$  be the Banach space consisting of all functions which are defined and continuous on the interval  $[0, T]$ . Our aim in this paper is to study the existence of continuous positive monotonic solutions  $x \in C[0, T]$  of the self-reference quadratic integral equation (1). The uniqueness of the solution will be studied also. Moreover we prove that the unique solution of (1) depends continuously on the the functions  $a$ ,  $f_1$  and  $f_2$ .

## 2. Existence of solution

Consider the quadratic integral equation (1) under the following assumptions:

(i)  $a: [0, T] \rightarrow R^+$  and there exists a positive constant  $a$  such that

$$|a(t_2) - a(t_1)| \leq a|t_2 - t_1|, \quad t_1, t_2 \in [0, T].$$

(ii)  $f_i : [0, T] \times [0, T] \rightarrow R^+$  satisfies Carathéodory condition, i.e.  $f_i$  are measurable in  $t$  for all  $x \in C[0, T]$  and continuous in  $x$  for almost all  $t \in [0, T]$ ,  $i = 1, 2$ .

(iii) There exist two constants  $b_1, b_2 \geq 0$  and two bounded measurable functions  $m_i : [0, T] \rightarrow R$ ,  $|m_i(t)| \leq c_i$  such that

$$|f_i(t, x)| \leq |m_i(t)| + b_i|x|, \quad i = 1, 2.$$

(iv)  $\phi_i : [0, T] \rightarrow [0, T]$  such that  $\phi_i(0) = 0$  and

$$|\phi_i(t) - \phi_i(s)| \leq |t - s|, \quad i = 1, 2.$$

This assumption implies that  $\phi_i(t) \leq t$ ,  $i = 1, 2$  and  $x(0) = a(0)$ .

(v)  $LT + |a(0)| \leq T$  and  $L = a + 2M_1M_2T < 1$  where

$$M_1 = c_1 + b_1T, \quad M_2 = c_2 + b_2T.$$

Define the set  $S_L$  by

$$S_L = \{x \in C[0, T] : |x(t) - x(s)| \leq L|t - s|\} \subset C[0, T].$$

It clear that  $S_L$  is nonempty, closed, bounded and convex subset of  $C[0, T]$ .

Now we can prove the following existence theorem

**Theorem 1.** *Let the assumptions (i) – (v) be satisfied, then the self-reference quadratic integral equation (1) has at least one positive solution  $x \in S_L \subset C[0, T]$ .*

**Proof.** Define the operator  $F$  associated with equation (1) by

$$Fx(t) = a(t) + \int_0^{\phi_1(t)} f_1(s, x(x(s)))ds \int_0^{\phi_2(t)} f_2(s, x(x(s)))ds, \quad t \in [0, T].$$

Let  $x \in S_L \subset C[0, T]$ ,  $t \in [0, T]$ . Then, from our assumptions we have

$$\begin{aligned} |Fx(t)| &= \left| a(t) + \int_0^{\phi_1(t)} f_1(s, x(x(s)))ds \int_0^{\phi_2(t)} f_2(s, x(x(s)))ds \right| \\ &\leq |a(t)| + \int_0^{\phi_1(t)} |f_1(s, x(x(s)))|ds \int_0^{\phi_2(t)} |f_2(s, x(x(s)))|ds \\ &\leq |a(t)| + \int_0^{\phi_1(t)} \{|m_1(s)| + b_1|x(x(s))|\}ds \int_0^{\phi_2(t)} \{|m_2(s)| + b_2|x(x(s))|\}ds \\ &\leq |a(t)| + [c_1\phi_1(t) + b_1 \int_0^{\phi_1(t)} \{L|x(s)| + |x(0)|\}ds] \\ &\quad [c_2\phi_2(t) + b_2 \int_0^{\phi_2(t)} \{L|x(s)| + |x(0)|\}ds] \\ &\leq |a(t)| + [c_1T + b_1(LT + |a(0)|)\phi_1(t)] [c_2T + b_2(LT + |a(0)|)\phi_2(t)] \\ &\leq |a(t)| + [c_1 + b_1T] [c_2 + b_2T]T^2 \\ &\leq |a(t)| + M_1M_2T^2 \leq aT + |a(0)| + M_1M_2T^2 \\ &< LT + |a(0)| \leq T. \end{aligned}$$

This proves that the class  $\{Fx\}$  is uniformly bounded.

Now let  $x \in S_L$  and  $t_1, t_2 \in [0, T]$  such that  $t_1 < t_2$  and  $|t_2 - t_1| < \delta$ , then

$$\begin{aligned} |Fx(t_2) - Fx(t_1)| &= \left| a(t_2) + \int_0^{\phi_1(t_2)} f_1(s, x(x(s)))ds \int_0^{\phi_2(t_2)} f_2(s, x(x(s)))ds \right. \\ &\quad \left. - a(t_1) - \int_0^{\phi_1(t_1)} f_1(s, x(x(s)))ds \int_0^{\phi_2(t_1)} f_2(s, x(x(s)))ds \right| \\ &= |a(t_2) - a(t_1)| \\ &\quad + \left| \int_0^{\phi_1(t_2)} f_1(s, x(x(s)))ds \int_0^{\phi_2(t_2)} f_2(s, x(x(s)))ds \right. \\ &\quad \left. - \int_0^{\phi_1(t_2)} f_1(s, x(x(s)))ds \int_0^{\phi_2(t_1)} f_2(s, x(x(s)))ds \right. \\ &\quad \left. + \int_0^{\phi_1(t_2)} f_1(s, x(x(s)))ds \int_0^{\phi_2(t_1)} f_2(s, x(x(s)))ds \right. \\ &\quad \left. - \int_0^{\phi_1(t_1)} f_1(s, x(x(s)))ds \int_0^{\phi_2(t_1)} f_2(s, x(x(s)))ds \right| \end{aligned}$$

$$\begin{aligned}
&\leq |a(t_2) - a(t_1)| \\
&+ \left| \int_0^{\phi_1(t_2)} f_1(s, x(x(s))) ds \left[ \int_0^{\phi_2(t_2)} f_2(s, x(x(s))) ds - \int_0^{\phi_2(t_1)} f_2(s, x(x(s))) ds \right] \right| \\
&+ \left| \int_0^{\phi_2(t_1)} f_2(s, x(x(s))) ds \left[ \int_0^{\phi_1(t_2)} f_1(s, x(x(s))) ds - \int_0^{\phi_1(t_1)} f_1(s, x(x(s))) ds \right] \right| \\
&\leq |a(t_2) - a(t_1)| \\
&+ \int_0^{\phi_1(t_2)} |f_1(s, x(x(s)))| ds \left| \int_{\phi_2(t_1)}^{\phi_2(t_2)} f_2(s, x(x(s))) ds \right| \\
&+ \int_0^{\phi_2(t_1)} |f_2(s, x(x(s)))| ds \left| \int_{\phi_1(t_1)}^{\phi_1(t_2)} f_1(s, x(x(s))) ds \right| \\
&\leq a |t_2 - t_1| \\
&+ \int_0^{\phi_1(t_2)} \{|m_1(s)| + b_1|x(x(s))|\} ds \left( \left| \int_{\phi_2(t_1)}^{\phi_2(t_2)} \{|m_2(s)| + b_2|x(x(s))|\} ds \right| \right) \\
&+ \left( \int_0^{\phi_2(t_1)} \{|m_2(s)| + b_2|x(x(s))|\} ds \right) \left( \left| \int_{\phi_1(t_1)}^{\phi_1(t_2)} \{|m_1(s)| + b_1|x(x(s))|\} ds \right| \right) \\
&\leq a |t_2 - t_1| \\
&+ \left[ c_1 \phi_1(t_2) + b_1 \int_0^{\phi_1(t_2)} \{L|x(s)| + |x(0)|\} ds \right] \\
&\quad \left[ c_2 |\phi_2(t_2) - \phi_2(t_1)| + b_2 \left| \int_{\phi_2(t_1)}^{\phi_2(t_2)} \{L|x(s)| + |x(0)|\} ds \right| \right] \\
&+ \left[ c_2 \phi_2(t_1) + b_2 \int_0^{\phi_2(t_1)} \{L|x(s)| + |x(0)|\} ds \right] \\
&\quad \left[ c_1 |\phi_1(t_2) - \phi_1(t_1)| + b_1 \left| \int_{\phi_1(t_1)}^{\phi_1(t_2)} \{L|x(s)| + |x(0)|\} ds \right| \right] \\
&\leq a |t_2 - t_1| \\
&+ \left[ c_1 + b_1 \{L T + |a(0)|\} \right] \left[ c_2 + b_2 \{L T + |a(0)|\} \right] \phi_1(t_2) |\phi_2(t_2) - \phi_2(t_1)| \\
&+ \left[ c_2 + b_2 \{L T + |a(0)|\} \right] \left[ c_1 + b_1 \{L T + |a(0)|\} \right] \phi_2(t_1) |\phi_1(t_2) - \phi_1(t_1)| \\
&\leq a |t_2 - t_1| \\
&+ \left[ c_1 + b_1 \{L T + |a(0)|\} \right] \left[ c_2 + b_2 \{L T + |a(0)|\} \right] T |t_2 - t_1| \\
&+ \left[ c_2 + b_2 \{L T + |a(0)|\} \right] \left[ c_1 + b_1 \{L T + |a(0)|\} \right] T |t_2 - t_1| \\
&\leq a |t_2 - t_1| + 2T(c_1 + b_1 T)(c_2 + b_2 T)|t_2 - t_1| \\
&= a |t_2 - t_1| + 2TM_1M_2|t_2 - t_1| = L|t_2 - t_1|.
\end{aligned}$$

This proves that  $F : S_L \rightarrow S_L$  and the class  $\{Fx\}$  is equicontinuous.

Now the class of continuous functions  $\{Fx\} \subset S_L \subset C[0, T]$  is uniformly bounded and equicontinuous on  $S_L$ . Hence, applying Arzela-Ascoli Theorem [12] we deduce that the operator  $F$  is compact.

Finally we show that  $F$  is continuous. Let  $\{x_n\} \subset S_L$  such that  $x_n \rightarrow x_0$  on  $[0, T]$ , then

$$\begin{aligned} |f_i(t, x_n(x_n(t)))| &\leq |m_i(t)| + b_i|x_n(x_n(t))| \\ &\leq |m_i(t)| + b_iT, \quad i = 1, 2 \end{aligned}$$

and

$$\begin{aligned} |x_n(x_n(t)) - x_0(x_0(t))| &= |x_n(x_n(t)) - x_n(x_0(t)) + x_n(x_0(t)) - x_0(x_0(t))| \\ &\leq |x_n(x_n(t)) - x_n(x_0(t))| + |x_n(x_0(t)) - x_0(x_0(t))| \\ &\leq L|x_n(t) - x_0(t)| + |x_n(x_0(t)) - x_0(x_0(t))|. \end{aligned}$$

This implies that

$$x_n(x_n(t)) \rightarrow x_0(x_0(t)).$$

From the continuity of  $f_i$ ,  $i = 1, 2$  in the second argument we have

$$f(t, x_n(x_n(t))) \rightarrow f(t, x_0(x_0(t))).$$

Now by Lebesgue's dominated convergence Theorem [12] we obtain

$$\begin{aligned} \lim_{n \rightarrow \infty} (Fx_n)(t) &= \lim_{n \rightarrow \infty} a(t) + \lim_{n \rightarrow \infty} \int_0^{\phi_1(t)} f_1(s, x_n(x_n(s))) ds + \int_0^{\phi_2(t)} f_2(s, x_n(x_n(s))) ds \\ &= a(t) + \int_0^{\phi_1(t)} f_1(s, x_0(x_0(s))) ds + \int_0^{\phi_2(t)} f_2(s, x_0(x_0(s))) ds \\ &= (Fx_0)(t). \end{aligned}$$

Then  $F$  is continuous. Using Schauder fixed point Theorem ([12]), then the operator  $F$  has at least one fixed point  $x \in S_L$ . Consequently there exist at least one solution  $x \in C[0, T]$  of equation (1).

Finally, from our assumptions we have

$$x(t) = a(t) + \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds + \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds > 0, \quad t \in [0, T].$$

and the solution of the quadratic integral equation (1) is positive. □

Now the following two corollaries can be easily proved.

**Corollary 1.** *Let the assumptions of Theorem 1 be satisfied. If the functions  $a$ ,  $\phi_1$  and  $\phi_2$  are nondecreasing, then the solution of the quadratic integral equation (1) is positive and nondecreasing.*

**Corollary 2.** *Let the assumptions of Corollary 1 be satisfied. If, in addition  $\phi_i(t) = t$ ,  $i = 1, 2$ , then the quadratic integral equation*

$$x(t) = a(t) + \int_0^t f_1(s, x(x(s))) ds + \int_0^t f_2(s, x(x(s))) ds, \quad t \in [0, T] \quad (2)$$

has at least one positive and nondecreasing solution  $x \in C[0, T]$ .

**Example 1.** Consider the following quadratic integral equation

$$\begin{aligned} x(t) = & \left( \frac{1}{4} + \frac{1}{8}t \right) + \int_0^{\beta_1 t} \left( \frac{1}{3} s^3 e^{-s^2} + \frac{\ln(1 + |x(x(s))|)}{4 + s^2} \right) ds \\ & + \int_0^{\beta_2 t^\zeta} \left( \frac{1}{12} |\cos(3(s+1))| + \frac{3}{24} |x(x(s))| \right) ds, \end{aligned} \quad (3)$$

where  $t \in [0, 1]$ ,  $\beta_1 \in (0, 1]$ ,  $\zeta > 1$  and  $\beta_2 \zeta < 1$ .

Here we have

$$f_1(t, x(x(t))) = \frac{1}{3} t^3 e^{-t^2} + \frac{\ln(1 + |x(x(t))|)}{4 + t^2},$$

$$|f_1(t, x(x(t)))| \leq \frac{1}{3} t^3 e^{-t^2} + \frac{1}{4} |x(x(t))| \quad \text{and} \quad m_1(t) = \frac{1}{3} t^3 e^{-t^2},$$

$$f_2(t, x(x(t))) = \frac{1}{12} \cos(3(t+1)) + \frac{3}{24} |x(x(t))|,$$

$$|f_2(t, x(x(t)))| = \frac{1}{12} |\cos(3(t+1))| + \frac{3}{24} |x(x(t))| \quad \text{and} \quad m_2(t) = \frac{1}{12} |\cos(3(t+1))|.$$

Also we have  $\phi_1(t) = \beta_1 t$ ,  $\phi_2(t) = \beta_2 t^\zeta$ ,  $a(t) = \frac{1}{4} + \frac{1}{8}t$ ,  $a = \frac{1}{8}$ ,  $b_1 = \frac{1}{4}$ ,  $b_2 = \frac{3}{24}$ ,  $c_1 = \frac{1}{3}$ ,  $c_2 = \frac{1}{12}$ , and  $M_1 = \frac{7}{12}$ ,  $M_2 = \frac{5}{24}$ .

Hence  $L \simeq 0.368 < 1$  and  $L T + |a(0)| = 0.618 \leq T = 1$ .

Now it is clear that all assumptions of Theorem 1 are satisfied, then equation (3) has at least one solution.

### 3. Uniqueness of the solution

In this section we study the uniqueness of the solution  $x \in C[0, T]$  of the quadratic integral equation (1).

Consider the following assumption

(ii\*)  $f_i : [0, T] \times [0, T] \rightarrow R^+$  are measurable in  $t$  for all  $x \in C[0, T]$ , satisfy the Lipschitz condition

$$|f_i(t, x) - f_i(t, y)| \leq b_i |x - y| \quad i = 1, 2$$

$$|f_i(t, 0)| \leq c_i, \quad \forall t \in [0, T].$$

**Theorem 2.** Let the assumptions (i), (iv), (v) and (ii\*) be satisfied, if

$$(\gamma_1 b_2 + \gamma_2 b_1) T (L + 1) < 1,$$

where  $\gamma_i = (c_i + b_i T)T$ ,  $i = 1, 2$ , then equation (1) has a unique solution  $x \in C[0, T]$ .

**Proof.** From assumption (ii\*) we can deduced that

$$|f_i(t, x)| \leq b_i |x| + |f_i(t, 0)| \leq b_i |x| + c_i, \quad i = 1, 2,$$

then all assumptions of Theorem 1 are satisfied and the integral equation (1) has at least one solution. Let  $x, y$  be two solutions of (1), then obtain

$$\begin{aligned} |x(t) - y(t)| &= \left| a(t) + \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds \right. \\ &\quad \left. - a(t) - \int_0^{\phi_1(t)} f_1(s, y(y(s))) ds \int_0^{\phi_2(t)} f_2(s, y(y(s))) ds \right| \\ &= \left| \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds \left[ \int_0^{\phi_2(t)} \{f_2(s, x(x(s))) - f_2(s, y(y(s)))\} ds \right] \right. \\ &\quad \left. + \int_0^{\phi_2(t)} f_2(s, y(y(s))) ds \left[ \int_0^{\phi_1(t)} \{f_1(s, x(x(s))) - f_1(s, y(y(s)))\} ds \right] \right| \\ &\leq \int_0^{\phi_1(t)} |f_1(s, x(x(s)))| ds \int_0^{\phi_2(t)} |f_2(s, x(x(s))) - f_2(s, y(y(s)))| ds \\ &\quad + \int_0^{\phi_2(t)} |f_2(s, y(y(s)))| ds \int_0^{\phi_1(t)} |f_1(s, x(x(s))) - f_1(s, y(y(s)))| ds \\ &\leq \int_0^{\phi_1(t)} |f_1(s, x(x(s)))| ds b_2 \int_0^{\phi_2(t)} |x(x(s)) - y(y(s))| ds \\ &\quad + \int_0^{\phi_2(t)} |f_2(s, y(y(s)))| ds b_1 \int_0^{\phi_1(t)} |x(x(s)) - y(y(s))| ds, \end{aligned} \quad (4)$$

$$\begin{aligned} \int_0^{\phi_i(t)} |f_i(s, x(x(s)))| ds &\leq b_i \int_0^{\phi_i(t)} |x(x(s))| ds + \int_0^{\phi_i(t)} |f_i(t, 0)| ds \\ &\leq b_i \int_0^{\phi_i(t)} \{L T + |x(0)|\} ds + c_i \phi_i(t) \\ &\leq b_i \phi_i(t) T + c_i \phi_i(t) \\ &\leq (b_i T + c_i) T = \gamma_i, \quad i = 1, 2 \end{aligned} \quad (5)$$

and

$$\begin{aligned} |x(x(s)) - y(y(s))| &= |x(x(s)) - y(y(s)) + x(y(s)) - x(y(s))| \\ &\leq |x(x(s)) - x(y(s))| + |x(y(s)) - y(y(s))| \\ &\leq L|x(s) - y(s)| + |x(y(s)) - y(y(s))|. \end{aligned} \quad (6)$$

Substituting (5) and (6) in (4) we can get

$$\begin{aligned}
|x(t) - y(t)| &\leq \gamma_1 b_2 \int_0^{\phi_2(t)} \{L|x(s) - y(s)| + |x(y(s)) - y(y(s))|\} ds \\
&+ \gamma_2 b_1 \int_0^{\phi_1(t)} \{L|x(s) - y(s)| + |x(y(s)) - y(y(s))|\} ds \\
&\leq \gamma_1 b_2 \|x - y\| (L + 1) \phi_2(t) + \gamma_2 b_1 \|x - y\| (L + 1) \phi_1(t) \\
&\leq (\gamma_1 b_2 + \gamma_2 b_1) T (L + 1) \|x - y\|
\end{aligned}$$

and

$$[1 - (\gamma_1 b_2 + \gamma_2 b_1) T (L + 1)] \|x - y\| \leq 0,$$

then  $x(t) = y(t)$ ,  $t \in [0, T]$  and equation (1) has a unique solution  $x \in C[0, T]$ .  $\square$

**Example 2.** Let  $T = 1$ ,  $t \in [0, 1]$  and  $\alpha, \beta, \mu, \rho \in (0, 1]$  are parameters. Consider the following quadratic integral equation

$$x(t) = \left(\frac{2}{7} + \frac{1}{7}t\right) + \int_0^{\alpha t} \left(\frac{\mu}{8-s} + \frac{1}{14}|x(x(s))|\right) ds \int_0^{\beta t} \left(\frac{\rho}{6} \ln(1+|s|) + \frac{1}{2}|x(x(s))|\right) ds. \quad (7)$$

Here we have

$$\begin{aligned}
f_1(t, x(x(t))) &= \frac{\mu}{8-t} + \frac{1}{14}|x(x(t))|, \\
|f_1(t, x) - f_1(t, y)| &\leq \frac{1}{14}|x - y|, \\
f_2(t, x(x(t))) &= \frac{\rho}{6} \ln(1+|t|) + \frac{1}{2}|x(x(t))|,
\end{aligned}$$

and

$$|f_2(t, x) - f_2(t, y)| \leq \frac{1}{2}|x - y|.$$

Also,  $m_1(t) = \frac{\mu}{8-t}$ ,  $c_1 = \frac{1}{7}$ ,  $m_2(t) = \frac{\rho}{6} \ln(1+|t|)$ ,  $c_2 = \frac{1}{6}$ ,  $\phi_1(t) = \alpha t$ ,  $\phi_2(t) = \beta t$  and  $a(t) = \frac{2}{7} + \frac{1}{7}t$ , then we obtain  $a = \frac{1}{7}$ ,  $b_1 = \frac{1}{14}$ ,  $b_2 = \frac{1}{2}$ ,  $M_1 = \frac{3}{14}$  and  $M_2 = \frac{2}{3}$ .

Hence  $L = \frac{3}{7} < 1$  and  $L T + |a(0)| = \frac{5}{7} \leq T = 1$ .

Moreover we have  $\gamma_1 = \frac{3}{14}$ ,  $\gamma_2 = \frac{2}{3}$  and

$$(\gamma_1 b_2 + \gamma_2 b_1) T (L + 1) \simeq 0.2210 < 1.$$

Now all assumptions of Theorem 2 are satisfied, then equation (7) has a unique solution.

## 4. Continuous dependence

In this section we prove that the solution of equation (1) depends continuously on the functions  $a$ ,  $f_1, f_2$ .



### 4.1. Continuous dependence on the function $a$

**Definition 1.** The solution of the integral equation (1) depends continuously on the function  $a$  if  $\forall \epsilon > 0 \exists \delta(\epsilon) > 0$  such that

$$|a(t) - a^*(t)| \leq \delta \quad \Rightarrow \quad \|x - x^*\| \leq \epsilon \quad (8)$$

where  $x^*$  is the unique solution of equation

$$x^*(t) = a^*(t) + \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds + \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds, \quad t \in [0, T]. \quad (9)$$

**Theorem 3.** Let the assumptions of Theorem 2 be satisfied, assume that  $|a(t) - a^*(t)| \leq \delta$ , then the solution of (1) depends continuously on the function  $a$ .

**Proof.** Let  $|a(t) - a^*(t)| \leq \delta$ , then we can get

$$\begin{aligned} |x(t) - x^*(t)| &= \left| a(t) + \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds + \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds \right. \\ &\quad \left. - a^*(t) - \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds - \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds \right| \\ &= |a(t) - a^*(t) + \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds \\ &\quad \times \left[ \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds - \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds \right] \\ &\quad + \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds \\ &\quad \times \left[ \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds - \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds \right]| \\ &\leq |a(t) - a^*(t)| \\ &\quad + \int_0^{\phi_1(t)} |f_1(s, x(x(s)))| ds \int_0^{\phi_2(t)} |f_2(s, x(x(s))) - f_2(s, x^*(x^*(s)))| ds \\ &\quad + \int_0^{\phi_2(t)} |f_2(s, x^*(x^*(s)))| ds \int_0^{\phi_1(t)} |f_1(s, x(x(s))) - f_1(s, x^*(x^*(s)))| ds \\ &\leq \delta + \int_0^{\phi_1(t)} (c_1 + b_1|x(x(s))|) ds + b_2 \int_0^{\phi_2(t)} |x(x(s)) - x^*(x^*(s))| ds \\ &\quad + \int_0^{\phi_2(t)} (c_2 + b_2|x^*(x^*(s))|) ds + b_1 \int_0^{\phi_1(t)} |x(x(s)) - x^*(x^*(s))| ds \end{aligned}$$

$$\begin{aligned}
&\leq \delta + M_1 \phi_1(t) b_2 \int_0^{\phi_2(t)} |x(x(s)) - x^*(x^*(s))| ds \\
&+ M_2 \phi_2(t) b_1 \int_0^{\phi_1(t)} |x(x(s)) - x^*(x^*(s))| ds \\
&\leq \delta + M_1 T b_2 (L+1) \|x - x^*\| \phi_2(t) \\
&+ M_2 T b_1 (L+1) \|x - x^*\| \phi_1(t) \\
&\leq \delta + (\gamma_1 b_2 + \gamma_2 b_1)(L+1) T \|x - x^*\|,
\end{aligned}$$

$$\|x - x^*\| (1 - (\gamma_1 b_2 + \gamma_2 b_1)(L+1) T) \leq \delta$$

and

$$\|x - x^*\| \leq \frac{\delta}{1 - (\gamma_1 b_2 + \gamma_2 b_1)(L+1)T} = \epsilon.$$

## 4.2. Continuous dependence on the functions $f_1$

Here we prove that the solution of the equation (1) depends continuously on the function  $f_1$ .

**Definition 2.** The solution of the integral equation (1) depends continuously on the function  $f_1$  if  $\forall \epsilon > 0 \exists \delta(\epsilon) > 0$  such that

$$|f_1(t, x(x(t))) - f_1^*(t, x(x(t)))| \leq \delta \Rightarrow \|x - x^*\| \leq \epsilon \quad (10)$$

where  $x^*$  is the unique solution of equation

$$x^*(t) = a(t) + \int_0^{\phi_1(t)} f_1^*(s, x^*(x^*(s))) ds \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds, \quad t \in [0, T].$$

**Theorem 4.** Let the assumptions of Theorem 2 be satisfied, assume that

$$|f_1(t, x(x(t))) - f_1^*(t, x(x(t)))| \leq \delta,$$

then the solution of (1) depends continuously on the functions  $f_1$ .

**Proof.** Let  $|f_1(t, x(x(t))) - f_1^*(t, x(x(t)))| \leq \delta$ , then we obtain

$$\begin{aligned}
|x(t) - x^*(t)| &= \left| a(t) + \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds \right. \\
&\quad \left. - a(t) - \int_0^{\phi_1(t)} f_1^*(s, x^*(x^*(s))) ds \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds \right|
\end{aligned}$$

$$\begin{aligned}
 &= \left| \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds \right. \\
 &- \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds \\
 &+ \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds \\
 &- \left. \int_0^{\phi_1(t)} f_1^*(s, x^*(x^*(s))) ds \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds \right| \\
 &= \left| \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds \right. \\
 &\times \left[ \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds - \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds \right] \\
 &+ \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds \\
 &- \int_0^{\phi_1(t)} f_1^*(s, x^*(x^*(s))) ds \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds \\
 &+ \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds \\
 &- \left. \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds \right| \\
 &= \left| \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds \left[ \int_0^{\phi_1(t)} f_1(s, x(x(s))) ds - \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds \right] \right. \\
 &+ \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds \left[ \int_0^{\phi_2(t)} f_2(s, x(x(s))) ds - \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds \right] \\
 &+ \int_0^{\phi_2(t)} f_2(s, x^*(x^*(s))) ds \left[ \int_0^{\phi_1(t)} f_1(s, x^*(x^*(s))) ds - \int_0^{\phi_1(t)} f_1^*(s, x^*(x^*(s))) ds \right] \left. \right| \\
 &\leq \int_0^{\phi_2(t)} |f_2(s, x(x(s)))| ds \int_0^{\phi_1(t)} |f_1(s, x(x(s))) - f_1(s, x^*(x^*(s)))| ds \\
 &+ \int_0^{\phi_1(t)} |f_1(s, x^*(x^*(s)))| ds \int_0^{\phi_2(t)} |f_2(s, x(x(s))) - f_2(s, x^*(x^*(s)))| ds \\
 &+ \int_0^{\phi_2(t)} |f_2(s, x^*(x^*(s)))| ds \int_0^{\phi_1(t)} |f_1(s, x^*(x^*(s))) - f_1^*(s, x^*(x^*(s)))| ds \\
 &\leq \int_0^{\phi_2(t)} |f_2(s, x(x(s)))| ds \int_0^{\phi_1(t)} b_1 |x(x(s)) - x^*(x^*(s))| ds \\
 &+ \int_0^{\phi_1(t)} |f_1(s, x^*(x^*(s)))| ds \int_0^{\phi_2(t)} b_2 |x(x(s)) - x^*(x^*(s))| ds \\
 &+ \int_0^{\phi_2(t)} |f_2(s, x^*(x^*(s)))| ds \int_0^{\phi_1(t)} |f_1(s, x^*(x^*(s))) - f_1^*(s, x^*(x^*(s)))| ds.
 \end{aligned}$$

Using (5) and (6) we obtain

$$|x(t) - x^*(t)| \leq \gamma_2 b_1 (L+1)T \|x - x^*\| + \gamma_1 b_2 (L+1)T \|x - x^*\| + \gamma_2 T \delta,$$

$$\|x - x^*\| [1 - (\gamma_2 b_1 + \gamma_1 b_2)(L+1)T] \leq \gamma_2 T \delta$$

and

$$\|x - x^*\| \leq \frac{\gamma_2 T \delta}{1 - (\gamma_2 b_1 + \gamma_1 b_2)(L+1)T} = \epsilon.$$

□

**Corollary 3.** *Let the assumptions of Theorem 4 be satisfied. In Example 2 if  $\mu$  changed to  $\mu^*$ , then the solution of equation (7) depends continuously on  $\mu$  (the function  $f_1$ ).*

### 4.3. Continuous dependence on the functions $f_2$

By the same way, as in Theorem 4 we can prove that the solution of equation (1) dependence continuously on the function  $f_2$ .

**Theorem 5.** *Let the assumptions of Theorem 2 be satisfied, assume that*

$$|f_2(t, x(x(t))) - f_2^*(t, x(x(t)))| \leq \delta,$$

*then the solution of (1) depends continuously on the functions  $f_2$ .*

**Corollary 4.** *Let the assumptions of Theorem 5 be satisfied. In Example 2 if  $\rho$  changed to  $\rho^*$ , then the solution of equation (7) depends continuously on  $\rho$  (the function  $f_2$ ).*

## References

- [1] P.K. Anh, L.T. Nguyen, N.M. Tuan, *Solutions to systems of partial differential equations with weighted self-reference and heredity*, Electronic Journal of Differential Equations 2012 (117) (2012) 1–14.
- [2] J. Banaś, M. Lecko, W.G. El-Sayed, *Existence theorems for some quadratic integral equations*, Journal of Mathematical Analysis and Applications 222 (1) (1998) 276–285.
- [3] J. Banaś, J. Caballero, J.R. Martin, K. Sadarangani, *Monotonic solutions of a class of quadratic integral equations of Volterra type*, Computers and Mathematics with Applications 49 (5-6) (2005) 943–952.

- [4] J. Banaś, J.R. Martin, K. Sadarangani, *On solutions of a quadratic integral equation of Hammerstein type*, Mathematical and Computer Modelling 43 (2006) 97–104.
- [5] J. Banaś, A. Martinon, *Monotonic solutions of a quadratic integral equation of Volterra type*, Computers and Mathematics with Applications 47 (2-3) (2010) 271–279.
- [6] J. Banaś, B. Rzepka, *Nondecreasing solutions of a quadratic singular Volterra integral equation*, Mathematical and Computer Modelling 49 (5-6) (2009) 488–496.
- [7] V. Berinde, *Existence and approximation of solutions of some first order iterative differential equations*, Miskolc Mathematical Notes 11 (1) (2010) 13–26.
- [8] A. Buică, *Existence and continuous dependence of solutions of some functional-differential equations*, Seminar on Fixed Point Theory 3 (1) (1995) 1–14, a publication of the Seminar on Fixed Point Theory Cluj-Napoca.
- [9] A.M.A. El-Sayed, H.H.G. Hashem, *Monotonic positive solution of a nonlinear quadratic functional integral equation*, Applied Mathematics and Computation, 216 (9) (2010) 2576–2580.
- [10] E. Eder, *The functional differential equation  $x'(t) = x(x(t))$* , J. Differential Equations 54 (2) (1984) 390–400.
- [11] C.G. Gal, *Nonlinear abstract differential equations with deviated argument*, Journal of Mathematical Analysis and Applications 333 (2) (2007) 971–983.
- [12] A.N. Kolmogorov, S.V. Fomin, *Elements of the Theory of Functions and Functional Analysis, Metric and Normed Spaces*, Dover, 1990.
- [13] N.T. Lan, E. Pascali, *A two-point boundary value problem for a differential equation with self-reference*, Electronic Journal of Mathematical Analysis and Applications 6 (1) (2018) 25–30.
- [14] M. Miranda, E. Pascali, *On a type of evolution of self-referred and hereditary phenomena*, Aequationes Mathematicae 71 (3) (2006) 253–268.
- [15] N.M. Tuan, L.T. Nguyen, *On solutions of a system of hereditary and self-referred partial-differential equations*, Numerical Algorithms 55 (1) (2010) 101–113.
- [16] U. Van Le, L.T. Nguyen, *Existence of solutions for systems of self-referred and hereditary differential equations*, Electronic Journal of Differential Equations 2008 (51) (2008) 1–7.

**Ahmed M.A. EL-Sayed**email: [amasayed@alexu.edu.eg](mailto:amasayed@alexu.edu.eg)

ORCID: 0000-0001-7092-7950

Faculty of Science

Alexandria University

Alexandria

EGYPT

**Hanaa R. Ebead**email: [HanaaRezqalla@alexu.edu.eg](mailto:HanaaRezqalla@alexu.edu.eg)

ORCID: 0000-0002-6085-3190

Faculty of Science

Alexandria University

Alexandria

EGYPT

*Received 04.04.2020**Accepted 19.09.2020*