The paper presents analytical solutions for displacements and stresses in an elastic layered half-space with periodic structure in the case of an axi-symmetrical contact problem. The solutions are arrived at employing the Hankel transform. Finally, a comparison is made between the results obtained using the classical theory of elasticity and those obtained within the framework of the homogenized model with microlocal parameters.

**Key words:** layered structures, contact, stress distribution

1. Introduction

Extensive applications of layered composite materials in both civil and mechanical engineering, geophysics as well as their widespread presence in nature (varved clays, sandstone-slates, thin layered limestones) have made composite materials an object of intensive research. To be able to create or verify strength hypotheses of the materials, adequate knowledge of stress distribution in the composites caused by mechanical factors, eg. pressure distribution, is essential.

The formulation of contact problems for periodically layered composites based on the classical theory of elasticity leads to boundary value problems for partial differential equations with discontinuous, strongly oscillating coefficients. As this approach is rather complicated, the classical formulation of the problem is often replaced with approximated models (Sun *et al*., 1967; Achenbach, 1975; Bensoussan *et al*., 1978; Christensen, 1980; Sanchez-Palenzia, 1980) in which mechanical properties of the medium are determined on the basis of mechanical and geometrical properties of the analyzed composite components.

In some problems, a periodically layered structure is replaced with a homogeneous transversely isotropic medium (Postma, 1955). In this model, calculated strains and stresses are averaged in the fundamental layer. On the other hand, the homogenized model with microlocal parameters (Matysiak and Woźniak, 1987; Woźniak, 1987) makes it possible to evaluate local values of strains and stresses in each sublayer. Owing to the simplification of the mathematical solution, the homogenized model with microlocal parameters has been applied to resolve some contact problems of mechanics and geomechanics (Kaczyński and Matysiak, 1988, 1993, 2001; Kulchytsky-Zhyhailo and Matysiak, 1995; Matysiak and Pauk, 1995).

However, the application of the homogenized model to a periodically layered structure results in errors. To estimate these errors, it is necessary to compare solutions for the periodically layered structure based on two approaches:

(i) homogenized model with microlocal parameters

(ii) non-homogeneous medium with separate elastic layers.

In the case of heat transfer and theory of elasticity, such investigations were carried out in Kulchytsky-Zhyhailo and Kołodziejczyk (2004, 2007), Kulchytsky-Zhyhailo and Matysiak (2005a,b). It was shown that the solutions obtained using these models were consistent if the
ratio \( \delta \) of thickness of the fundamental layer to the size of heating area or loading area was small \((\delta < 0.2)\).

One of the fundamental issues of contact mechanics is the problem of pressing a rigid sphere into an elastic half-space. In the case of a homogeneous half-space, the problem is reduced to the loading of the surface by Hertz pressure

\[
p(r) = \frac{3}{2}p_0 \sqrt{1 - r^2}
\]

where: \( p_0 \) – mean contact pressure, \( r \) – dimensionless cylindrical coordinate \((r < 1)\) with respect to the radius \( a \) of the contact area.

Similar results were obtained for a periodically layered half-space using the homogenized model with microlocal parameters (Kulchytsky-Zhyhailo and Matysiak, 1995). For a non-homogeneous half-space, expression (1.1) is a good description of pressure distribution for the case when \( \delta < 0.2 \) (Kulchytsky-Zhyhailo and Kołodziejczyk, 2007). It should be noted here that the authors focused their attention on two parameters only, i.e. pressure distribution and size of the contact area.

In the present paper, the authors focus on stress analysis in a layered medium with periodical structure caused by pressure (1.1) and compare the results obtained using the two models.

2. Formulation of the problem

Let us consider a two-layered elastic half-space with a periodic structure loaded by Hertz pressure (Fig. 1). A repeated fundamental layer is composed of two homogeneous elastic sublayers with thickness \( l_1 \) and \( l_2 \). Mechanical properties of the sublayers are characterized by Young’s moduli \( E_1 \) and \( E_2 \) and Poisson’s ratios \( \nu_1 \) and \( \nu_2 \).

![Fig. 1. Diagram of the analyzed problem](image)

3. Homogenized model

Initially, the basis for consideration is the homogenized model with microlocal parameters. The governing equations of the homogenized model given in terms of macro-displacements can be written in the following form (Kaczyński and Matysiak, 2001):

— equations

\[
\begin{align*}
A_1 \left( \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} - \frac{u}{r^2} \right) + (A_3 + A_5) \frac{\partial^2 w}{\partial r \partial z} + A_5 \frac{\partial^2 u}{\partial z^2} &= 0 \\
(A_3 + A_5) \left( \frac{\partial^2 u}{\partial r \partial z} + \frac{1}{r} \frac{\partial u}{\partial z} \right) + A_4 \frac{\partial^2 w}{\partial z^2} + A_5 \left( \frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} \right) &= 0
\end{align*}
\]
— boundary conditions on the surface of the half-space
\[ \sigma_{zz} = -p(r)H(1 - r) \quad \sigma_{rz} = 0 \quad z = 0 \] (3.2)
— regularity conditions in infinity
\[ u, w \to 0 \quad r^2 + z^2 \to \infty \] (3.3)
where
\[
A_1 = (\tilde{\lambda} + 2\tilde{\mu} - \frac{[\lambda]^2}{\lambda + 2\tilde{\mu}}) \\
A_3 = \tilde{\lambda} - \frac{[\lambda](\lambda + 2[\mu])}{\lambda + 2\tilde{\mu}} \\
A_5 = \tilde{\mu} - \frac{[\mu]^2}{\tilde{\mu}} \\
A_4 = (\tilde{\lambda} + 2\tilde{\mu}) - \frac{(\lambda + 2[\mu])^2}{\lambda + 2\tilde{\mu}} \\
\tilde{\lambda} = \eta\lambda_1 + (1 - \eta)\lambda_2 \\
\tilde{\mu} = \eta\mu_1 + (1 - \eta)\mu_2 \\
\lambda_i = \frac{E_i\nu_i}{(1 + \nu_i)(1 - 2\nu_i)} \\
\mu_i = \frac{E_i}{2(1 + \nu_i)}
\]
and \( \eta = l_1/l \), \( u, w \) are dimensionless displacements, \( \sigma \) — stress tensor, \( H(\cdot) \) — Heviside’s unit step function.

Relations between the stresses and macro-displacements are as follows (Kaczyński, 1994)
\[
\sigma_{zz} = A_3 \left( \partial u / \partial r + \frac{u}{r} \right) + A_4 \frac{\partial w}{\partial z} \\
\sigma_{rr}^{(i)} = K_i \frac{\partial u}{\partial r} + L_i \frac{u}{r} + M_i \frac{\partial w}{\partial z} \\
\sigma_{\psi\psi}^{(i)} = L_i \frac{\partial w}{\partial r} + K_i \frac{u}{r} + M_i \frac{\partial w}{\partial z} \\
\sigma_{rz} = A_5 \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial r} \right)
\] (3.4)
and
\[
K_i = \lambda_i + 2\mu_i - h_i\lambda_i \frac{[\lambda]}{\lambda + 2\tilde{\mu}} \\
L_i = \lambda_i - h_i\lambda_i \frac{[\lambda]}{\lambda + 2\tilde{\mu}} \\
M_i = \lambda_i - h_i\lambda_i \frac{[\lambda] + 2[\mu]}{\lambda + 2\tilde{\mu}} \\
h_1 = 1 \\
h_2 = -\frac{\eta}{1 - \eta}
\] (3.5)
where \( i \) is the sublayer number in the fundamental layer. From relations (3.4), it follows that the presented model yields separate equations for computation of stress tensor components in the first and second sublayer of the fundamental layer. However, for \( \sigma_{zz} \) and \( \sigma_{rz} \) they are identical (index \( i \) can be omitted). For the stress components \( \sigma_{rr} \) and \( \sigma_{\psi\psi} \) having jump discontinuities on boundaries between the layers we have two formulas for each.

Solutions of the set of equations (3.1) can be expressed as follows (Elliot, 1949a,b)
\[
u = \frac{\partial \Psi_1}{\partial r} + \frac{\partial \Psi_2}{\partial z} \\
w = \kappa_1 \frac{\partial \Psi_1}{\partial z} + \kappa_2 \frac{\partial \Psi_2}{\partial z}
\] (3.6)
where
\[
\kappa_k = \frac{\gamma_k^2 A_1 - A_5}{A_3 + A_5}
\] (3.7)
\( \Psi_k \) are elastic potentials satisfying equations
\[
\frac{\partial^2 \Psi_i}{\partial r^2} + \frac{1}{r} \frac{\partial \Psi_i}{\partial r} + \frac{\partial^2 \Psi_i}{\partial z^2} \gamma_i^2 = 0 \quad i = 1, 2
\] (3.8)
\[ \gamma_i^2 \text{ are roots of the characteristic equation} \]
\[ A_1 A_5 \gamma^4 + (A_3^2 + 2A_3 A_5 - A_1 A_4) \gamma^2 + A_4 A_5 = 0 \]  
(3.9)

In order to find a solution to equations (3.8), Hankel's transform is used

\[ \tilde{f}(s, z) = \int_0^\infty r f(r, z) J_0(sr) \, dr \]  
(3.10)

where \( J_0 \) is the Bessel function. A general solution to the set of equations (3.8) satisfying conditions (3.3) takes the form

\[ \tilde{\Psi}_i(s, z) = C_i(s) \exp\left(-\frac{s z}{\gamma_i}\right) \quad i = 1, 2 \]  
(3.11)

Expressing (3.4)-(3.6) in Hankel’s transform domain and satisfying boundary conditions (3.2), we obtain

\[ C_1 = C_{-1}(p) \frac{1}{s^2} \quad C_2 = C_0(p) \frac{1}{s^2} \]  
(3.12)

where

\[ \tilde{p}(s) = \frac{3}{2} p_0 \sqrt{\frac{J_{3/2}(s)}{2}} \quad C_{-1} = \frac{\gamma_1}{A_5(\gamma_2 - \gamma_1)} A_3 + A_5 \]
\[ C_0(p) = -\frac{\gamma_2}{A_5(\gamma_2 - \gamma_1)} A_3 + A_5 \gamma_2 \]

Taking into account (3.4), (3.6), (3.11), we obtain

\[ u(r, z) = \int_0^\infty U_r(s, z) \tilde{p}(s) J_1(sr) \, ds \quad w(r, z) = \int_0^\infty U_z(s, z) \tilde{p}(s) J_0(sr) \, ds \]
\[ \sigma_{rr}^{(i)} = \int_0^\infty S_{r1}^{(i)}(s, z) \tilde{p}(s) J_0(sr) s \, ds + \frac{1}{r} \int_0^\infty S_{r2}^{(i)}(s, z) \tilde{p}(s) J_1(sr) \, ds \quad i = 1, 2 \]
\[ \sigma_{zz}^{(i)} = \int_0^\infty S_{z1}^{(i)}(s, z) \tilde{p}(s) J_0(sr) s \, ds \quad \sigma_{rz} = \int_0^\infty S_{z2}^{(i)}(s, z) \tilde{p}(s) J_1(sr) \, ds \]  
(3.13)

where

\[ U_r(s, z) = -\sum_{k=1}^2 C_{k-2}^{(p)} \exp\left(-\frac{s z}{\gamma_k}\right) \quad U_z(s, z) = -\sum_{k=1}^2 \kappa_k \gamma_k^{-1} C_{k-2}^{(p)} \exp\left(-\frac{s z}{\gamma_k}\right) \]
\[ S_{r1}^{(i)}(s, z) = \sum_{k=1}^2 \left(M_i \frac{K_k}{\gamma_k} - K_i\right) C_{k-2}^{(p)} \exp\left(-\frac{s z}{\gamma_k}\right) \]
\[ S_{r2}^{(i)}(s, z) = 2\mu_i \sum_{k=1}^2 C_{k-2}^{(p)} \exp\left(-\frac{s z}{\gamma_k}\right) \]
\[ S_{z1}^{(i)}(s, z) = \sum_{k=1}^2 \left(A_1 \frac{K_k}{\gamma_k} - A_3\right) C_{k-2}^{(p)} \exp\left(-\frac{s z}{\gamma_k}\right) \]
\[ S_{z2}^{(i)}(s, z) = A_5 \sum_{k=1}^2 (1 + \kappa_k) \gamma_k^{-1} C_{k-2}^{(p)} \exp\left(-\frac{s z}{\gamma_k}\right) \]
4. Classical model

Let us consider a layered half-space as \( n \) fundamental layers (2\( n \) sublayers) joined with a homogeneous part of the half-space (Fig. 2). It was shown (Kulchytsky-Zhyhailo and Kołodziejczyk, 2007) that over a fixed number of separately considered layers, the mechanical properties of the homogeneous part of the half-space can be quite arbitrarily chosen. They may include the properties of either the first or the second layer. However, considering the fact that the homogeneous part of the half-space possesses averaged properties of the homogenized medium described above, it is possible to obtain a sufficiently exact approximation solution of the problem for a significantly smaller number of separately considered layers.

![Fig. 2. Diagram of the analyzed problem](image)

The equations for separately considered layers can be written as follows

\[
\Delta u_k - \frac{u_k}{r^2} + d_k \frac{\partial \theta_k}{\partial r} = 0 \quad \Delta w_k + d_k \frac{\partial \theta_k}{\partial z'} = 0 \quad k = 1, 2, \ldots, 2n
\]

(4.1)

where \( \theta_k = \frac{\partial u_k}{\partial r} + u_k/r + \frac{\partial w_k}{\partial z'} \), \( k \) – layer number, \( d_{2j} = 1/(1 - 2\nu_1) \), \( d_{2j-1} = 1/(1 - 2\nu_2) \), \( j = 1, 2, \ldots, n \).

Differential equations (3.1) for the homogenized medium “0” should be attached to the above system of equations. The solution to the equations should satisfy the following conditions:

— boundary conditions on the surface \( z' = n\delta \)

\[
\sigma_{zz}^{(n)} = -p(r)H(1 - r) \quad \sigma_{rz}^{(n)} = 0 \quad z' = n\delta
\]

(4.2)

— boundary conditions between the layers and between the layers and the homogenized medium

\[
\begin{align*}
\sigma_{zz}^{(k)} &= \sigma_{zz}^{(k+1)} \\
w_k &= w_{k+1} \\
u_k &= u_{k+1} \\
\sigma_{rz}^{(k)} &= \sigma_{rz}^{(k+1)} \\
z' &= z_k
\end{align*}
\]

(4.3)

— regularity conditions in infinity

\[
u_k, w_k \to 0 \quad \text{for} \quad r^2 + z'^2 \to \infty
\]

(4.4)

where \( z_k \) is the coordinate \( z' \) of the point of intersection of the upper plane limiting the \( k \)-th layer with \( z' \) axis.

The solution to the classical elasticity theory problem formulated in this way was obtained using the Hankel transform. Applying the algorithm described in Kulchytsky-Zhyhailo and Kołodziejczyk (2007), we obtain expressions to calculate displacements and stresses in form (3.13),
where functions $U_r, U_z, S_{z1}, S_{z2}, S_{r1}, S_{r2}$ should be replaced with the following

\[ 2U_r^{(k)}(s, z') = D_k s_k C_{4k-3}^{(p)}(s) + D_k c_k C_{4k-2}^{(p)}(s) + 2ss_k C_{4k-1}^{(p)}(s) + 2sc_k C_{4k}^{(p)}(s) \]
\[ 2U_z^{(k)}(s, z') = \frac{\mu_k}{k} S_{z1}^{(k)}(s, z') = ((2 + d_k)s_k + D_k c_k) C_{4k-3}^{(p)}(s) \]
\[ S_{z1}^{(k)}(s, z') = ((1 + 2d_k)s_k + D_k c_k) C_{4k-3}^{(p)}(s) + ((1 + 2d_k)c_k + D_k s_k) C_{4k-2}^{(p)}(s) \]  
\[ + 2sc_k C_{4k-1}^{(p)}(s) + 2ss_k C_{4k}^{(p)}(s) \]
\[ S_{z2}^{(k)}(s, z') = ((1 + d_k)c_k + D_k s_k) C_{4k-3}^{(p)}(s) + ((1 + d_k)s_k + D_k c_k) C_{4k-2}^{(p)}(s) \]  
\[ + 2ss_k C_{4k-1}^{(p)}(s) + 2sc_k C_{4k}^{(p)}(s) \]

where $c_k = \cosh(s(z_k - z'))$, $s_k = \sinh(s(z_k - z'))$, $D_k = d_k s(z_k - z')$, $\mu_k = \frac{E_k}{2(1 + \nu_k)}$.

Expressions (4.5) and the corresponding equations for the homogenized half-space “0” include \((8n + 2)\) unknown functions $C_k(s)$, $k = -1, 0, 1, \ldots, 8n$. Satisfying boundary conditions (4.2) and (4.3), we obtain a system of algebraic equations allowing us to determine the unknown functions (Kulchytsky-Zhyhailo and Kołodziejczyk, 2007).

5. Numerical results and discussion

The stress distribution arising in the non-homogeneous half-space obtained within the framework of the homogenized model depends on four dimensionless parameters: ratio $E_1/E_2$ of Young’s moduli of the materials of individual layers, Poisson’s ratios $\nu_1$ and $\nu_2$, the thickness ratio of the upper layer to the thickness of the periodicity cell $\eta = l_1/l = \delta_1/\delta$. When considering the layered medium, the stress distribution is additionally dependent on the parameter $\delta$. In order to confine the range of the considered parameters, it was assumed that $\nu_1 = \nu_2 = 0.3$. To emphasize the differences that arise between the solutions obtained from both models the ratio of Young’s modulus was assumed $E_1/E_2 = 8$. Since the results change only insignificantly within the considered range of $\delta$ parameter when altering the sequence of layers in the periodicity cell, we restrict our analysis to the case when $E_1/E_2 > 1$.

The calculations show that the stress distributions $\sigma_{zz}$ and $\sigma_{rz}$ for the homogenized model are very close to the corresponding stress distribution for the layered medium. All the distributions are similar to those obtained for a homogeneous medium in the classical Hertz contact problem. However, significantly different results can be observed for the stress distribution of $\sigma_{rr}$ and $\sigma_{\psi \psi}$. These stress distributions along $z$-axis are shown in Fig. 3 (at $z$-axis $\sigma_{rr} = \sigma_{\psi \psi}$). For a non-homogeneous medium on each boundary between layers these stress components undergo a jump. This discontinuity is illustrated by black vertical lines. The two gray lines are obtained on the basis of the homogenized model, and they describe the stress distribution in the layers with smaller and greater Young’s modulus respectively. As seen in Fig. 3, the stress distribution obtained from the homogenized model describes the stress distribution in the layered medium with sufficient accuracy. The difference between the results decreases with reduction of $\delta$ parameter. Thus, a suggestion can be made that a detailed analysis of stress distribution in a
non-homogeneous medium can be based on the homogenized model, which will radically reduce the time of computation.

Fig. 3. Stress distribution $\sigma_{rr}/p_{\text{max}}$ along $z$-axis for different values of $\delta$; black line – solution for the layered medium, gray lines – solution for the homogenized model, dashed lines – boundaries between layers; $E_1/E_2 = 8$, $\nu_1 = \nu_2 = 0.3$, $\eta = 0.5$.

When analyzing the stress level, special attention should be paid to the existence of regions of tensile stresses that are determined on the basis of principal stress $\sigma_1$ as well as to the distribution of the second invariant of the deviatoric stress tensor

$$J_2 = \frac{1}{\sqrt{6}} \sqrt{(\sigma_1 - \sigma_2)^2 + (\sigma_1 - \sigma_3)^2 + (\sigma_2 - \sigma_3)^2}$$

(5.1)

Typical distributions of dimensionless parameters $\sigma_1$ and $J_2$ with respect to parameter $p_{\text{max}} = (3/2)p_0$ are shown in Figs. 4 and 5. In layers with greater Young’s modulus two regions of tensile stresses occur. The first is found in the vicinity of the points of the unloaded surface of the half-space (Fig. 4a). Maximum of the $\sigma_1$ stress, similarly to the contact problem for the homogeneous medium, occurs on the boundary of the loaded circle. The stress can be determined from the expression

$$\sigma_1^{(1)}(1,0) = \frac{p_{0}\mu_1}{\sqrt{A_1 A_4 + A_3}}$$

(5.2)

The other region arises at a certain depth. Tensile stresses in this region are generally much smaller than the stress at points $z = 0$, $r = 1$.

Fig. 4. Tensile stress distribution $\sigma_1$ in layers with: (a) greater Young’s modulus, (b) smaller Young’s modulus.

In layers with smaller Young’s modulus, the region of tensile stresses occurs beneath the unloaded surface of the half-space (Fig. 4b). In this case, there exist two local maxima of $\sigma_1$. 
stresses. The first at the boundary of the loading area, the other at a certain small depth in the vicinity of the boundary of the contact surface. It should be noted that for points \( z = 0, \ r = 1 \) we have a simple relation \( \sigma_1^{(1)} / \sigma_1^{(2)} = \mu_1 / \mu_2 \).

The distribution of \( J_2 \) parameter in the layers with greater Young’s modulus has three local maxima (Fig. 5a). The first one occurs at some depth on \( z \)-axis, the second one – at point \( z = 0, \ r = 0 \), the third one – at points \( z = 0, \ r = 1 \). The distribution of \( J_2 \) parameter in layers with smaller Young’s modulus (Fig. 5b) is similar the one that occurs for the homogeneous isotropic medium in the classical Hertz contact problem. The only maximum arises on \( z \)-axis at some depth beneath the surface.

\[
\sigma_1^{(i)} = \frac{1}{3} \sigma^{(i)}_{\text{max}, H}(1 - 2\nu_i) \quad J_2^{(i)}(\nu_i = 0.3) = 0.356 \sigma^{(i)}_{\text{max}, H}
\]

(5.3)

where \( \sigma^{(i)}_{\text{max}, H} \) is the maximum pressure in the classical Hertz contact problem of pressing of a sphere into a homogeneous isotropic half-space and

\[
\frac{\sigma^{(i)}_{\text{max}, H}}{p_{\text{max}}} = \left[ \frac{A_1(\gamma_1 + \gamma_2)\mu_i}{(A_1 A_4 - A_3^2)(1 - \nu_i)} \right]^{2/3}
\]

(5.4)

Fig. 5. Distribution of \( J_2 \) in layers with: (a) greater Young’s modulus, (b) smaller Young’s modulus

Figures 6 and 7 show maximum values of relative parameters \( \sigma_1^{(i)} / \sigma_1^{(i)} \) and \( J_2^{(i)} / J_2^{(i)} \) as a function of \( \eta \) for three values \( E_1 / E_2 = 2, 4, 8 \) described by lines 1,2,3 respectively. \( \sigma_1^{(i)} \), \( J_2^{(i)} \) are corresponding parameters given by the classical Hertz contact problem for the homogeneous medium with mechanical properties of the \( i \)-th layer \((i = 1, 2)\) (Timoshenko and Goodier, 1951; Johnson, 1985)

It can be seen in Fig. 6a that tensile stresses on \( z \)-axis and on the boundary of the circle of contact achieve comparable values for small values of \( \eta \) and relatively large difference in values of Young’s moduli. For \( \eta \) close to 1, the tensile stress does not appear at all.

It follows from Fig. 6b that the local maximum \( J_2 \) existing on \( z \)-axis dominates the local maximum at the boundary of the loading circle. One exception is the small range \( 0.37 < \eta < 0.47 \) \((E_1/E_2 = 8)\). It should be noted that gray line 3 consists of two parts. The left hand part corresponds to the case when the maximum \( J_2 \) at the center of the loading circle prevails in the maximum \( J_2 \) on \( z \)-axis at some depth. The part on the right refers to the opposite situation. When \( \eta \to 1 \), the maximum on \( z \)-axis is at the same depth as in the classical Hertz contact problem, i.e. \( z = 0.48 \) \((\nu_1 = 0.3)\). With decreasing \( \eta \), the depth of maximum \( J_2 \) increases (e.g. \( E_1/E_2 = 4 \) from 0.48 \((\eta \to 1)\) to 0.66 \((\eta = 0.01)\)).
6. Conclusions

The paper presents the stress state in a layered half-space with periodical structure caused by Hertz pressure. Two different models of the layered medium have been considered: one – a homogenized model in which mechanical properties of the medium are determined using both the mechanical and geometrical properties of the analyzed composite components, and the other – where a certain number of layers are considered as separate homogeneous and interacting entities satisfying the conditions of ideal mechanical contact. In conclusion, it is demonstrated that stresses in layers of different mechanical properties are quite different. Additionally, the location of tensile stress regions $\sigma_1$ as well as the distribution of the second invariant of the deviatoric stress tensor $J_2$ are presented.

Acknowledgements

The investigations described in this paper are a part of the research projects S/WM/2/08 and S/WM/1/08 realized at Bialystok University of Technology.
References

5. Elliot D.A., 1949b, Axial symmetric stress distributions in aeolotropic hexagonal crystals, Cambridge Phil. Society, 45, 621-630
18. Postma G.W., 1995, Wave propagation in a stratified medium, Geophysics, 20, 780-806

Manuscript received September 27, 2012; accepted for print December 28, 2012