



DOI: 10.2478/sjpna-2020-0009



NONHOMOGENEOUS GENERALISATIONS OF POISSON PROCESS IN THE MODELING OF RANDOM PROCESSES RELATED TO ROAD ACCIDENTS

Franciszek Grabski 

Polish Naval Academy, Department of Mathematics and Physics, Śmidowicza 69 Str., 81-127 Gdynia, Poland, e-mail: f.grabski@amw.gdynia.pl, ORCID ID: 0000-0001-5772-4550

ABSTRACT

The stochastic processes theory provides concepts, and theorems, which allow to build the probabilistic models concerning accidents. "Counting process" can be applied for modelling the number of road, sea, and railway accidents in the given time intervals. A crucial role in construction of the models plays a Poisson process and its generalizations. The nonhomogeneous Poisson process, and the corresponding nonhomogeneous compound Poisson process are applied for modelling the road accidents number, and number of people injured and killed in Polish roads. To estimate model parameters were used data coming from the annual reports of the Polish police.

Keywords:

road accident, nonhomogeneous Poisson process, nonhomogeneous compound Poisson process

Research article

© 2020, Franciszek Grabski

This journal provides immediate open access to its content under the Creative Commons by 4.0 license. Authors who publish with this journal retain all copyrights and agree to the terms of the above-mentioned [CC BY 4.0 license](https://creativecommons.org/licenses/by/4.0/)

1. INTRODUCTION

Von Bortkiewitsch (1898) calculated, using the data of the Prussian army, the number of soldiers who died, during 20 consecutive years, because of being kicked by a horse. He noticed that a random variable, say X , denoting the number of solders killed accidentally by the horse kick per year, has approximately Poisson distribution with parameter $\lambda=0.61$ [1/year]. Since then Poisson's distribution, and the corresponding stochastic Poisson process, have found use in various fields of science and technology.

A Poisson process and its extensions, are used in safety and reliability problems. They allow to construct the models denoting number of road, sea, and railway accidents in the given time intervals.

It should be mentioned, that this paper is an extension of article [3], because of the new data concerning the Polish road accidents in 2019 [11].

2. NONHOMOGENEUS POISSON PROCESS

We start from definition of nonhomogeneous Poisson Process (NPP).

Let

$$\tau_0 = \vartheta_0 = 0, \quad \tau_n = \vartheta_1 + \vartheta_2 + \dots + \vartheta_n, \quad n \in \mathbb{N}, \quad (1)$$

where $\vartheta_1, \vartheta_2, \dots, \vartheta_n$ are positive independent random variables.

$$\tau_\infty = \lim_{n \rightarrow \infty} \tau_n = \sup\{\tau_n: n \in \mathbb{N}_0\}. \quad (2)$$

A stochastic process $\{N(t): t \geq 0\}$ defined by the formula

$$N(t) = \sup\{n \in \mathbb{N}_0: \tau_n \leq t\} \quad (3)$$

is called a *counting process* corresponding to a random sequence $\{\tau_n: \in \mathbb{N}_0\}$.

Let $\{N(t): t \geq 0\}$ be a stochastic process, taking values on $S = \{0,1,2, \dots\}$, value of which represents the number of events in a time interval $[0, t]$.

A counting process $\{N(t): t \geq 0\}$ is said to be *nonhomogeneous Poisson process* (NPP) with an intensity function $\lambda(t) \geq 0, t \geq 0$, if

1. $P(N(0) = 0) = 1$; (4)

2. The process $\{N(t): t \geq 0\}$ is the stochastic process with independent increments, the right continuous and piecewise constant trajectories;

3. $P(N(t+h) - N(t) = k) = \frac{(\int_t^{t+h} \lambda(x) dx)^k}{k!} e^{-\int_t^{t+h} \lambda(x) dx}$; (5)

From the definition it follows, that the one dimensional distribution of NPP is given by the rule:

$$P(N(t) = k) = \frac{(\int_0^t \lambda(x) dx)^k}{k!} e^{-\int_0^t \lambda(x) dx}, \quad k = 0, 1, 2, \dots \quad (6)$$

The expectation and variance of NPP are the functions:

$$\Lambda(t) = E[N(t)] = \int_0^t \lambda(x) dx \qquad V(t) = V[N(t)] = \int_0^t \lambda(x) dx, \quad t \geq 0. \quad (7)$$

The corresponding standard deviation is:

$$D(t) = \sqrt{V[N(t)]} = \sqrt{\int_0^t \lambda(x) dx}, \quad t \geq 0. \quad (8)$$

The expected value of the increment $N(t+h) - N(t)$ is:

$$\Delta(t; h) = E(N(t+h) - N(t)) = \int_t^{t+h} \lambda(x) dx. \quad (9)$$

The corresponding standard deviation is :

$$D(t; h) = D(N(t+h) - N(t)) = \sqrt{\int_t^{t+h} \lambda(x) dx} \quad (10)$$

A nonhomogeneous Poisson process with $\lambda(t) = \lambda, t \geq 0$ for each $t \geq 0$, is a regular Poisson process. The increments of nonhomogeneous Poisson process are independent, but not necessarily stationary. A nonhomogeneous Poisson process is a Markov process.

3. NONHOMOGENEOUS COMPOUND POISSON PROCESS

We assume that $\{N(t): t \geq 0\}$ is a *nonhomogeneous Poisson process* (NPP) with an intensity function $\lambda(t)$, $t \geq 0$ such that $\lambda(t) \geq 0$ for $t \geq 0$, and X_1, X_2, \dots is a sequence of the independent random variables independent of $\{N(t): t \geq 0\}$. A stochastic process

$$X(t) = X_1 + X_2 + \dots + X_{N(t)}, \quad t \geq 0 \quad (11)$$

is said to be a *nonhomogeneous compound Poisson process* (NCP).

Proposition 1.

Let $\{X(t): t \geq 0\}$ be a *nonhomogeneous compound Poisson process* (NCP).

If $E(X_1^2) < \infty$, then:

$$1. \quad E[X(t)] = \Lambda(t) E(X_1) \quad (13)$$

$$2. \quad V[X(t)] = \Lambda(t) E(X_1^2), \quad (14)$$

Where:

$$\Lambda(t) = E[N(t)] = \int_0^t \lambda(x) dx.$$

P r o o f [6].

Corollary 1

Let $\{X(t+h) - X(t): t \geq 0\}$ be an increment of a *nonhomogeneous compound Poisson process* (NCP).

If $E(X_1^2) < \infty$, then:

$$E[X(t+h) - X(t)] = \Delta(t; h) E(X_1), \quad (15)$$

$$V[X(t+h) - X(t)] = \Delta(t; h) E(X_1^2), \quad (16)$$

where:

$$\Delta(t; h) = \int_t^{t+h} \lambda(x) dx. \quad (17)$$

4. DATA ON MOTORIZATION AND ROAD ACCIDENTS IN POLAND

Quoted data from the Central Statistical Office from 2017, 2018, and 2019 were presented in reports of the Polish Police [9], [10], [11].

4.1 GENERAL DATA ON MOTORIZATION

Since the beginning of the 90's, the number of vehicles registered in Poland has been systematically growing

Tab.1. Number of motor vehicles in the years 2007-2018

Years	Motor vehicles in total	Passenger cars	Trucks	Motorcycles
2007	19 471 836	14 588 739	2 345 068	825 305
2008	21 336 913	16 079 533	2 511 677	909 144
2009	22 024 697	16 494 650	2 595 845	974 906
2010	23 037 149	17 239 800	2 767 035	1 013 014
2011	24 189 370	18 125 490	2 892 064	1 069 195
2012	24 875 718	18 744 412	2 920 779	1 107 260
2013	25 683 575	19 389 446	2 962 064	1 153 169
2014	26 472 274	20 003 863	3 037 427	1 189 527
2015	27 409 106	20 723 423	3 098 376	1 272 333
2016	28 601 037	21 675 388	3 179 655	1 355 625

2017	29 149 178	22 109 572	3 212690	1 398 609
2018	29 656 238	22 514 047	3 249 961	1 428 299
2019	31 388 643	23 874 531	3 387 536	1 553 370

It is easy to count, that from 2007 to 2019, the number of passenger cars increased by 38.68 %, number of trucks by 30.77%, while the number of motorcycles increased by 46.68% . During this time, the total number of motor vehicles increased by 37.96%.

The location of our country on the East-West transport route generates heavy transit traffic. According to the border guards, cited in the police report [10], in 2018, 12 435 345 vehicles entered the European Union's external borders, including 9 970 787 passenger cars.

4.2 GENERAL DATA ON ROAD ACCIDENTS

A table, containing the number of accidents, and their consequences, is presented below. The data comes from police reports [9], [10]. [11].

Tab.2. Number of accidents and their consequences in the years 2007-2019

Years	Interval [days]	Center of interval	Number of accident	Number of fatalities	Number of injured	Indica- tor α	Indicator β
2007	[0, 365)	183,5	49 536	5 583	63 224	0,1127	1,2763
2008	[365, 731)	548	49 054	5 432	62 097	0,1108	1,2658
2009	[1096,1461)	1278,5	44 196	4 572	56 046	0,1034	1,2681

2010	[1461,1826)	1643,5	38 832	3 907	48 952	0,1006	1,2606
2011	[1826,2192)	2008,5	40 065	4 189	49 501	0,1045	1,2355
2012	[2192,2558)	2375	37 046	3 571	45 792	0,0963	1,236
2013	[2558, 2923)	2740,5	35 847	3 357	44 059	0,0957	1,2571
2014	[2923, 3288)	3105,5	34 970	3 209	42 545	0,0915	1,2166
2015	[3288, 3653)	3470,5	32 967	2 938	39 778	0,0891	1,2066
2016	[3653, 4019)	3836	33 664	3 026	40 766	0,0898	1,2109
2017	[4019, 4384)	4201,5	32 760	2 831	39 466	0,0864	1,2047
2018	[4384, 4749)	4566,5	31 674	2 862	37 359	0,0903	1,1794
2019	[4749, 5114)	4931,5	30 288	2 909	35 477	0,0960	1,1713

The table does not contain the number of traffic collisions. For example, in 2018, 436 414 road collisions were reported.

5. MODEL OF THE ROAD ACCIDENT NUMBERS

Due to the nature of these events, pre-assumption that it is a nonhomogeneous Poisson process with some parameter $\lambda(t) > 0$, seems to be justified. The expected value of increment of this process is given by (9), while its one dimensional distribution is determined by (5). We can use practically these rules if the intensity

function $\lambda(t) > 0$ is known. To define this function one utilizes information presented in table 2. The statistical analysis of the data shows that the intensity function $\lambda(t)$ can be approximated by the linear function $\lambda(t) = at + b$.

5.1. ESTIMATION OF THE MODELS PARAMETERS

Dividing the number of accidents in each year, by 365 or 366 we get the intensity in units of [1 / day].

We approximate the empirical intensity by a linear regression function $y = ax + b$ that satisfies condition

$$S(a, b) = \sum_{i=1}^n [y_i - (ax_i + b)]^2 \rightarrow \min$$

Recall, that solution of above optimization problem leads to finding parameters a and b . The parameters are given by the rules:

$$a = \frac{\mu_{11}}{\mu_{20}}, \quad b = m_{01} - am_{10}, \quad \bar{x} = m_{10} = \frac{1}{n} \sum_{i=1}^n x_i, \quad \bar{y} = m_{01} = \frac{1}{n} \sum_{i=1}^n y_i, \quad (22)$$

$$m_{11} = \frac{1}{n} \sum_{i=1}^n x_i y_i, \quad \mu_{11} = m_{11} - m_{10} m_{01},$$

$$m_{20} = \frac{1}{n} \sum_{i=1}^n x_i^2, \quad \mu_{20} = m_{20} - m_{10}^2.$$

Applying the rules (26) for the data from Table 2 and using Excel system we obtain:

$$a = -0.000003658, \quad b = 2,534128 \quad (23)$$

The linear intensity of accidents is:

$$\lambda(x) = -0,000113629 x + 3.442384 \geq 0 \quad (24)$$

This function is shown in figure 1.

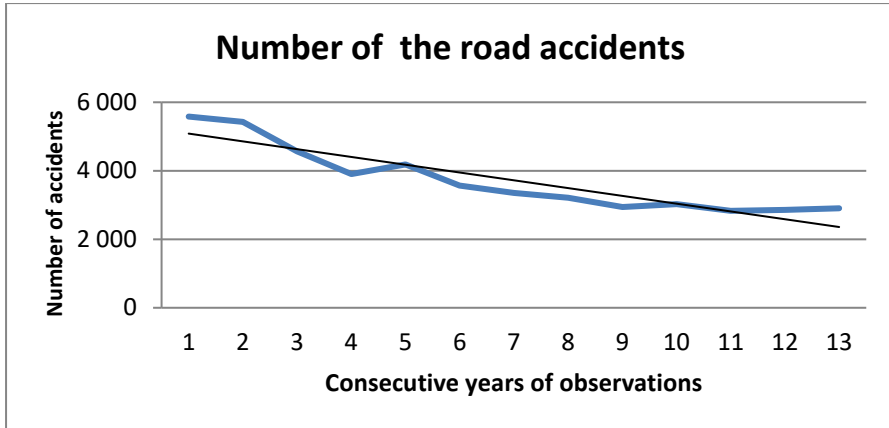


Fig. 1. Intensity of the road accidents in Poland

From (7) we obtain:

$$\Lambda(t) = -0,000113629 t^2 + 2,534128t, \quad t \geq 0. \tag{25}$$

Therefore the one dimensional distribution of NPP is:

$$P(N(t) = k) = \frac{(\Lambda(t))^k}{k!} e^{-\Lambda(t)} \quad k = 0,1,2, \dots, \tag{26}$$

where $\Lambda(t)$ is given by (25).

Finally one can say that the model of the accident number on Polish roads is the nonhomogeneous Poisson process with the parameter $\Lambda(t)$, $t \geq 0$, determined by (25).

Using data from the Table 1 and Figure 2 one can compute the indicator of fatalities intensity in road accidents in relation to the number of vehicle crossing

$$\alpha = \mathbf{NF} / \mathbf{NVC} \tag{27}$$

where \mathbf{NF} denotes number of fatalities, \mathbf{NVC} designates number of vehicles crossing

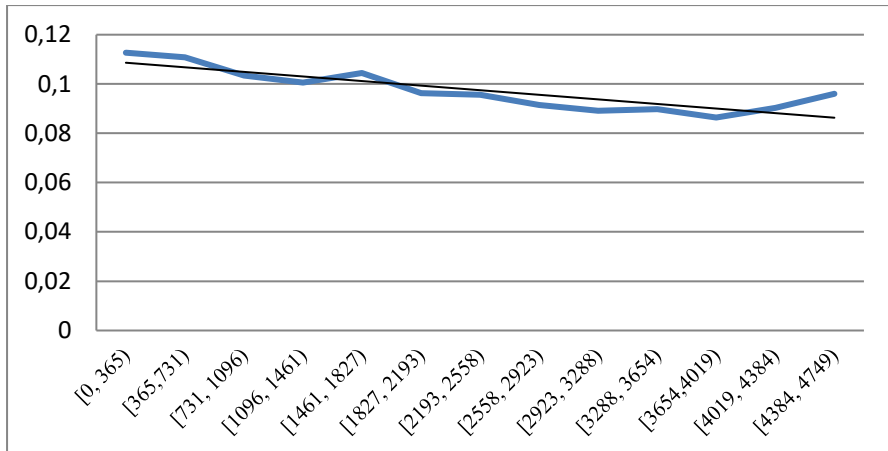


Fig. 2. Indicators of fatalities intensity in road accidents in relation to the crossing number

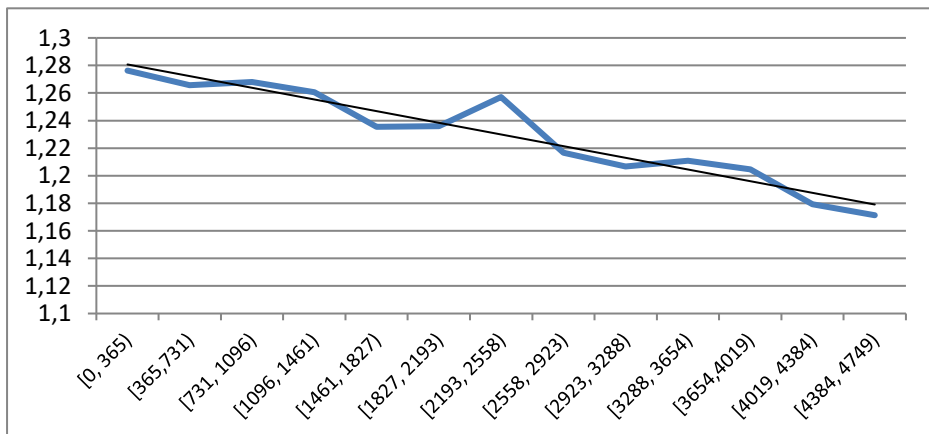


Fig. 3. Indicators of injured intensity in road accidents in relation to the crossing number

$$\beta = NI/NVC$$

6. ANTICIPATION OF ACCIDENT NUMBER

From (5) and (10) we get:

$$P(N(t+h) - N(t) = k) = \frac{\Delta(t;h)}{k!} e^{-[\Delta(t;h)]}. \quad (28)$$

It means that one can anticipate number of accidents at any time interval, with a length of h . The expected value of the increment $N(t+h) - N(t)$ is defined by (10). For the function:

$$\Lambda(t) = a \frac{t^2}{2} + b t \quad (29)$$

we obtain the expected value of the accidents at time interval $[t, t+h)$

$$\Delta(t; h) = h \left(\frac{a h}{2} + b + a t \right), \quad (30)$$

The corresponding standard deviation is:

$$\sigma(t; h) = \sqrt{h \left(\frac{a h}{2} + b + a t \right)}. \quad (31)$$

Example 1.

We want to predict the number of accidents from June 1st of 2020 to August 30th of 2020. We also want to calculate the probability of a given number of accidents. First we have parameters t and h . As extension of table 2 on year 2019 we can obtain an interval [4749, 5114]. From January 1st of 2020 to June 1st of 2020 152 days have passed. Hence $t = 4749 + 152 = 4901$. From June 1st to August 31st $h = 92$ days have passed. For these parameters using (29) and (30) we obtain $\Delta(t; h) = 7074.406$, $\sigma(t; h) = 84.109$.

This means, that the average predicted number of accidents between June 1st, 2019 and August 31st, 2019 is about 7074, with a standard deviation of about 84.

$$P_{c \leq X \leq d} = P(c \leq N(t+h) - N(t) \leq d) = \sum_{x=c}^{x=d} \frac{7074.406^x}{x!} e^{-7074.406}; x = 0, 1, 2, \dots$$

Applying approximation by normal distribution we get:

$$P_{c \leq X \leq d} = \Phi \left(\frac{d - 7074,406}{84,109} \right) - \Phi \left(\frac{c - 7074,406}{84,109} \right)$$

For $d = k\sigma$, $c = -k\sigma$, $k = 1, 2, 3$ we obtain k -sigma formula:

$$P_{-k\sigma \leq X \leq k\sigma} = 2\Phi(k) - 1 = \begin{cases} 0.6827 & \text{for } k = 1 \\ 0.9545 & \text{for } k = 2 \\ 0.9973 & \text{for } k = 3 \end{cases}$$

Therefore, for the predicted number of accidents between June 1st, 2019 and August 31st, 2019:

$$\begin{aligned} P(X \in [6990.297, 7158.515]) &= 0.6827, \\ P(X \in [6906.188, 7242.624]) &= 0.9545, \\ P(X \in [6822.079, 7326.733]) &= 0.9973. \end{aligned}$$

6.1. ANTICIPATION OF THE ACCIDENTS CONSEQUENCES

Let $X = X_i$, $i = 1, 2, \dots, N(t)$ denotes number of fatal events in a single accident. We suppose that the random variables X_i , $i = 1, 2, \dots$ have the identical Poisson distribution with parameters $E(X_i) = V(X_i) = \mu$, $i = 1, 2, \dots, N(t)$.

The predicted number of fatal events in the time interval $[t, t + h)$ is described by the expectation of the increment $X(t + h) - X(t)$. Recall that the expected value, and standard deviation of the accidents number in the time interval $[t, t + h)$ are given by (10) and (11). For the data from *Example 1* using (29) and (30), we obtain the expected value of fatalities number (**EFN**), and the corresponding standard deviation (**DFN**) in the time interval $[t, t + h) = [4900, 4992)$:

$\Delta(t; h) = \Delta(t; h) \times \mu$, and $\mathbf{DFN} = \sqrt{\Delta(t; h) \times (\mu + \mu^2)}$. We assume that the NCPP is homogenous in this time interval, and a mean is calculated in center of interval.

Finally we obtain **EFN = 315.034** and **DFN = 17.7492**.

For the same data we obtain the expected value of injured number, denoted by **EIN**, and corresponding standard deviation (**DIN**) in the time interval $[4900, 4992)$. We assume that the NCPP is homogenous in this time interval, and a mean is calculated in center of that one. In this case $\Delta(t; h) = 626.62$. Using the same formulas we get the expectation **EIN**, and the standard deviation **DGN = 25,03** of injured people number.

7. CONCLUSIONS

The nonhomogeneous Poisson process, and the corresponding nonhomogeneous compound Poisson process are applied for modelling the road accidents number, and the number of injured and fatalities on Polish roads. To estimate model parameters one used data coming from the annual reports of the Polish police. Constructed models allowed to anticipate number of accidents at any time interval, with a length of h and the accident consequences. One obtained the expected value of fatalities or injured, and the corresponding standard deviation in the time interval $[t, t + h)$.

The statistical distribution of fatalities number in a single accident, and statistical distribution of injured people number, and also statistical distribution of fatalities or injured number in a single accident, are computed.

REFERENCES

- [1] Di Crescenzo A., Martinucci B., Zacks S. Compound Poisson process with Poisson subordinator *Journal of Applied Probability* Vol. 52, No. 2, p. 360- 374, 2015.
- [2] Fisz M. Probability and Mathematical Statistics, Warsaw PWN; (in Polish) 1969
- [3] Grabski F. Nonhomogeneous Poisson process and compound Poisson process in modeling of random processes related to road accidents. *Journal of KONES Powertrain and Transport*, Vol.26, No.1 2019. Pp 39-46.
- [4] Grabski F. *Semi-Markov Processes: Applications in Systems Reliability and Maintenance* Elsevier; Amsterdam, Boston, Heidelberg, London, NewYork, Oxford, Paris, San Diego, San Francisco, Sydney, 2015.
- [5] Grabski F. Nonhomogeneous Poisson process application to modelling accidents numberat Baltic waters and ports. *Journal of Polish Safety and Reliability Association*; volume 8, number 1, p. 39-46, 2017.
- [6] Grabski F. Nonhomogeneous stochastic processes connected to Poisson process. *Scientific Journal of Polish Naval Academy*, 2 (213), pp. 5-15, Gdynia 2018 (LIX).
- [7] Limnios N, Oprisan G., *Semi-Markow Processes and Reliability*; Birkhauser, Boston 2001.
- [8] Shiriyayev A. N., *Probability*. Springer-Verlag, New York, Berlin, Heidelberg, Tokyo 1984.
- [9] Symon E. *Wypadki drogowe w Polsce w roku 2017* . Wydział Opiniodawczo-Analityczny Biura Ruchu Drogowego Komendy Głównej Policji, Warszawa 2018.

[10] Symon E. *Wypadki drogowe w Polsce w roku 2018*. Wydział Opiniodawczo-Analityczny Biura Ruchu Drogowego Komendy Głównej Policji, Warszawa 2019.

[11] Symon E. *Wypadki drogowe w Polsce w roku 2019*. Wydział Opiniodawczo-Analityczny Biura Ruchu Drogowego Komendy Głównej Policji, Warszawa 2020.

NIEJEDNORODNE UOGÓLNIENIE PROCESU POISSONA W MODELOWANIU LOSOWYCH PROCESÓW ZWIĄZANYCH Z WYPADKAMI DROGOWYMI

STRESZCZENIE

W pracy przedstawiono niektóre uogólnienia procesu Poissona i ich własności. Skupiono się na dwóch uogólnieniach – niejednorodnym procesie Poissona i niejednorodnym złożonym procesie Poissona. Niejednorodny proces Poissona pozwala na skonstruowanie modelu probabilistycznego, opisującego liczbę różnych rodzajów wypadków. Niejednorodny złożony proces Poissona pozwala matematycznie opisywać konsekwencje tych wypadków. Przedstawione tu wyniki teoretyczne dają możliwość przewidywania liczby wypadków i ich konsekwencji. Estymacja parametrów modelu została wykonana na podstawie danych zamieszczonych w rocznych raportach Policji [9], [10], [11].

Słowa kluczowe:

wypadek drogowy, niejednorodny proces Poissona, niejednorodny złożony proces Poissona