

APPLICATION OF HPM TO FIND ANALYTICAL SOLUTION OF COETTE FLOW WITH VARIABLE VISCOSITY

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Abstract: In this paper, the couette flow of fluid with variable viscosity is studied analytically by using Homotopy Perturbation Method (HPM). At first the basic idea of Homotopy Perturbation Method (HPM) is presented. The mathematical formulation and application of HPM to nonlinear problem are presented in section three. In order to check the validity of solution the analytical results are compared with exact ones for various numerical cases. The good agreement between exact method and Homotopy Perturbation Method has been assures us about the solution accuracy.

Key words: Analytical Solution, HPM, Coette Flow, Viscosity

1. INTRODUCTION

Modelling of natural phenomena such as coquette flow and other fluid problems mostly leads to solving nonlinear equations. Except a limited number of these problems, most of them do not have analytical solution. So, the study on the various methods used for solving the nonlinear differential equations is a significant topic for the analysis of engineering problems. In recent years many powerful methods have been presented to construct solutions of Nonlinear Differential Equations such as Variational Iteration Method (VIM) (He, 1999), Homotopy Analysis Method (HAM) (Abasbandy, 2006), Homotopy Perturbation Method (Ghotbi et al., 2011; Jalal et al., 2011; Moghimi et al., 2011; Rashidi et al., 2012; Sharma and Methi, 2010) and Adomian Decomposition Method (Alan and Alkhaled, 2006; Ghosh, 2007; Lesnic, 2005; Pamuk, 2005).

The purpose of this present work is to present approximate analytical solution to a couette flow problem (Aziz and Na, 1984) with variable viscosity by Homotopy perturbation method. In order to investigate the validity and accuracy of results, the obtained results are compared with the exact solution.

2. BASIC IDEA OF HPM

The homotopy perturbation method (HPM) was first proposed by He. The HPM does not depend upon a small parameter in the equation. By the homotopy technique in topology, a homotopy is constructed with an imbedding parameter $p \in [0,1]$, which is considered as a "small parameter".

The HPM was successfully applied to the nonlinear oscillators with discontinuities (He, 2004b) bifurcation of nonlinear problems

(He, 2004a), nonlinear wave equations (He, 2005). In (He, 2004a) comparison of HPM and homotopy analysis method was made, revealing that the former is more powerful than the later.

To illustrate the basic ideas of this method, we consider the following nonlinear differential equation (He, 2004a):

$$A(u) - g(r) = 0, \quad r \in \Omega \quad (1)$$

with boundary conditions:

$$B(u, \partial u / \partial n) = 0, \quad r \in \Gamma \quad (2)$$

where: $A, B, g(r)$ and Γ are a general differential operator, a boundary operator, a known analytical function, and the boundary of domain Ω .

Generally speaking the operator A can be divided into a linear part L and a nonlinear part $N(u)$. Equation (1), therefore, can be rewritten as follows:

$$L(u) + N(u) - g(r) = 0 \quad (3)$$

By the homotopy technique, we construct a homotopy $f(r, p): \Omega \times [0,1] \rightarrow R$ which satisfies:

$$H(f, p) = (1 - p)[L(f) - L(u_0)] + p[A(f) - g(r)] = 0, \quad p \in [0,1], r \in \Omega \quad (4)$$

or

$$H(f, p) = L(f) - L(u_0) + pL(u_0) + p[N(f) - g(r)] = 0 \quad (5)$$

where $p \in [0,1]$ is an imbedding parameter, u_0 is an initial approximation of Equation (1), which satisfies the boundary conditions. Obviously, from Equations (4) and (5) we have:

$$H(v, 0) = L(v) - L(u_0) = 0 \quad (6)$$

$$H(v, 1) = A(v) - g(r) = 0 \quad (7)$$

the changing process of p from zero to unity is just that of $v(r, p)$ from $u_0(r)$ to $u(r)$. In topology, this is called deformation, and $L(v) - L(u_0)$ and $A(u) - f(r)$ are called homotopy.

According to the HPM, we can first use the imbedding parameter p as a "small parameter", and assumed that the solution of Equations (4) and (5) can be written as a power series in p :

$$f = f_0 + pf_1 + p^2f_2 + p^3f_3 + \dots \quad (8)$$

Setting $p = 1$ results in the approximate solution of Equation (3):

$$f = \lim_{p \rightarrow 1} f = f_0 + f_1 + f_2 + \dots \quad (9)$$

The coupling of the perturbation method and the homotopy method is called the homotopy perturbation method (HPM), which has eliminated limitations of the traditional perturbation methods. In the other hand, this technique can take full advantage of the traditional perturbation techniques.

The series (8, 9) are convergent for most cases, however, the convergent rate depends upon the nonlinear operator $N(v)$. The following opinions are suggested by He (He, 2004a):

1. The second derivative of $N(v)$ with respect to v must be small, because the parameter p may be relatively large, i.e. $p \rightarrow 1$.
2. The norm of $L^{-1}(\partial N / \partial v)$ must be smaller than one, in order that the series converges.

3. SOLUTION PROCEDURE

Consider the steady flow of an incompressible Newtonian fluid between two infinite, parallel plates separated by a distance a as shown in Fig. 1. Each plate is maintained at temperature T_0 . The lower plate is stationary while the upper plate moves with a uniform velocity V . The thermal conductivity of the fluid is assumed to be constant, but the viscosity is allowed to vary. The pertinent momentum and energy equations are (Aziz and Na, 1984):

$$\frac{d}{dy}(\mu \frac{du}{dy}) = 0 \quad (10)$$

$$\frac{d^2T}{dy^2} + \frac{\mu}{k} (\frac{du}{dy})^2 = 0 \quad (11)$$

$$y = 0, \quad u = 0, \quad T = T_0 \quad (12)$$

$$y = a, \quad u = V, \quad T = T_0 \quad (13)$$

where: u - axial velocity, T - temperature, μ - viscosity and k - thermal conductivity.

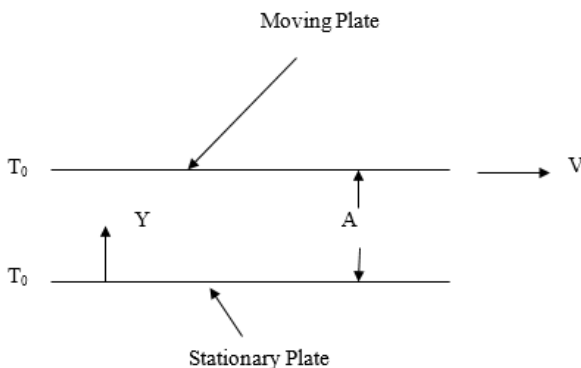


Fig. 1. Plane Coeette Flow

Let the viscosity vary exponentially with temperature according to:

$$\mu = \mu_0 e^{-\alpha(T-T_0)} \quad (14)$$

where: μ_0 is the viscosity at T_0 and α is a constant.

Introduce Equation (14) and the following dimensionless quantities into Equations (10)-(13):

$$\theta = \frac{T-T_0}{T_0}, \quad Y = \frac{y}{a}, \quad U = \frac{u}{V} \quad (15)$$

$$\beta = \alpha T_0, \quad \varepsilon = \frac{\mu_0 V^2}{k T_0}$$

to give:

$$\begin{cases} \frac{d}{dY}(e^{-\beta\theta} \frac{dU}{dY}) = 0 \\ \frac{d^2\theta}{dY^2} + \varepsilon e^{-\beta\theta} (\frac{dU}{dY})^2 = 0, \end{cases} \quad (16)$$

$$\begin{cases} Y = 0, & U = 0, & \theta = 0 \\ Y = 1, & U = 1, & \theta = 0 \end{cases} \quad (17)$$

In this case, the parameter $\mu_0 V^2 / k T_0$ is identified as the perturbation quantity ε . In viscous flow terminology, it is called the Brinkman number, and represents the ratio of viscous heating due to conduction. Thus, if the effect of viscous heating is weak, one may treat ε as small and carry out a perturbation analysis. As shown by Turian and Bird (1963), such an analysis is applicable to flow in a cone-and-plate viscometer.

In order to solve this system with homotopy perturbation method (HPM), we consider:

$$\begin{aligned} U(Y) &= v_1(Y), & \theta(Y) &= v_2(Y) \\ v_{1,0}(Y) &= U_0(Y), & v_{2,0}(Y) &= \theta_0(Y) \end{aligned} \quad (18)$$

$$\begin{aligned} v_1(Y) &= v_{1,0}(Y) + p v_{1,1}(Y) + p^2 v_{1,2}(Y) \\ v_2(Y) &= v_{2,0}(Y) + p v_{2,1}(Y) + p^2 v_{2,2}(Y) \end{aligned} \quad (19)$$

the term $e^{-\beta \theta(Y)}$ must be expanded as follows:

$$e^{-\beta \theta(Y)} = 1 - \beta \theta(Y) + \frac{1}{2} \beta^2 \theta^2(Y) \quad (20)$$

The substitution of Equation (20) into Equation (16) yields:

$$\begin{cases} \left(1 - \beta \theta + \frac{1}{2} \beta^2 \theta^2\right) \frac{d^2 U}{dY^2} + \beta \left(\beta \theta - \frac{1}{2} \beta^2 \theta^2 - 1\right) \frac{dU}{dY} \frac{d\theta}{dY} = 0 \\ \frac{d^2 \theta}{dY^2} + \varepsilon \left(1 - \beta \theta + \frac{1}{2} \beta^2 \theta^2\right) \left(\frac{dU}{dY}\right)^2 = 0 \end{cases} \quad (21)$$

According to the HPM, we must firstly determine the initial approximations for $v_1(Y)$ and $v_2(Y)$. So we construct following system for linear parts:

$$\begin{cases} \frac{d^2 U_0}{dY^2} = 0 \\ \frac{d^2 \theta_0}{dY^2} = 0 \end{cases} \quad (22)$$

with following conditions:

$$\begin{cases} Y = 0, & U_0(Y) = 0, & \theta_0(Y) = 0 \\ Y = 1, & U_0(Y) = 1, & \theta_0(Y) = 0 \end{cases} \quad (23)$$

The solution of Equation (21) is as follows:

$$\begin{cases} U_0(Y) = v_{1,0}(Y) = Y \\ \theta_0(Y) = v_{2,0}(Y) = 0 \end{cases} \quad (24)$$

A homotopy for the system of Equation (21) can be constructed as follows:

$$\begin{cases} (1-p)\left(\frac{d^2v_1}{dY^2} - \frac{d^2v_{1,0}}{dY^2}\right) + \\ p\left(\left(1 - \beta v_2 + \frac{1}{2}\beta^2 v_2^2\right)\frac{d^2v_1}{dY^2}\right) + \beta\left(\beta v_2 - \frac{1}{2}\beta^2 v_2^2 - 1\right)\frac{dv_1}{dY}\frac{dv_2}{dY} = 0 \\ (1-p)\left(\frac{d^2v_2}{dY^2} - \frac{d^2v_{2,0}}{dY^2}\right) + \\ p\left(\frac{d^2v_2}{dY^2} + \left(1 - \beta v_2 + \frac{1}{2}\beta^2 v_2^2\right)\varepsilon\left(\frac{dv_1}{dY}\right)\right) = 0 \end{cases} \quad (25)$$

The substitution of Equation (24) into Equation (25) yields:

$$\begin{cases} (1-p)\left(\frac{d^2v_1}{dY^2}\right) + \\ p\left(\left(1 - \beta v_2 + \frac{1}{2}\beta^2 v_2^2\right)\frac{d^2v_1}{dY^2} + \beta\left(\beta v_2 - \frac{1}{2}\beta^2 v_2^2 - 1\right)\frac{dv_1}{dY}\frac{dv_2}{dY}\right) = 0 \\ (1-p)\left(\frac{d^2v_2}{dY^2}\right) + \\ p\left(\frac{d^2v_2}{dY^2} + \left(1 - \beta v_2 + \frac{1}{2}\beta^2 v_2^2\right)\varepsilon\left(\frac{dv_1}{dY}\right)\right) = 0 \end{cases} \quad (26)$$

The substitution of Equation (19) into Equation (26) and collect the result up to p^2 yields:

$$\begin{cases} \left(-\beta\frac{dv_{2,1}}{dY} + \frac{d^2v_{1,2}}{dY^2}\right)p^2 + \frac{d^2v_{1,1}}{dY^2}p = 0 \\ \left(\frac{d^2v_{2,2}}{dY^2} - \varepsilon\beta v_{2,1}\right)p^2 + \left(\frac{d^2v_{2,1}}{dY^2} + \varepsilon\right)p = 0 \end{cases} \quad (27)$$

then we must equalize the coefficients of p and p^2 in Equation (27) with zero:

$$\begin{cases} \frac{d^2v_{1,1}}{dY^2} = 0 \\ \frac{d^2v_{2,1}}{dY^2} + \varepsilon = 0 \\ -\beta\frac{dv_{2,1}}{dY} + \frac{d^2v_{1,2}}{dY^2} = 0 \\ \frac{d^2v_{2,2}}{dY^2} - \varepsilon\beta v_{2,1} = 0 \end{cases} \quad (28)$$

with following conditions:

$$v_{i,j}(0) = v_{i,j}(1) = 0, \quad i, j = 1, 2 \quad (29)$$

therefore the results are as follows:

$$\begin{cases} v_{1,1}(Y) = 0 \\ v_{1,2}(Y) = -\frac{1}{6}\beta\varepsilon Y^3 + \frac{1}{4}\beta\varepsilon Y^2 - \frac{1}{12}\beta\varepsilon Y \\ v_{2,1}(Y) = -\frac{1}{2}\varepsilon Y^2 + \frac{1}{2}\varepsilon Y \\ v_{2,2}(Y) = -\frac{1}{24}\beta\varepsilon^2 Y^4 + \frac{1}{12}\beta\varepsilon^2 Y^3 - \frac{1}{24}\beta\varepsilon^2 Y \end{cases} \quad (30)$$

According to the HPM, we can conclude:

$$\begin{aligned} U(Y) &= \lim_{p \rightarrow 1} (v_{1,0}(Y) + pv_{1,1}(Y) + p^2v_{1,2}(Y)) \\ \theta(Y) &= \lim_{p \rightarrow 1} (v_{2,0}(Y) + pv_{2,1}(Y) + p^2v_{2,2}(Y)) \end{aligned} \quad (31)$$

The substitution of Equations (24) and (30) into Equation (31) yields:

$$U(Y) = Y - \frac{1}{2}\beta\varepsilon\left(\frac{1}{3}Y^3 - \frac{1}{2}Y^2\right) - \frac{1}{12}\beta\varepsilon Y \quad (32)$$

$$\begin{aligned} \theta(Y) &= -\frac{1}{2}\varepsilon Y^2 + \frac{1}{2}\varepsilon Y - \frac{1}{2}\beta\varepsilon^2\left(\frac{1}{12}Y^4 - \frac{1}{6}Y^3\right) \\ &\quad - \frac{1}{24}\varepsilon^2\beta Y \end{aligned} \quad (33)$$

We avoid listing the other components. The forgoing homotopy perturbation solution may be compared with the exact

solution (Turian and Bird, 1963) which is given by:

$$e^{\beta\theta} = \left(1 + \frac{\varepsilon\beta}{8}\right) \operatorname{sech}^2 \left[(2Y - 1) \sinh^{-1} \left(\frac{\varepsilon\beta}{8} \right)^{1/2} \right] \quad (34)$$

$$U = \frac{1}{2} \left\{ \left(1 + \frac{8}{\varepsilon\beta}\right)^{1/2} \tanh \left[(2Y - 1) \sinh^{-1} \left(\frac{\varepsilon\beta}{8} \right)^{1/2} \right] + 1 \right\} \quad (35)$$

4. RESULTS AND DISCUSSIONS

In previous section, analytical investigation of plane couette flow with variable viscosity is presented. In this section, we will present the obtained results. As it can be illustrated in Fig. 2 the comparison is made between HPM solution and exact ones for $\beta = 1$ and a range of values of ε . In Fig. 3, the deviations with the exact solutions have been plotted for $\beta = 1$ and a range of values of ε .

According to Fig. 3 effect of the Brinkman number on temperature profile is considerable. The increasing of Brinkman number cause higher peak in temperature profile.

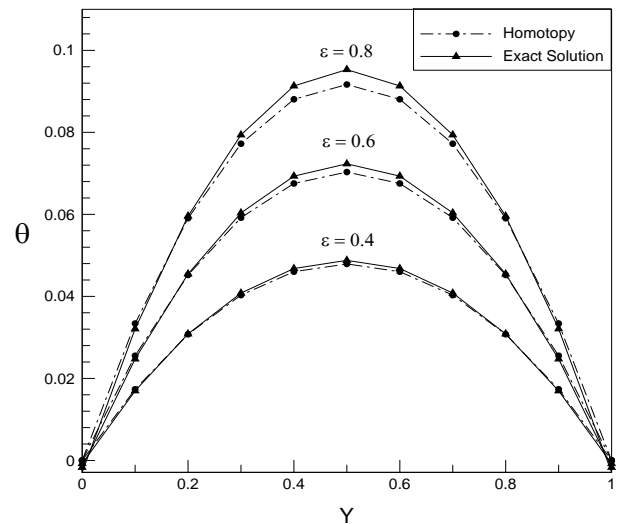


Fig. 2. Temperature distribution in plane couette flow, $\beta = 1$

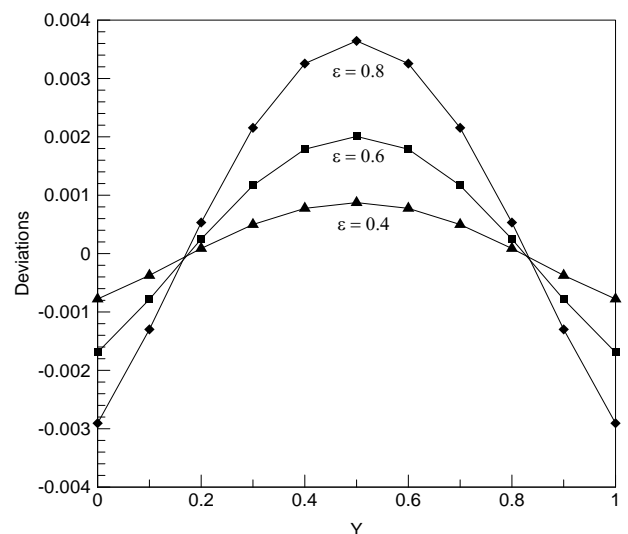


Fig. 3. Deviations of the HPM (2-term expansion) results with exact solution, with fixed value $\beta = 1$

Tab. 1 shows the effect of increasing the number of HPM terms on obtained temperature values for a range of values of ε when $Y = 0.5, \beta = 1$.

Tab. 1. Comparison between Exact solutions and Analytical results for various term expansions of HPM and different value of ε in case $Y = 0.5, \beta = 1$

ε	HPM (3-term expansion)	HPM (4-term expansion)	Exact
0.05	0.0061514	0.0062104	0.0062305
0.5	0.0604317	0.0606101	0.0606246
1	0.1176017	0.117721	0.1177831
1.5	0.1717675	0.1718101	0.1718502
2	0.2210188	0.2230992	0.2231435

Good agreement between analytical approximate solution and numerical method assure us about validity and accuracy of solution.

5. CONCLUSIONS

In this paper, the homotopy perturbation method (HPM) has been successfully applied to finding the solutions of plane couette flow with variable viscosity. The HPM does not require small parameters in the equations, so that the limitations of the traditional perturbation methods can be eliminated and the calculations in HPM is simple and straightforward. In HPM, the approximations obtained are valid, not only for small parameters, but also for larger ones. The results show that the HPM is a powerful mathematical tool for solving differential system, it is also a promising method to solve other nonlinear ordinary and partial differential systems. The solutions obtained are shown graphically and compared with the exact solution.

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